Existence of multidimensional phase transitions in a steady Van Der Waals flow

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Abstract. The purpose of this paper is to prove the existence of multidimensional subsonic phase transitions in a steady supersonic flow with the van der Waals type state function. The viscosity capillarity criterion \[ 23 \] is applied to seek physical admissible planar waves in stead of the Lax entropy inequality \[ 15 \], which is invalid under the subsonic condition. With the uniform stability result in \[ 26 \], we shall proceed to establish the existence by performing the iteration scheme \[ 19 \].

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1. Introduction

In a fluid with non-monotonic state functions, say van der Waals fluid, nonlinear waves with different characteristic feature usually appear, such as shock waves, rarefaction waves, contact discontinuities and subsonic phase transitions, among which we shall be concerned with the subsonic phase transition in this paper. Roughly speaking, the subsonic phase transition is a piecewise smooth solution to the Euler
equations with a single discontinuity, on both sides of which the sound speed is less than the fluid velocity in the normal direction to the discontinuity.

Due to the subsonic property, the well-known Lax entropy inequality for classical shock waves is violated. Hence, other admissible criterion is needed to assure the physical admissibility of subsonic phase transitions. There are several candidates available, among which the viscosity capillarity criterion is an important one. The viscosity capillarity criterion was first introduced by Slemrod [23] to study phase transitions in an unsteady van der Waals fluid. Ever since, the study of unsteady van der Waals fluid, especially on problems in one dimensional spaces have been carried out in many works. See [10], [16], [22], [23] and references therein. There are also works concerning multidimensional problems in an unsteady van der Waals fluid. See [3], [4], [5], [25], [27] and references therein.

However, in contrast with the unsteady flow, the knowledge on steady van der Waals fluid is much less. In [26], the author proved the uniform stability of subsonic phase boundaries in multi-dimensional spaces by showing the validity of Lopatinski condition [13, 18]. The purpose of this paper is to proceed to establish the existence of steady subsonic phase transitions. Since the stability result [26] indicates an $L^2$ energy estimate for the linearized problem, we can expect to establish the existence result by iteration as in [19]. To complete the work, we will show the validity of compatibility conditions and fulfill the detail of the iteration.

The content of this paper is arranged as follows. The rest part of this section is a brief introduction to the concept of subsonic phase transition in a steady flow. In section 2, we will explain the viscosity-capillarity criterion and formulate the main problem for multi-dimensional phase transitions. In section 3, the result of linear estimates in [26] will be presented. Section 4 and 5 mainly deal with the existence problem and the calculations of related compatibility conditions.

Let us briefly recall the equation of a steady van der Waals fluid and the concept of subsonic phase transitions.

The motion of an isothermal (or isentropic) 3-dimensional steady flow is governed by the following well-known Euler equations

\[
\begin{align*}
\partial_x(\rho u) + \partial_y(\rho v) + \partial_z(\rho w) &= 0 \\
\partial_x(\rho u^2 + p(\rho)) + \partial_y(\rho uv) + \partial_z(\rho uw) &= 0 \\
\partial_x(\rho uv) + \partial_y(\rho v^2 + p(\rho)) + \partial_z(\rho uw) &= 0 \\
\partial_x(\rho uw) + \partial_y(\rho vw) + \partial_z(\rho w^2 + p(\rho)) &= 0
\end{align*}
\]

where $\rho$ is the density of the flow, $(u, v, w)^T$ is the velocity of the flow and $p$ is the pressure which is a function of $\rho$. Denote $U = (\rho, u, v, w)^T$, $F_0(U) = \begin{pmatrix} \rho u \\ \rho u^2 + p \\ \rho uv \\ \rho uw \end{pmatrix}$, $F_1(U) = \begin{pmatrix} \rho v \\ \rho uv \\ \rho v^2 + p \\ \rho vw \end{pmatrix}$, $F_2(U) = \begin{pmatrix} \rho w \\ \rho uw \\ \rho vw \\ \rho w^2 + p \end{pmatrix}$.
and
\[
A_1(U) = (\nabla U F_0(U))^{-1} \nabla U F_1(U) \\
= \frac{1}{\rho u(u^2 - c^2)} \begin{pmatrix}
\rho u^2 v & -\rho^2 uv & \rho^2 u^2 & 0 \\
-wu^2c^2 & \rho u^2 v & -\rho u c^2 & 0 \\
(u^2 - c^2)c^2 & 0 & \rho v(u^2 - c^2) & 0 \\
0 & 0 & 0 & \rho v(u^2 - c^2)
\end{pmatrix},
\]
\[
A_2(U) = (\nabla U F_0(U))^{-1} \nabla U F_2(U) \\
= \frac{1}{\rho u(u^2 - c^2)} \begin{pmatrix}
\rho u^2 w & -\rho^2 uw & 0 & \rho^2 u^2 \\
-wu^2c^2 & \rho u^2 w & 0 & -\rho u c^2 \\
(u^2 - c^2)c^2 & 0 & \rho w(u^2 - c^2) & 0 \\
0 & 0 & 0 & \rho w(u^2 - c^2)
\end{pmatrix},
\]
where \(c^2 = d_p \rho(p)\) is the sound speed and the Euler equations (1.1) can be rewritten as
\[
\partial_x F_0(U) + \partial_y F_1(U) + \partial_z F_2(U) = 0
\]
or
\[
\partial_x U + A_1(U) \partial_y U + + A_2(U) \partial_z U = 0.
\]
When the flow is supersonic, namely
\[
u^2 + v^2 + w^2 > c^2,
\]
the system (1.1) is a hyperbolic conservation law, which is the case we are concerned with in this paper. In such case, nonlinear waves such as shock waves, rarefaction waves and contact discontinuities usually appear in a \(\gamma\)-pressure law flow. Rich literatures have been devoted to such topics and there still remain interesting open problems. See [6], [7], [17], [21], [28] and references therein.

However, in a van der Waals type flow, the above nonlinear waves are not all the cases, subsonic phase transitions usually appear due to the non-monotonicity of the state equation, which reads
\[
p(\tau) = \frac{R \theta}{\tau - b} - \frac{a}{\tau^2}
\]
where \(\tau \equiv \rho^{-1}\) is the specific volume of the fluid, \(\theta\) is the temperature of the fluid which is assumed to be a constant in an isothermal fluid, \(R\) is the perfect gas constant and \(a, b\) are positive constants. For \(\theta \in (a/(4bR), 8a/(27bR))\), the state equation (1.5) is not monotonic with respect to \(\tau\). Precisely speaking, we can find \(\tau_*, \tau^* \in (b, +\infty)\) such that
\[
\begin{align*}
d_x p(\tau) &< 0 & \tau \in (b, \tau_*) \cup (\tau^*, +\infty) \\
d_x p(\tau) &> 0 & \tau \in (\tau_*, \tau^*).
\end{align*}
\]
From the physical point of view, the fluid is in liquid phase for \(\tau \in (b, \tau_*)\), while it is in vapor phase for \(\tau \in (\tau^*, +\infty)\). The state in the region \((\tau_*, \tau^*)\) is highly unstable, which doesn’t actually exist in the real world [10].

