

SOLITON DYNAMICS IN A POTENTIAL

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ABSTRACT. We study the semiclassical limit of subcritical focussing NLS with a potential, for initial data of the form $s(\frac{x-x_0}{\epsilon})e^{i\frac{v_0 \cdot x}{\epsilon}}$, where s is the ground state of an associated unscaled problem. We show that in the semiclassical limit, the solution has roughly the form $s(\frac{x-x^\epsilon(t)}{\epsilon})e^{i\frac{v^\epsilon(t) \cdot x}{\epsilon}}$, and we show that the approximate center of mass $x^\epsilon(\cdot)$ converges to a solution of the equation $x'' = -DV(x)$, $x(0) = x_0$, $x'(0) = v_0$ as $\epsilon \rightarrow 0$.

1. Introduction

In this paper we study the $\epsilon \rightarrow 0$ limit of solutions $u^\epsilon : \mathbb{R}^n \times [0, \infty) \rightarrow \mathbb{C} \cong \mathbb{R}^2$ of the equation

$$(1.1) \quad iu_t^\epsilon + \frac{\epsilon}{2}\Delta u^\epsilon + \frac{1}{\epsilon}|u^\epsilon|^{p-1}u^\epsilon - \frac{1}{\epsilon}V(x)u^\epsilon = 0$$

with initial data

$$(1.2) \quad u^\epsilon(\cdot, 0) = \phi^\epsilon, \quad \text{where } \phi^\epsilon(x) \sim s\left(\frac{x-x_0}{\epsilon}\right)e^{i\frac{v_0 \cdot x}{\epsilon}},$$

where s is the ground state solution of an associated scalar elliptic problem. This data can be thought of as corresponding to a point particle with position x_0 and velocity v_0 . Roughly speaking, we show that in the limit $\epsilon \rightarrow 0$, $u^\epsilon(x, t) \sim \rho^\epsilon e^{i\frac{v^\epsilon(t) \cdot x}{\epsilon}}$, where $\rho^\epsilon(x, t) \sim s(\frac{x-X^\epsilon(t)}{\epsilon})$, the center of mass $X^\epsilon(t)$ of the solution converges, as $\epsilon \rightarrow 0$ to the solution of the ordinary differential equation

$$(1.3) \quad x'' = -DV(x), \quad x(0) = x_0, \quad x'(0) = v_0,$$

and $v^\epsilon(t) \rightarrow v(t) = x'(t)$.

Similar problems in linear geometric asymptotics were studied intensively in the 70's, see for example Guilleman and Sternberg [7]. Motivated by these linear results, Alan Weinstein [16] proposed the study of geometric optics for certain nonlinear equations, including (1.1). In the same paper, Weinstein proves that on the sphere S^2 , the wave equation with a focussing cubic nonlinearity has a family of solutions u^ϵ with $\|u^\epsilon\|_{L^2} = \epsilon$, and concentrating around geodesics as $\epsilon \rightarrow 0$. The proof relies on some estimates established by Stanton and Weinstein [15].

Later work of Floer and Weinstein [5] showed that, if X_0 is any nondegenerate critical point of V , then for all sufficiently small ϵ there exists a standing wave solution u^ϵ of (1.1) such that u^ϵ concentrates around X_0 as $\epsilon \rightarrow 0$. This was

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subsequently generalized in several papers of Y.-G. Oh, see for example [13], [14]. Recent work on the same problem includes papers of Ambrosetti *et al* [1] and Li [12].

The papers mentioned above are all concerned with standing wave solutions, and thus reduce to the study of elliptic equations. A first result about the full dynamic problem (1.1) was established by Grillakis, Shatah, and Strauss [6]. They establish, as a special case of a more general theory, the orbital stability of the standing wave solutions of Floer and Weinstein when the critical point of V is a local minimum.

There has also been a good deal of work in the mathematical physics community on this and related questions, often in the general framework of studying nonintegrable perturbations of integrable systems. For example, problems very similar to the ones we consider here are studied in Kaup and Newell [9] and Keener and McLaughlin [10].

The present paper is the first that we know of to establish any rigorous results about the asymptotic behavior of (1.1) in the case where the limiting classical trajectory is nontrivial. We do not linearize the equation. We show instead that the result follows easily from conservation laws for the equation, if the mass density of the solution can be shown to be sufficiently close to a point mass. We accomplish the latter using well-known results on the nonlinear stability of ground states. Many of the techniques we use were developed in [4] and [8] in somewhat different contexts.