A subsonic phase transition is a discontinuous solution to the Euler equation (1.1) with a single discontinuity, which changes phases across the discontinuity and satisfies certain subsonic condition on both sides of the discontinuity. To explain
the concept with more detail, let us consider the following planar subsonic phase transition

\[(1.7)\]  
\[U(x, y, z) = \begin{cases} 
U_- = (\rho_-, u_-, v_-, w_0) & y < \sigma x \\
U_+ = (\rho_+, u_+, v_+, w_0) & y > \sigma x \end{cases} \]

where \(\rho_\pm, u_\pm, v_\pm, w_0\) are constant states of the flow, \(\sigma\) is the constant speed of the discontinuity \(\{y = \sigma x\}\) and \(\rho_\pm\) belong to different phases. The solution (1.7) satisfies the Rankine-Hugoniot condition

\[(1.8)\]  
\[\sigma [F_0(U)] - [F_1(U)] = 0,\]

and the subsonic condition

\[(1.9)\]  
\[M_\pm = \left| \frac{\sigma u_\pm - v_\pm}{c_\pm \sqrt{1 + \sigma^2}} \right| < 1,\]

where \([\cdot]\) denotes the difference of a function across the discontinuity \(\{y = \sigma x\}\) respectively. Denote by \(u_{\text{ne}} = (\sigma u_\pm - v_\pm)/\sqrt{1 + \sigma^2}\) and \(u_r = (u_\pm + \sigma v_\pm)/\sqrt{1 + \sigma^2}\) the normal velocity and the tangential velocity on each side of the discontinuity \(\{y = \sigma x\}\) respectively, \(j = \rho_\pm u_{\text{ne}}\) the mass transfer flux, and \(\pi = p_\pm + j^2 \tau_\pm\). Then, the Rankine-Hugoniot condition (1.8) and the subsonic condition (1.9) can be simplified as

\[(1.10)\]  
\[[j] = 0, \quad [\pi] = 0, \quad [u_r] = 0,\]

and

\[(1.11)\]  
\[\left| \frac{u_{\text{ne}}}{c_\pm} \right| < 1 \quad \text{or} \quad \left| \frac{j^2}{d_\pm} \right| < 1,\]

respectively. Like subsonic phase transitions in an unsteady fluid, those in a steady flow do not satisfy the Lax entropy inequality either. Considering the planar wave (1.7), we assume that the following supersonic condition is always valid in the coming arguments

\[(1.12)\]  
\[u_\pm^2 - c_\pm^2 > 0.\]

Denote by

\[\lambda_1^\pm = \frac{1}{u_\pm^2 - c_\pm^2} (u_\pm v_\pm - c_\pm \sqrt{\Delta_\pm}),\]

\[\lambda_2^\pm = \frac{v_\pm}{u_\pm},\]

\[\lambda_3^\pm = \frac{1}{u_\pm^2 - c_\pm^2} (u_\pm v_\pm + c_\pm \sqrt{\Delta_\pm}),\]

the eigenvalues of \(A_1(U_\pm)\) respectively with \(\Delta_\pm = u_\pm^2 + v_\pm^2 - c_\pm^2\), which satisfy

\[(1.13)\]  
\[\lambda_1^\pm < \lambda_3^\pm < \lambda_2^\pm.\]

Obviously, the subsonic condition (1.9) yields the inequality

\[(1.14)\]  
\[\lambda_2^\pm < \sigma < \lambda_3^\pm,\]

which violates the Lax inequality for 1st-shocks (3rd-shocks),

\[\lambda_2^\pm < \sigma < \lambda_3^- \quad (\lambda_3^+ < \sigma < \lambda_3^-).\]
2. Admissible Criterion and the Main Problem

In order to seek physical admissible solution, Slemrod [23] proposed the viscosity capillarity criterion for one dimensional unsteady fluids under Lagrange coordinates. Motivated by the study of multidimensional problems, Benzoni-Gavage [3, 4] applied this criterion to unsteady fluids under Euclid coordinates. In this section, let’s recall the viscosity capillarity criterion to seek physical admissible phase transitions in a steady flow.

2.1. Viscosity capillarity criterion. Analogue to the traveling wave method for viscous shocks, the viscosity capillarity criterion picks the planar wave (1.7) which admits the existence of the following traveling wave

\[ U(\xi) = U\left(\frac{y - \sigma x}{\epsilon}\right) \]

satisfying \( U(\pm \infty) = U_\pm \) and the Navier-Stokes equations

\[
\begin{align*}
\partial_x (pu) + \partial_y (pv) + \partial_z (pw) &= 0 \\
\partial_x (pu^2 + p(\rho)) + \partial_y (puv) + \partial_z (puw) &= \epsilon \nu \Delta u - \epsilon^2 \partial_x \Delta (\rho^{-1}) \\
\partial_x (puv) + \partial_y (pv^2 + p(\rho)) + \partial_z (puvw) &= \epsilon \nu \Delta v - \epsilon^2 \partial_y \Delta (\rho^{-1}) \\
\partial_x (pww) + \partial_y (pww) + \partial_z (w^2 + p(\rho)) &= \epsilon \nu \Delta w - \epsilon^2 \partial_z \Delta (\rho^{-1})
\end{align*}
\]

where \( \Delta = \partial_x^2 + \partial_y^2 + \partial_z^2 \) is the Laplace operator, \( \epsilon \nu \) is the viscosity coefficient and \( \epsilon^2 \) is the capillarity coefficient with \( \epsilon \geq 0, \nu > 0 \). Substituting (2.1) into (2.2) and employing the Rankine-Hugoniot condition (1.10), we get the following heteroclinic problem for the unknown function \( \tau(\xi) \equiv 1/\rho(\xi) \)

\[
\begin{align*}
\tau'' &= \nu j' + \pi - p(\tau) - j^2 \tau \\
\tau(\pm \infty) &= \tau_\pm
\end{align*}
\]

where the prime ‘\( ' \) denotes the derivative of a function with respect to \( \xi \). As in [4], the admissibility of subsonic phase transitions can be defined by

**Definition 2.1.** The planar subsonic phase transition (1.7) is admissible if and only if the problem (2.3) has a solution. The solution \( \tau(\xi) \) is called the viscosity capillarity profile or \( \nu \)-profile for simplicity. The pair \( (\tau_-, \tau_+) \) is called \( \nu \)-admissible.

One can find that the heteroclinic problem (2.3) is exactly the same one for unsteady fluids [4]. Thus, the advantage of the known results in [4] is for us to take and let us have a brief recall. Denote by \( \{\tau_m, \tau_M\} \) the Maxwell equilibrium defined by the equal area rule

\[
\int_{\tau_m}^{\tau_M} (p(\tau_m) - p(\tau)) d\tau = 0.
\]

Then, there exists \( \tau_1 \in (\tau_M, +\infty) \) such that the chord connecting \( (\tau_1, p(\tau_1)) \) and \( (\tau_m, p(\tau_m)) \) is tangent to the graph of \( p = p(\tau) \) at \( (\tau_1, p(\tau_1)) \). With \( \tau_1 \) and \( \tau_m \), we define

\[
\nu_j = \frac{p(\tau_1) - p(\tau_m)}{\tau_m - \tau_1}.
\]

When \( \nu = 0 \), the \( \theta \)-profile satisfies

\[
\begin{align*}
\tau'' &= \pi - p(\tau) - j^2 \tau \\
\tau(\pm \infty) &= \tau_\pm
\end{align*}
\]

\[
\nu_j = \frac{\pi - j^2 \tau}{\tau_m - \tau_1}.
\]
As in [4], a $\theta$-profile $\tilde{\tau}(\xi; j)$ satisfying the first equation of (2.4) can be found by the generalized equal area rule, which means

$$\int_{\tau_-}^{\tau_+} (\pi - p(\tau) - j^2 \tau) d\tau = 0.$$  

Moreover, for every $j$ ($0 < j^2 \leq j_1^2$), a unique pair $(\tilde{\tau}_-(j), \tilde{\tau}_+(j))$ can be found such that $\tilde{\tau}_-\tau$ and $\tilde{\tau}_+$ can be connected by the $\theta$-profile with the parameters $j$. With the above results, Benzoni-Gavage [4] proved the structural stability and the existence of traveling waves for small $\nu$ by the center manifold method.

**Theorem 2.1.** For $0 < j^2 \leq j_1^2$, there exist $\nu_0 > 0$ and neighborhoods $\mathcal{J}_0$, $\mathcal{V}_0$ of $\tilde{j}$, $(\tilde{\tau}_-(\tilde{j}), \tilde{\tau}_+(\tilde{j}))$ respectively, such that, for $(j, \nu) \in \mathcal{J}_0 \times [0, \nu_0]$, there are unique pair $(\tau_-, \tau_+)$ in $\mathcal{V}_0$, for which $\tau_-$ and $\tau_+$ are $\nu$ admissible with the parameters $j$.

Moreover, an additional jump condition can be derived from the above result for the subsonic phase transition (1.7). As we can see from the subsonic condition (1.9), a subsonic phase transition has one more characteristic going out of the free boundary than a shock wave. Hence, the Rankine-Hugoniot condition is not sufficient to guarantee the well-posedness of the corresponding initial boundary value problem. Nevertheless, the viscosity capillarity criterion can provide the following additional jump condition. By multiplying the equation in (2.3) with $\tau'(\xi)$ and integrating from $-\infty$ to $+\infty$ with respect to $\xi$, it follows

$$f + \pi \tau - j_1^2 \tau^2 = -\nu a(j, \nu)$$

where $f = -\frac{\partial}{\partial \nu} - R\theta \ln(\tau - b)$ is the free energy of the fluid and

$$a(j, \nu) = j \int_{-\infty}^{+\infty} (\tau'(\xi; j, \nu))^2 d\xi$$

with $\tau(\xi; j, \nu)$ being the $\nu$-profile. Noticing $a(j, \nu)$ being a nonlocal term, the following lemma in [3] will be needed for linear estimate.

**Lemma 2.2.** For all $\nu \in [0, \nu_0]$, the functions $a(j, \nu)$ is continuously differentiable. Moreover, its derivatives are continuous with respect to $\nu$ at $\nu = 0$ and are bounded depending on the bounds of $U_\pm$ given in (1.7). There exists $\alpha > 0$ such that for all $j \in \mathcal{J}$

$$\lim_{\nu \to 0} \frac{\partial}{\partial j} a(j, \nu) \geq \alpha > 0.$$

**2.2. Problems, assumptions and main results.** Compared with the unsteady fluid, in a steady supersonic flow, the variable $x$ can be regarded as the time variable [7]. Thus, endow the Euler equations with the initial data

$$U(0, y, z) = \begin{cases} U_\theta(y, z) & y < \varphi_0(z) \\ U_\theta(y, z) & y > \varphi_0(z) \end{cases},$$

which changes phases across the discontinuity $\{y = \varphi_0(z)\}$ and satisfies certain compatibility conditions. We expect to construct the multidimensional subsonic phase transition

$$U(x, y, z) = \begin{cases} U_-(x, y, z) & y < \varphi(x, z) \\ U_+(x, y, z) & y > \varphi(x, z) \end{cases},$$
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which satisfies the following nonlinear initial boundary value problem

\[
\begin{aligned}
\frac{\partial U}{\partial t} + A_1(U) \partial_y U + A_2(U) \partial_z U &= 0, \quad x, y, z > 0, \\
\varphi [F_0(U)] - [F_1(U)] + \varphi [F_2(U)] &= 0, \quad y = \varphi(x, z) \\
I(\rho) + (\varphi_u u - v + \varphi_v w)^2 &= -\nu a(j, \nu), \quad y = \varphi(x, z) \\
U_\pm(0, y, z) &= U_0^\pm(y, z), \quad \varphi(0, z) = \varphi_0(z),
\end{aligned}
\]

where the second equation is the Rankine-Hugoniot condition, the third equation is a reformulation of the jump condition (2.5) with \(I(\rho) = f + \rho r_a\) and \(a(j, \nu) = j \int_{t_0}^t (r_j(j, \nu)) \, dt\) with \(j = \rho_\pm(\varphi_u u_\pm - v_\pm + \varphi_v w_\pm)/\sqrt{1 + \varphi_x^2 + \varphi_y^2} \big|_{y = \varphi(x, z)}\) and \(r_j(j, \nu)\) satisfying

\[
\begin{aligned}
\tau'' &= \nu j \tau' + \pi - p(\tau) - j^2 \tau, \\
\tau(\pm \infty) &= \tau_\pm \big|_{y = \varphi(x, z)}.
\end{aligned}
\]

Following Majda’s approach [18], the following transformation

\[
\begin{cases}
\tilde{x} = x \\
\tilde{y} = \pm(y - \varphi(x, z)), \quad \pm(y - \varphi(x, z)) > 0, \\
\tilde{z} = z
\end{cases}
\]

maps the free boundary \(\{y = \varphi(x, z)\}\) to the fixed one \(\{\tilde{y} = 0\}\). Then the problem (2.9) becomes

\[
\begin{aligned}
\frac{\partial U}{\partial t} + A_1(U) \partial_y U + A_2(U) \partial_z U &= 0, \quad x, y, z > 0, \\
\varphi [F_0(U)] - [F_1(U)] + \varphi [F_2(U)] &= 0, \quad y = 0 \\
I(\rho) + (\varphi_u u - v + \varphi_v w)^2 &= -\nu a(j, \nu), \quad y = 0 \\
U_\pm(0, y, z) &= U_0^\pm(y, z), \quad \varphi(0, z) = \varphi_0(z),
\end{aligned}
\]

where the tildes have been dropped for simplicity. We shall mainly deal with the above problem in the coming arguments.

For convenience, let’s introduce several notations. Denote by \(\omega\) the part of a neighborhood of the origin \(\{x = 0, y > 0\}\), \(I = \omega \cap \{y = 0\}, \Omega \subset \{x, y > 0\}\) a determinacy domain of \(\omega\) with respect to the problem (2.11) with \(\Omega_T = \Omega \cap \{x < T\}\) and \(\partial \Omega_T = \Omega_T \cap \{y = 0\}\).

To solve the problem (2.11), we propose the following assumptions:

(A1) For any fixed \((y_0, z_0) \in \Sigma_0 = \{y = \varphi_0(z)\}\), there exists \(\sigma(z_0) \in \mathbb{R}\) such that the problem (2.11) with the initial data frozen at \((y_0, z_0)\), admits a planar subsonic phase transition:

\[
U(x, y, z) = \begin{cases}
U_0^\pm(\varphi_0(z_0), z_0), \quad x > \varphi_0(z_0) + \sigma(z_0)x, \\
U_0^\pm(\varphi_0(z_0), z_0), \quad x < \varphi_0(z_0) + \sigma(z_0)x
\end{cases}
\]

satisfying the viscosity-capillarity criterion.

(A2) For any fixed \(s \geq 9\), \(U_\pm^0 \in H^{s+1}(\omega), \varphi_0 \in H^{s+3/2}(I)\) satisfy the higher order compatibility condition, which will be given in section 4.1, for \(0 \leq k \leq s - 1\).

The main result of this paper is
Theorem 2.3. Suppose that the initial data $(U_0^+, \varphi_0)$ satisfies the assumptions (A1) and (A2), the problem (2.11) has a solution locally in time.

3. Linear Estimates

In this section we briefly recall the linear stability result of subsonic phase transitions in [26] and establish the energy estimate for the linear problem. First, let us derive the linearized problem of (2.11) and introduce the weighted Sobolev space.