2. Preliminaries

For two vectors $u, v \in \mathbb{C}$, we use “ \cdot ” to denote the *real* inner product, $u \cdot v = \frac{1}{2}(u\bar{v} + \bar{u}v)$.

We write $o_\epsilon(1)$ to denote a quantity that vanishes as $\epsilon \rightarrow 0$.

We follow the convention that repeated indices are summed.

We also assume that the exponent p in (1.1) satisfies $1 < p < 1 + \frac{4}{n}$.

2.1. Densities. We define a number of functionals acting on functions $v \in H^1(\mathbb{R}^n)$: the total mass

$$(2.1) \quad M^\epsilon[v] = \int m_v^\epsilon dx, \quad m_v^\epsilon = \frac{1}{\epsilon^n} |v|^2;$$

the total energy

$$(2.2) \quad E^\epsilon[v] = \int e_v^\epsilon dx, \quad e_v^\epsilon = \frac{1}{2\epsilon^{n-2}} |Dv|^2 - \frac{2}{\epsilon^n} \frac{|v|^{p+1}}{p+1} + \frac{1}{\epsilon^n} V(x) |v|^2;$$

and the momentum

$$(2.3) \quad P^\epsilon[v] = \int p_v^\epsilon dx, \quad p_v^\epsilon = \frac{1}{\epsilon^{n-1}} i v \cdot Dv.$$

In the final equation, p_v^ϵ is a vector with components $p_v^{\epsilon,j} = \frac{1}{\epsilon^{n-1}} i v \cdot v_{x_j}$, for $j = 1, \dots, n$.

Smooth solutions of (1.1) satisfy the following identities.

$$(2.4) \quad \frac{\partial}{\partial t} m_{u^\epsilon}^\epsilon = -\operatorname{div} p_{u^\epsilon}^\epsilon,$$

$$(2.5) \quad \frac{\partial}{\partial t} e_{u^\epsilon}^\epsilon = \frac{1}{\epsilon^{n-2}} \operatorname{div}(Du^\epsilon \cdot u_t^\epsilon),$$

and

$$(2.6) \quad \frac{\partial}{\partial t} p_{u^\epsilon}^{\epsilon,j} = -\frac{1}{\epsilon^{n-2}} (u_{x_j}^\epsilon \cdot u_{x_k}^\epsilon)_{x_k} + \left(e_{u^\epsilon}^\epsilon + \frac{1}{\epsilon^{n-1}} i u^\epsilon \cdot u_t^\epsilon \right)_{x_j} - V_{x_j}(x) m_{u^\epsilon}^\epsilon.$$

For a function v taking values in \mathbb{C} ,

$$(2.7) \quad \begin{aligned} |v_{x_j}|^2 &= (v_{x_j} \cdot \frac{v}{|v|})^2 + (v_{x_j} \cdot \frac{iv}{|v|})^2 \\ &= (|v|_{x_j})^2 + \epsilon^{n-2} \frac{|p_v^{\epsilon,j}|^2}{m_v^\epsilon}. \end{aligned}$$

Using this fact, we can decompose the energy in the form $E^\epsilon[v] = E_b^\epsilon[v] + E_k^\epsilon[v] + E_p^\epsilon[v]$, where

$$E_b^\epsilon[v] = \int e_{b,v}^\epsilon, \quad e_{b,v}^\epsilon = \frac{2}{\epsilon^n} |D|v||^2 - \frac{1}{2\epsilon^n} \frac{|v|^{p+1}}{p+1};$$

$$E_k^\epsilon[v] = \int e_{k,v}^\epsilon, \quad e_{k,v}^\epsilon = \frac{|p_v^\epsilon|^2}{2m_v^\epsilon};$$

$$E_p^\epsilon[v] = \int e_{p,v}^\epsilon, \quad e_{p,v}^\epsilon = \frac{1}{\epsilon^n} V(x) |v|^2 = V m_v^\epsilon.$$

We refer to these as the binding energy, the kinetic energy, and the potential energy respectively. Note that the binding energy depends only on the magnitude $|v|$ of v . Although the total energy E^ϵ is conserved for solutions of (1.1), in general E_b^ϵ , E_k^ϵ , and E_p^ϵ can vary with time.