3.1. Linearized problem. Consider the perturbation, $(U_+^\varepsilon, U_-^\varepsilon, \varphi^\varepsilon)$, of the planar phase transition (1.7), which satisfies the problem (2.11) and

$$((U_+^\varepsilon, U_-^\varepsilon, \varphi^\varepsilon))_{\varepsilon=0} = (U_+, U_-, \sigma x).$$

Denote

$$(V_+, V_-, \psi) = \frac{d}{d\varepsilon}((U_+^\varepsilon, U_-^\varepsilon, \varphi^\varepsilon))_{\varepsilon=0}.$$

Then, the following linearized problem for the unknowns $(V_+, V_-, \psi)$ can be derived from (2.11),

$$\begin{align*}
\begin{cases}
\partial_x V_\pm + (A_1(U_\pm) - \sigma I)\partial_y V_\pm + A_2(U_\pm)\partial_z V_\pm = f_\pm, & x, y > 0 \\
b_0 \psi_x + b_1 \psi_z + \mathcal{M}_+ V_+ + \mathcal{M}_- V_- = g, & y = 0 \\
(V_+, V_-, \psi)|_{x<0} & \text{vanish,}
\end{cases}
\end{align*}
$$

where

$$b_0 = \left( \frac{[F_0(U)]}{\sqrt{1 + \sigma^2}} \right), b_1 = \left( \frac{[F_2(U)]}{\sqrt{1 + \sigma^2}} \right),$$

$$\mathcal{M}_+ = \left( \sigma F_0'(U_+) - F_1'(U_+) \right), \mathcal{M}_- = \left( -\sigma F_0'(U_-) + F_1'(U_-) \right),$$

with

$$l_+ = \left( \frac{c^2 + \check{v}_j}{\rho_+} \frac{\sigma u_{\text{m}} + \check{v} \rho_+}{\sqrt{1 + \sigma^2}}, -\frac{u_{\text{m}} + \check{v} \rho_+}{\sqrt{1 + \sigma^2}}, 0 \right),$$

$$l_- = \left( \frac{c^2}{\rho_-} - \frac{\sigma u_{\text{m}} - \check{v}_j}{\sqrt{1 + \sigma^2}}, \frac{u_{\text{m}} - \check{v} \rho_-}{\sqrt{1 + \sigma^2}}, 0 \right),$$

with $u_{\text{m}} = (\sigma u_+ - v_\pm)/\sqrt{1 + \sigma^2}$, $u_\tau = (u_+ + \sigma v_\pm)/\sqrt{1 + \sigma^2}$, $j = \rho_\pm u_{\text{m}}$ and $\check{v} = \nu \partial_j a(j, \nu)$.

To establish the energy estimate for the problem (3.1), let us introduce the following weighted norms. For any $\lambda > 0$ and integer $s \geq 0$, we denote

$$\langle g \rangle^2_{s, \lambda, T} = \sum_{\alpha + \beta + \gamma = s} \int_0^T \int_{-\infty}^{+\infty} \lambda^{2\alpha} e^{-2\lambda x} |\partial_\tau^\alpha \partial_x^\beta g|^2 dz dx,$$

$$|f|^2_{s, \lambda, T} = \sum_{k=0}^s \int_0^T \int_{-\infty}^{+\infty} \langle \partial_y^k f \rangle^2_{s-k, \lambda, T} dy.$$
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and

$$\|(V_+, V_-)\|_{s,\lambda,T}^2 = \langle \psi \rangle_{s+1,\lambda,T}^2 + \sum_{k=0}^s \left( \left\langle \frac{\partial V_+}{\partial x^j} \right\rangle_{s-j,\lambda,T}^2 + \left\langle \frac{\partial V_-}{\partial x^j} \right\rangle_{s-j,\lambda,T}^2 \right)$$

$$+ \lambda \left( |V_+|_{s,\lambda,T}^2 + |V_-|_{s,\lambda,T}^2 \right) .$$

We will simply denote $\langle \cdot \rangle_{s,T}$, $| \cdot |_{s,T}$, $\| \cdot \|_{s,T}$ the cases when the above norms are independent of $\lambda$ and $\langle \cdot \rangle_s$, $| \cdot |_s$, $\| \cdot \|_s$ the case $T = +\infty$.

3.2. Linear estimates. Let us recall the first main result of [26]. For the problem (3.1), we have

**Theorem 3.1.** There exists $\nu_1 > 0$ depending on the bounds of $U_{\pm}$ and $\sigma$, such that for $0 < \nu < \nu_1$, the subsonic phase transition (1.7) is stable with respect to perturbations in the $y$-direction, which means the problem (3.1) without the variable $z$ being well-posed.

Denote by $V = (V_+, V_-)^T$ and

$$\hat{V}(s, \omega, y) = \frac{1}{(2\pi)^2} \int_0^\infty \int_{-\infty}^{\infty} e^{-(sx + i\omega z)} V(x, y, z) dz dx$$

the Laplace-Fourier transform of $V$ in $(x, z)$ with $\text{Re} s > 0$. Then from (3.1), we know that $\hat{V}$ satisfies

$$\frac{\partial \hat{V}}{\partial y} = B(s, \omega) \hat{V} + \hat{f}$$

where

$$B(s, \omega) = \begin{pmatrix} -(A_1(U_+) - \sigma I)^{-1}(sI + i\omega A_2(U_+)) & 0 \\ 0 & (A_1(U_-) - \sigma I)^{-1}(sI + i\omega A_2(U_-)) \end{pmatrix}$$

and $\hat{f} = ((A_1(U_+) - \sigma I)^{-1}\hat{f}_+, -(A_1(U_-) - \sigma I)^{-1}\hat{f}_-)^T$.

Denote by $\{\lambda_j\}_{j=1}^l$ all distinct eigenvalues of $B(s, \omega)$ with multiplicity being $m_j$. Obviously, we have

$$\mathbb{C}^8 = \bigoplus_{j=1}^l \text{Ker}[(\lambda_j I - B(s, \omega))^{m_j}].$$

Introduce

$$E^+(s, \omega) = \{ w_j \in \text{Ker}[(\lambda_j I - B(s, \omega))^{m_j}] | \text{Re} \lambda_j < 0, 1 \leq j \leq l \}$$

the space of boundary values of all bounded solutions of the special form

$$\hat{V}(s, \omega, y) = \sum_{\text{Re} \lambda_j < 0} e^{\lambda_j y} \sum_{p=0}^{m_j-1} \frac{y^p}{p!} (\lambda_j I - B(s, \omega))^p w_j$$

to (3.2) with $\hat{f} \equiv 0$. The second main result of [26] is
Theorem 3.2. There exists $\nu_1 > 0$ depending on the bounds of $U_\pm$ and $\sigma$ given in (1.7) such that for $0 < \nu < \nu_1$, the $\nu$-admissible subsonic phase transition (1.7) is uniformly stable, i.e. there exists $\eta > 0$ such that the estimate

$$\inf_{\lambda \geq 0} \left| \left( b_0 s + ib_1 \omega \right) \mu + \mathcal{M}_+ V_+ + \mathcal{M}_- V_- \right|^2 \geq \eta^2 (|V_+|^2 + |V_-|^2 + \mu^2)$$

(3.3)

holds for all $V = (V_+, V_-) \in E^+(s, \omega)$ and $\mu \in \mathbb{R}$.

Therefore, for the linear problem with variable coefficients (3.1), we can prove the following result by the same way as in [18]. Under assumption (A1) given at section 2.2 on the initial data $(U_0^1(y, z), U_0^2(y, z), \varphi_0(z))$, there is $\delta > 0$ such that for any smooth function $(U_+(x, y, z), U_-(x, y, z), \varphi(t, y))$ satisfying

$$\sup_{\Omega_{T_0}} (|U_\pm - U_0^\pm| + |\varphi - \varphi_0| + |\varphi_x - \sigma(z)| + |\partial_x (\varphi - \varphi_0)|) < \delta$$

(3.4)

the problem (3.1) is well-posed for $(V_+, V_-, \psi)$, which means

Theorem 3.3. Suppose that the assumption (A1) is satisfied and (3.4) holds for $(U_+, U_-, \varphi)$. If we have

$$\begin{align*}
&\text{if} \quad f_+ f_- + |g|^2 < 0 \text{ and } x > T_0, \\
&\text{then there is a unique strong solution } (V_+, V_-, \psi) \text{ to (3.1), and the estimate}
\end{align*}$$

(3.5)

(3.6)

$$\| (V_+, V_-, \psi) \|_{0, \lambda, T}^2 \leq C_1 \left( \frac{1}{\lambda} (|f_+|^2_{0, \lambda, T} + |f_-|^2_{0, \lambda, T} + |g|^2_{0, \lambda, T}) \right), \quad 0 \leq T \leq T_0
$$

for any fixed $s \geq 9$.

Additionally, if $|f_+|^2 + |f_-|^2 + |g|^2$ is finite for $s \geq 9$, and

$$\partial^j_x f_0 |_{x=0} = \partial^j_x g |_{x=0} = 0$$

(3.7)

for any $0 \leq j \leq s - 1$, then the solution $(V_+, V_-, \psi)$ belongs to

$$H^s \times H^s \times H^{s+1}$$

and satisfies

$$\| (V_+, V_-, \psi) \|_{s, \lambda, T}^2 \leq C_1 \left( \frac{1}{\lambda} (|f_+|^2_{s, \lambda, T} + |f_-|^2_{s, \lambda, T} + |g|^2_{s, \lambda, T}) \right), \quad 0 \leq T \leq T_0.
$$

(3.8)

4. Compatibility conditions

Before proving the existence, we have to derive the compatibility conditions for the initial data with which an approximate solution to the problem (2.11) can be constructed.
4.1. Compatibility conditions. In order to derive the compatibility condition up to order \( s - 1 \) with \( s \) being a given positive integer, let us perform the formal Cauchy-Kowaleski computations. Assume that there is a smooth solution \((U_+, U_-, \varphi)\) to (2.11). Then, from (A1) and (2.9), the zero-th order compatibility condition is that at \( x = 0 \), the initial data satisfy

\[
\begin{align*}
\sigma [F_0(U^0)] - [F_i(U^0)] + \varphi_0'[F_0(U^0)] &= 0 \\
[I(\rho^0) + \frac{(\sigma_{u_0} - v_0 + \varphi_0 u_0^2)}{\sqrt{1 + \sigma^2 + \varphi_0^2}}] &= -\nu a(j_0, \nu)
\end{align*}
\]

where

\[
j = \rho_0^0 (\sigma(z) u_0^0 - v_0^0 + \varphi_0 u_0^0)/\sqrt{1 + \sigma(z)^2 + \varphi_0^2} \big|_{y=0}
\]

and \( a(j_0, \nu) \) is defined similarly as in (2.5) with the parameter \( j_0 \).

Next, let us derive relations among \( \partial^{k+1}_x \varphi|_{x=0} \) and \( \partial^k_0 U^0_\pm|_{y=0} \). Differentiating the second and third equations of (2.9) with respect to \( x \) at \( x = y = 0 \), it follows

\[
[F_0(U^0)]_{x}^{k+1} \varphi + F_0(U^0_+) \partial^k_x U_+ + F_0(U^0_-) \partial^k_x U_- = g^k_1
\]

and

\[
\partial_x^k \varphi|_{x=0} : 0 \leq j \leq k, l + j \leq k + 1,
\]

and

\[
\{ \partial_x^k \partial_y^0 U^0_\pm|_{y=0} : 0 \leq j \leq k - 1, l + j \leq k \}
\]

and

\[
\begin{align*}
a_0 &= \frac{u_\tau}{1 + \sigma^2 + \varphi_0^2} ([u_n] + \tilde{\nu} \rho_+), \\
l_+^0 &= \left( \frac{\sigma(u_n_+ + \tilde{\nu} \rho_+)}{\rho_+} \right) \left( \frac{1 + \sigma^2 + \varphi_0^2}{\sqrt{1 + \sigma^2 + \varphi_0^2}} \right) 0, \\
l_-^0 &= \left( \frac{-\sigma u_n_+}{\rho_-} \right) \left( \frac{1 + \sigma^2 + \varphi_0^2}{\sqrt{1 + \sigma^2 + \varphi_0^2}} \right) 0
\end{align*}
\]

with \( u_n_\pm = (\sigma u_\pm - v_\pm^0 + \varphi_0^2 v_\pm^0)/\sqrt{1 + \sigma^2 + \varphi_0^2} \), \( u_\tau = (u_\pm + \sigma v_\pm)/\sqrt{1 + \sigma^2 + \varphi_0^2} \), \( j = \rho_+ u_n_\pm \) and \( \tilde{\nu} = \nu \partial_x a(j, \nu) \). On the other hand, from the equations of \( U_\pm \) in (2.9) it follows

\[
\partial_x^k U_\pm|_{x=0} = \partial_x^k \partial_y U^0_\pm + h^k_\pm
\]

where \( h^k_\pm \) smoothly depend on

\[
\{ \partial_x^j \partial_y^k \varphi|_{x=0} : 0 \leq j \leq k, l + j \leq k + 1 \}
\]

and

\[
\{ \partial_x^j \partial_y^k U^0_\pm|_{y=0} : 0 \leq j \leq k - 1, l + j \leq k \}.
\]

Substituting (4.4) into (4.2) and (4.3), we obtain the following \( k \)-th order compatibility conditions for the problem (2.9) at \( x = y = 0 \)

\[
\begin{align*}
[F_0(U^0)]_{x}^{k+1} \varphi + F_0(U^0_+) \partial^k_x U_+ + F_0(U^0_-) \partial^k_x U_- &= f^k_1 \\
a_0 \partial_x^k \varphi + l_+^0 \partial^k_x U_+ + l_-^0 \partial^k_x U_- &= f_2^1
\end{align*}
\]
where \( f_k^1 \) and \( f_k^2 \) smoothly depend on \( \{ \partial_{x_i}^j \varphi \mid_{x=0} : 0 \leq j \leq k, l + j \leq k + 1 \} \) and \( \{ \partial_{x_i}^j \varphi \mid_{y=0} : 0 \leq j \leq k - 1, l + j \leq k \} \).

4.2. Initial data satisfying the compatibility conditions. As in [19], here we show that there exist large classes of initial data satisfying the compatibility conditions. By simple calculation, we get the eigenvalues of \((A_1(U_0^0) - \varphi'(0)A_2(U_0^0) - \sigma(z)I)|_{x=0}\) as the following:

\[
\begin{align*}
\lambda^1_\pm(z) &= \frac{v_0^0 - c_\pm^0 + \sqrt{\Delta_\pm}}{2} - \sigma(z) \\
\lambda^2_\pm(z) &= \frac{v_0^0 - c_\pm^0 - \sqrt{\Delta_\pm}}{2} - \sigma(z) \\
\lambda^3_\pm(z) &= \frac{v_0^0 - c_\pm^0 \sqrt{\Delta_\pm}}{2} - \sigma(z)
\end{align*}
\]

(4.6)

where \( c_\pm^0 = (d_p\rho_\pm^0)\frac{\tau}{2}, \)

\[
\begin{align*}
v_0^0 &= v_0^0 - \varphi'(0)w_0^0, \hspace{1cm} \Delta_\pm = (\varphi'(0))^2 + ((v_0^0)^2 - (c_\pm^0)^2)(1 + (\varphi'(0))^2).
\end{align*}
\]

Noting that \( \lambda^1_\pm \) and \( \lambda^3_\pm \) are of multiplicity 1, \( \lambda^2_\pm \) is of multiplicity 2, we denote by \( r^1_\pm, r^3_\pm \) and \( r^2_\pm, r^4_\pm \) the eigenvectors correspondingly.

Without loss of generality, we assume that the initial mass transfer flux

\[
\begin{align*}
j_0 = \rho_\pm^0(\sigma(z)u_0^0 - v_0^0 + \varphi'(0))\sqrt{1 + \sigma(z)^2 + \varphi'(0)^2}
\end{align*}
\]

is positive, then from the subsonic condition (1.9) we have

\[
\begin{align*}
\lambda^2_\pm(z) < 0 &< \lambda^3_\pm(z).
\end{align*}
\]

Denote by \( P^+(z) \) and \( P^-(z) \) the smoothly varying projections onto the subspaces spanned by the eigenvectors associated with eigenvalues \( \lambda^2_\pm(z), \lambda^3_\pm(z) \) and \( \lambda^4_\pm(z) \) respectively. Similar to the Lemma 2.1 of Majda in [19], we have the following result:

**Lemma 4.1.** There exists \( \nu_0 \) depending on the bounds of \( U_0^0 \) and \( M \), such that for \( 0 < \nu \leq \nu_0 \), if \( (v^+, v^-) \in \mathbb{R}^3 \times \mathbb{R}^4 \) satisfies

\[
\begin{align*}
P^+v^+ = v^+, \hspace{1cm} P^-v^- = v^-
\end{align*}
\]

and \( \beta \) is constant, then from the identity

\[
\begin{align*}
G(\beta, v^+, v^-) = \beta \left[ \left( F_0(U_0^0) \right) \frac{a_0(y)}{v_0^0} \right] + \left( F_0(U_0^0) \frac{d_{k+1}^+}{l_0^+(y)} \varphi_{k+1}^+ \right) v^+ + \left( F_0(U_0^0) \frac{d_{k-1}^-}{l_0^-(y)} \varphi_{k-1}^- \right) v^- = 0
\end{align*}
\]

we should have \((\beta, v^+, v^-) = 0\).

**Proof.** The basis of the set

\[
\begin{align*}
\{(\beta, v^+, v^-) | P^+v^+ = v^+, P^-v^- = v^- \}
\end{align*}
\]

is given by

\[
(1, 0, 0) \cup (0, r^+_2, 0) \cup (0, r^+_3, 0) \cup (0, r^-_3, 0) \cup (0, r^-_1, 0).
\]
Therefore, we get that the following determinant
\[
G(1, 0, 0) = \left( \begin{array}{c} [F_0(U^0)] \\ a_0 \end{array} \right),
\]
\[
G(0, r_2^+, 0) = \left( (-\lambda_2^+)^{k+1} F_0(U^0) r_2^+ \right),
\]
\[
G(0, r_2^+, 0) = \left( (-\lambda_2^+)^{k+1} F_0(U^0) r_2^+ \right),
\]
\[
G(0, r_3^+, 0) = \left( (-\lambda_3^+)^{k+1} F_0(U^0) r_3^+ \right),
\]
\[
G(0, 0, r_1^-) = \left( (\lambda_1^-)^{k+1} F_0(U^0) r_1^- \right).
\]
Therefore, we get that the following determinant
\[
\det \left( G(1, 0, 0), G(0, r_2^+, 0), G(0, r_3^+, 0), G(0, 0, r_1^-) \right)
\]
\[
= \left( (\lambda_2^+) \lambda_3^+ \lambda_1^- \right)^{k+1} \left( \begin{array}{cccc} [F_0(U^0)] & F_0(U^0) r_2^+ & F_0(U^0) r_3^+ & F_0(U^0) r_1^- \\ a_0 & -\frac{\lambda_2^+ r_2^+}{\lambda_2^-} & -\frac{\lambda_3^+ r_3^+}{\lambda_3^-} & -\frac{\lambda_1^- r_1^-}{\lambda_1^-} \end{array} \right)
\]
does not vanish for sufficiently small \( \nu \) and \( K \) according to Theorem 3.1.\( \square \)

From the Lemma 4.1, now we can show that there exist large classes of initial data satisfying the compatibility conditions. As in [19], we have the following proposition

**Proposition 4.2.** Assume that \((V_0, V_0, \sigma) \in H^{s+\frac{1}{2}}(I) \) and \( \phi_0 \in H^{2+\frac{1}{2}}(I) \) satisfy the zero-th order compatibility condition (4.1), and \( g_k^\pm \in H^{s+1-k}(I) \) (\( k \leq s-1 \)) are arbitrary functions satisfying \( P^\pm g_k^\pm = 0 \). Then there are \((U_0^\pm(y, z), \phi^0(x, z)) \in H^{s+1}(\omega) \times H^{s+2}((-\infty, \infty) \times I) \) so that
\[
U_0^0(0, z) = V_0^0(z), \phi^0(0, z) = \phi_0(z), \partial_x \phi^0(0, z) = \sigma(z)
\]
and
\[
(I - P^\pm) \partial_x U_0^\pm|_{x=0} = g_k^\pm(z)
\]
for \( 1 \leq k \leq s-1 \);
\[
(2) \, U_0^\pm(y, z), \phi^0(x, z) \) satisfies the compatibility condition (4.5) for any \( 0 \leq k \leq s-1 \).

5. Existence of the solution

In this section, we prove the existence of the solution to the problem (2.11). For simplicity, let us denote the problem in the following abstract form
\[
\begin{cases}
L^\pm(U_\pm, \phi) U_\pm = 0, & x, y > 0 \\
B(U_+, U_-, \phi_+, \phi_-) = 0, & \text{on } y = 0 \\
U_\pm|_{x=0} = U_0^\pm, & \phi|_{x=0} = \phi_0
\end{cases}
\]
(5.1)
where
\[
L^\pm(U_\pm, \phi) = \partial_x \pm (A_1(U_\pm) - \phi_2 A_2(U_\pm) - \phi_2 I) \partial_y + A_2(U_\pm) \partial_z
\]
and \( B(\cdot) = 0 \) represents the Rankine-Hugoniot condition and the viscosity-capillarity admissibility criterion given in (2.11).
First let us construct a approximate solution to (5.1).

5.1. Approximate solutions. We are going to construct the following functions

\[
\tilde{U}_0^0 \in \bigcap_{j=0}^{s+1} \mathcal{C}^j([0, T_0], H^{s+1-j}(\omega_i)) \quad \text{and} \quad \varphi^0 \in H^{s+2}(\Omega_{T_0})
\]

such that

\[
\begin{align*}
L^\pm(\tilde{U}_0^0, \varphi^0)\tilde{U}_0^0 &= f_0^\pm, & x, y > 0 \\
B(\tilde{U}_0^0, \varphi^0, \tilde{U}_0^0, \varphi^0) &= g_0^1, & \text{on } y = 0 \\
\tilde{U}_0^0|_{x=0} &= U_0^0, & \varphi^0|_{x=0} = \varphi_0 
\end{align*}
\]

and

\[
\partial^j_x f_0^0|_{x=0} = 0, \quad \partial^j_x g_0^1|_{x=0} = \partial^j_x g_0^2|_{x=0} = 0
\]

for \(0 \leq j \leq s - 1\).

Denoting

\[
m^j_\pm = \frac{\partial^j\tilde{U}_0^0}{\partial x^j}|_{x=0}, \quad (0 \leq j \leq s)
\]

then from (5.3) and (5.4), we obtain

\[
m^j_\pm \in H^{s+1-j} \quad (0 \leq j \leq s)
\]

Let \(P(\partial_t, \partial_x, \partial_y)\) be a scalar linear hyperbolic operator of order \(s + 1\), \(\tilde{m}^j_\pm \in H^{s+1-j}(\mathbb{R}^2)\) be an appropriate extension of \(m^j_\pm\) to \(\{y < 0\}\), and

\[
W_0^0 \in \bigcap_{j=1}^{s+1} \mathcal{C}^j([0, T_0], H^{s+1-j})
\]

be the unique solution to the following Cauchy problem:

\[
\begin{align*}
P W_0^0 &= 0, & x > 0 \\
\partial^j_x W_0^0|_{x=0} &= \tilde{m}^j_\pm, & 1 \leq j \leq s.
\end{align*}
\]

Then the restriction

\[
\tilde{U}_0^0 = W_0^0|_{x>0}
\]

together with \(\varphi^0 \in H^{s+2}(\Omega_{T_0})\) given in Proposition 4.1 are the approximate solutions satisfying (5.3) (5.4). Indeed, since the initial data \((U_0^0, \varphi_0)\) satisfy the compatibility conditions up to \(s - 1\), and from (4.5) we conclude (5.4).

5.2. The iteration scheme. Let us prove the existence of the solution to (5.1).

Denote by \(E_T\) the extension operator given in the Lemma 3.1 of [19]. More precisely, for any fixed \(0 \leq T \leq \frac{T_0}{2}\), \((v_+, v_-, \varphi)\) satisfies \(\|(v_+, v_-, \varphi)\|_{s, \lambda, T} < \infty\) and

\[
\begin{align*}
\partial^j_x v_\pm|_{x=0} &= 0, & 0 \leq j \leq s - 1 \\
\partial^j_x \varphi|_{x=0} &= 0, & 0 \leq j \leq s
\end{align*}
\]
the extended function $E_T(v_+, v_-, \varphi)$ satisfies

$$
(5.7) \quad \begin{cases}
E_T(v_+, v_-, \varphi) = (v_+, v_-, \varphi) & \text{for } 0 \leq x \leq T \\
E_T(v_+, v_-, \varphi) = 0 & \text{for } x < 0 \text{ and } x > T_0 \\
\|E_T(v_+, v_-, \varphi)\|_{s_1, \lambda, T_0} \leq C_s\|(v_+, v_-, \varphi)\|_{s_1, \lambda, T} & \text{for any } 0 \leq s_1 \leq s
\end{cases}
$$

with a constant $C_2$ depending only on $s$.

As in [19], we introduce the iteration scheme for the problem (5.1). Let us define the functions inductively as the following:

$$
(5.8) \quad ((U^n_+, U^n_-, \varphi^n) = (\tilde{U}^0_+, \tilde{U}^0_-, \varphi^0) + E_{T_n}(W^n_+, W^n_-, \psi^n) \text{ with } (W^n_+, W^n_-, \psi^n) = (0, 0, 0)
$$

where $(\tilde{U}^0_+, \tilde{U}^0_-, \varphi^0)$ is the approximate solution constructed in section 5.1 and $(W^n_+, W^n_-, \psi^n)$ is the unique solution for $0 \leq t \leq T_n$ to the following problem provided $(W^n_+, W^n_-, \psi^n) = (0, 0, 0)$ being known already for $0 \leq x \leq T_{n-1}$:

$$
(5.9) \quad \begin{cases}
L^\pm(U^{n-1}_+, \varphi^{n-1})W^n_+ = f^n_+ & x > 0 \\
B'(U^{n-1}_-, \varphi^{n-1}_-, \varphi^n_-, \varphi^n_+)\left((W^n_+, W^n_-, \psi^n_+, \psi^n_+)\right) = g^n & x < 0
\end{cases}
$$

where $B'(U_+, U_-, \varphi, \varphi, \varphi, \varphi, \varphi)$ denotes the Fréchet derivatives of $B_k$ with respect to their arguments at $(U_+, U_-, \varphi, \varphi, \varphi, \varphi, \varphi)$, i.e.

$$
\frac{d}{de} B(U_+ + eW_+, U_- + \epsilon W_-, \varphi_+ + \epsilon \psi_+, \varphi_- + \epsilon \psi_-) \bigg|_{e=0},
$$

and

$$
g^n = G(U^{n-1}_+, U^{n-1}_-, \varphi^{n-1}_-, \varphi^{n-1}_+),
$$

$$(E_{T_{n-1}}W^n_{+1}, E_{T_{n-1}}W^n_{-1}, (E_{T_{n-1}}\varphi^{n+1})_x, (E_{T_{n-1}}\varphi^{n+1})_x)$$

As in [19], we expect to obtain the existence result by using the uniform stability result, namely Theorem 3.3.

For any fixed $s \geq 9$, we denote by $C_s$ the Sobolev embedding constant satisfying

$$
\|v_+\|_{L^\infty(\Omega_+)} + \|v_-\|_{L^\infty(\Omega_-)} + \|\varphi\|_{W^{1, \infty}(\partial\Omega_+)} \leq C_s\|(v_+, v_-, \varphi)\|_{s, T}
$$

for any $(v_+, v_-, \varphi) \in H^s \times H^s \times H^{s+1}$, and $\epsilon_0 > 0$ a small quantity such that $(U_+, U_-, \varphi)$ satisfies

$$
(5.10) \quad \|(U_+ - U^n_+, U_- - U^n_-, \varphi - \varphi^n(y) - x\sigma(y))\|_{s, T_0} < \epsilon_0
$$

we have the estimate (3.4) valid.

For the iteration scheme (5.8), let us define

$$
T'_n = \min \{T \mid \|(W^n_+, W^n_-, \psi^n)\|_{s, T} \geq \epsilon_0\}
$$

and

$$
T_n = \min \left(\frac{T_0}{2}, T'_n\right).
$$
We have the following two propositions to prove Theorem 2.3:

**Proposition 5.1.** (Boundness) For any fixed $s \geq 9$, and $\epsilon_0 > 0$ being given in (5.10), there are $\beta \in (0, 1)$ and $T_*> 0$ such that the solution sequence $(W^n_+, W^n_-, \psi^n)$ defined by (5.8) satisfies

\[
\| (W^n_+, W^n_-, \psi^n) \|_{s, \lambda(T_*), T_*} < \epsilon_0 \quad (\forall n \in \mathbb{N})
\]

where $\lambda(T) = C_0 T^{-\beta}$.

**Proof.** Let briefly recall the proof of Proposition 4.1 in [19]. We shall prove the estimate (5.12) by induction on $n$. Obviously, it is true for $n = 0$. Assuming that (5.12) holds for the case $n - 1$, we study the problem (5.9).

Employing Theorem 3.3 for (5.9), it follows

\[
\| (W^n_+, W^n_-, \psi^n) \|_{s, \lambda(T_*), T_*} \leq C_1 \left( \frac{1}{\lambda(T)} \| f^n_+ \|_{s, \lambda(T), T}^2 + \| f^n_- \|_{s, \lambda(T), T}^2 + \| g^n \|_{s, \lambda(T), T}^2 \right).
\]

Without loss of generality, we consider the case $0 < T_0 \leq 1$, which yields

\[ e^{-2C_0} \leq e^{-2C_{0\alpha} T^{-\beta}} \leq 1 \]

for any $0 \leq \beta < 1$ and $0 \leq x \leq T \leq T_0 \leq 1$.

From the definition, we can easily deduce

\[
\left\{
\begin{array}{l}
|f^n_+|_{s, \lambda(T), T} \leq C_2 \sum_{k=0}^{s} T^{-2\beta(s-k)} |f^n_+|_{k, T}^2 \\
|g^n|_{s, \lambda(T), T} \leq C_2 \sum_{k=0}^{s} T^{-2\beta(s-k)} |g^n|_{k, T}^2 \\
\| (W^n_+, W^n_-, \psi^n) \|_{s, T}^2 \leq C_2 \| (W^n_+, W^n_-, \psi^n) \|_{s, \lambda(T), T}^2
\end{array}
\right.
\]

with an absolute constant $C_2 > 0$ when $\lambda(T) = C_0 T^{-\beta}$.

Therefore, from (5.13) we get

\[
\| (W^n_+, W^n_-, \psi^n) \|_{s, T}^2 \leq C_2 \left( T^\beta \sum_{k=0}^{s} T^{-2\beta(s-k)} (|f^n_+|_{k, T}^2 + |f^n_-|_{k, T}^2) + \sum_{k=0}^{s} T^{-2\beta(s-k)} |g^n|_{k, T}^2 \right).
\]

On the other hand, we have the following interpolation inequality:

\[
\left\{
\begin{array}{l}
|f^n_+|_{k, T} \leq \tilde{C}_s |f^n_+|_{2k/\gamma, T} \| f^n_+ \|_{0, T}^{2-2k/\gamma} \\
|g^n|_{k, T} \leq \tilde{C}_s |g^n|_{2k/\gamma, T} \| g^n \|_{0, T}^{2-2k/\gamma}
\end{array}
\right.
\]

for any $0 \leq T \leq T_0/2$, $0 \leq k \leq s$ with $\tilde{C}_s$ depending only upon $s$.

From the assumption (A2), and the induction assumption on $(W^n_+, W^n_-, \psi^n)$, we have a constant $\tilde{C}(\epsilon_0)$ depending only upon $\epsilon_0 > 0$ such that

\[
|f^n_+|_{s, T_0} \leq \tilde{C}(\epsilon_0)
\]

for $f^n_+$ given in (5.9).

Furthermore, by using $f^n_+ |_{s < 0} = 0$ and $\| f^n_+ \|_{C^1(\Omega T_0)} \leq C$, we have

\[
|f^n_+|_{0, T}^2 \leq C T^3.
\]

Substituting (5.16) and (5.17) into (5.15), it follows

\[
|f^n_+|_{k, T} \leq C T^{3+3k/\gamma} \quad (0 \leq k \leq s)
\]
which implies
\begin{equation}
(5.19) \quad \sum_{k=0}^{s} T^{-2\beta(s-k)} (|f_{n,k}^n|^2 + |f_{n,k}^n|^2) \leq C(1 + T^{3/s-2\beta})
\end{equation}
when \( 0 \leq \beta \leq \frac{2}{2s+1} \).

From the property of Newton iteration scheme, we get
\[ g^n = -B(\bar{U}_+^0, \bar{U}_-^0, \partial_x \varphi^0, \partial_y \varphi^0) + O(|E_{T_{n-1}}(W_+^{n-1}, W_-^{n-1}, \partial_x \psi^{n-1}, \partial_z \psi^{n-1})|^2) \]
which implies
\begin{equation}
(5.20) \quad \langle g^n \rangle_{s,T}^2 \leq C \langle B(\bar{U}_+^0, \bar{U}_-^0, \partial_x \varphi^0, \partial_z \varphi^0) \rangle_{s,T}^2 + \|(W_+^{n-1}, W_-^{n-1}, \psi^{n-1})\|_{s,T}^4
\end{equation}

Similar to (5.18), we obtain
\begin{equation}
(5.21) \quad (\langle g^n \rangle_{0,T}^2 \leq CT^3
\end{equation}
by using \( g^n \big|_{x=0} = 0 \) and \( \|g^n\|_{C^{1}(\partial_\Omega T)} \leq C \).

Substituting (5.20) and (5.21) into (5.15), it follows
\[ \langle g^n \rangle_{s,T}^2 \leq CT^{3-3k/s} \left( \langle B(\bar{U}_+^0, \bar{U}_-^0, \partial_x \varphi^0, \partial_z \varphi^0) \rangle_{s,T}^2 + \|(W_+^{n-1}, W_-^{n-1}, \psi^{n-1})\|_{s,T}^4 \right)^{k/s} \]
which implies
\begin{equation}
(5.22) \quad C \left( T^{3-2\beta s} + \langle B(\bar{U}_+^0, \bar{U}_-^0, \partial_x \varphi^0, \partial_z \varphi^0) \rangle_{s,T}^2 + \|(W_+^{n-1}, W_-^{n-1}, \psi^{n-1})\|_{s,T}^4 \right)^{k/s} \leq \sum_{k=0}^{s} T^{-2\beta(s-k)} (\langle g^n \rangle_{k,T}^2)
\end{equation}

Substituting (5.19) and (5.22) into (5.14), we conclude
\[ \|(W_+^{n}, W_-^{n}, \psi^n)\|_{s,T}^2 \leq C \left( T^{3-2\beta s} + T^\beta + T^{3/s-\beta} + \langle B(\bar{U}_+^0, \bar{U}_-^0, \partial_x \varphi^0, \partial_z \varphi^0) \rangle_{s,T}^2 + \|(W_+^{n-1}, W_-^{n-1}, \psi^{n-1})\|_{s,T}^4 \right)^{k/s} \]
which implies that there exist \( T_* > 0, \epsilon_0 > 0 \) such that if \( \|(W_+^{n-1}, W_-^{n-1}, \psi^{n-1})\|_{s,T_*}^2 < \epsilon_0 \), we have
\begin{equation}
(5.23) \quad \|(W_+^{n}, W_-^{n}, \psi^n)\|_{s,T_*}^2 < \epsilon_0
\end{equation}
\[ \square \]

**Proposition 5.2. (Convergence)** Under the same assumption as in Proposition 5.1, there are constants \( C_1, C_2 > 0 \) depending only on \( \delta \), such that for any \( \lambda > C_2 \) and \( T \leq T_* \), we have
\[ \|(W_+^{n+1}, W_-^{n+1}; \psi^{n+1}) - (W_+^{n}, W_-^{n}, \psi^n)\|_{0,\lambda,T}^2 \leq C_1 \left( \frac{1}{\lambda} + T^2 \right) \|(W_+^{n}, W_-^{n}, \psi^n) - (W_+^{n-1}, W_-^{n-1}, \psi^{n-1})\|_{0,\lambda,T}^2. \]
Proof. When $T \leq T_s$, we can omit $E_{r_{n-1}}$ in the problem (5.9), from which we know that $(W^{n+1}_+, W^{n+1}_-, W^n_-, \psi^{n+1}_-, \psi^n_+)$ satisfies the following problem (5.25)

$$
\begin{cases}
L^\pm(U^\pm, \phi^\pm)(W^{n+1}_+ - W^n_+) = \tilde{f}^{n+1}_+ + L^\pm(U^\pm, \phi^{n-1})U^n_+ \\
B'(U^\pm, \phi^\pm)(W^{n+1}_+ - W^n_+, W^n_+ - W^n_-, \psi^n_+ - \psi^n_+) = \tilde{g}^{n+1}_+
\end{cases}
$$

Employing Theorem 3.3 for the problem (5.25), it yields

$$
\begin{aligned}
&\left\| (W^{n+1}_+ - W^n_+, W^n_+ - W^n_-, \psi^{n+1}_+, \psi^n_-) \right\|^2_{0, \lambda, T} \\
\leq &\ C_1 \left( \frac{1}{\lambda} \left( \| f^{n+1}_{\pm} \|^2_{0, \lambda, T} + \| f^{n+1}_{-} \|^2_{0, \lambda, T} + \langle \tilde{g}^{n+1} \langle \| \psi_{\pm}^{n+1} \|^2_{0, \lambda, T} \rangle \right) .
\end{aligned}
$$

On the other hand, from (5.26) we easily deduce

$$
\begin{aligned}
&\left\| (W^{n+1}_+ - W^n_+, W^n_+ - W^n_-, \psi^{n+1}_+, \psi^n_-) \right\|^2_{0, \lambda, T} \\
\leq &\ C_2 \left( \| f^{n+1}_{\pm} \|^2_{0, \lambda, T} + \| f^{n+1}_{-} \|^2_{0, \lambda, T} + \langle \tilde{g}^{n+1} \langle \| \psi_{\pm}^{n+1} \|^2_{0, \lambda, T} \rangle \right) .
\end{aligned}
$$

when $T \leq T_s$ be using Proposition 5.1. Thus, we immediately conclude (5.24) from (5.27) and (5.28).

With the above two propositions, we can prove Theorem 2.3.

The proof of Theorem 2.3: From Proposition 5.2 we know that there are $T_{s*} \in (0, T_s)$, $\alpha \in (0, 1)$ and $\lambda_0 > 0$ such that

$$
\begin{cases}
\| (W^{n+1}_+ - W^n_+, W^n_+ - W^n_-, \psi^{n+1}_+, \psi^n_-) \|^2_{0, \lambda_0, T_{s*}} \\
\leq &\ \alpha \| (W^n_+ - W^n_+, W^n_+ - W^n_-, \psi^n_-) \|^2_{0, \lambda_0, T_{s*}}
\end{cases}
$$

From Proposition 5.1 we know that $(W^n_+, W^n_-, \psi^n)$ is bounded in $H^s \times H^s \times H^{s+1}$ for $0 \leq \alpha \leq T_s$. Thus we obtain $(W_+, W_-, \psi) \in H^s(\Omega_{T_{s*}}) \times H^s(\Omega_{T_{s*}}) \times H^{s+1}(\partial \Omega_{T_{s*}})$ such that

$$
\begin{cases}
W^n_+ \rightarrow W^\pm_+ \text{ in } H^r(\Omega_{T_{s*}}) \\
\psi^n \rightarrow \psi \text{ in } H^{r+1}(\partial \Omega_{T_{s*}})
\end{cases}
$$

for any $0 \leq r < s$, and

$$
U^\pm_+ := \tilde{U}^0_+ + W^\pm_+ , \quad \phi = \varphi^0 + \psi
$$

are the solutions to (5.1). □

References


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