2.2. Existence of solution. It is known that for initial data $\phi^\epsilon \in H^1(\mathbb{R}^n)$, (1.1) has a unique solution that exists globally in time, and that these solutions depend continuously on the initial data; see [3], Theorem 6.3.2 and Remark 6.3.4.

If in addition $\phi^\epsilon \in H^2(\mathbb{R}^n)$ then $u^\epsilon(t) \in H^2(\mathbb{R}^n)$ for all $t > 0$; see [3], Theorem 5.2.3 and Remark 5.2.9.

As a consequence, if $\phi^\epsilon \in H^2(\mathbb{R}^n)$ then the flux terms in (2.4), (2.5), and (2.6) integrate to zero, and thus

$$(2.8) \quad \frac{d}{dt} M^\epsilon[u^\epsilon(t)] = \frac{d}{dt} E^\epsilon[u^\epsilon(t)] = 0,$$

$$(2.9) \quad \frac{d}{dt} P^{\epsilon,j}[u^\epsilon(t)] = - \int_{\mathbb{R}^n} V_{x_j}(x) m_{u^\epsilon}^\epsilon dx.$$

These identities remain valid for initial data $\phi^\epsilon \in H^1$ by an approximation argument and the continuous dependence on the data.

We remark that the proof of well-posedness makes use of the estimate

$$(2.10) \quad \|Du^\epsilon(t)\|_{L^2} \leq C_\epsilon$$

for all $t > 0$, where the constant C_ϵ depends on the H^1 norm of the initial data ϕ^ϵ . We briefly recall why this holds. We find from the conservation of mass that

$$(2.11) \quad E_b^\epsilon[u^\epsilon(t)] + E_k^\epsilon[u^\epsilon(t)] = E^\epsilon[u^\epsilon(t)] - E_p^\epsilon[u^\epsilon(t)] \leq C,$$

using (2.8) and the assumption that V is bounded below. Once this is known, one can use the Gagliardo-Nirenberg inequality

$$\|v\|_{L^q} \leq C\|v\|_{L^2}^\theta \|Dv\|_{L^2}^{1-\theta}, \quad \text{where } \frac{n}{q} = \theta \frac{n}{2} + (1-\theta)\left(\frac{n}{2} - 1\right),$$

to estimate $\|u^\epsilon(t)\|_{p+1} \leq C$. At this stage we need to use the assumption $p < 1 + \frac{4}{n}$. The constant C depends on $M^\epsilon[u^\epsilon(0)]$ and $\sup_t (E_p^\epsilon[u^\epsilon(t)] + E_k^\epsilon[u^\epsilon(t)])$. The estimate $\|u^\epsilon(t)\|_{p+1} \leq C$ and (2.11) immediately imply (2.10).

2.3. Spectral estimate. For every $M > 0$ we define

$$I_M := \inf \{ E_b^\epsilon[v] : v \in H^1(\mathbb{R}^n; \mathbb{R}), M^\epsilon[v] = M \}.$$

Note that, by scale invariance, I_M does not depend of ϵ .

It is known that there is a positive, radial function s^ϵ such that

$$M^\epsilon[s^\epsilon] = M, \quad E_b^\epsilon[s^\epsilon] = I_M.$$

This minimizer is unique in the sense that if ϕ is any other function such that $M^\epsilon[\phi] = M$ and $E_b^\epsilon[\phi] = I_M$, then $\phi = \tau_y s^\epsilon$ for some $y \in \mathbb{R}^n$. Here $\tau_y f$ denotes f translated by y , that is, $\tau_y f(x) = f(x - y)$.

In fact more is true:

Proposition 1. *There exist constants $C, h > 0$ (depending on M, n, p) such that*

$$(2.12) \quad \min_{y \in \mathbb{R}^n} \left\{ \int \frac{1}{\epsilon^n} (\phi - \tau_y s^\epsilon)^2 + \int \frac{1}{\epsilon^{n-2}} |D(\phi - \tau_y s^\epsilon)|^2 \right\} \leq C(E_b^\epsilon(\phi) - E_b^\epsilon(s^\epsilon)).$$

for all nonnegative $\phi \in H^1(\mathbb{R}^n)$ such that $M^\epsilon(\phi) = M$ and $E_b^\epsilon(\phi) - E_b^\epsilon(s^\epsilon) < h$.

This was proven by Michael Weinstein [17], [18] in 1 and 3 space dimensions. Estimates in a subsequent paper of Kwong [11] combined with Weinstein's arguments show that Proposition 1 is valid without restrictions on the dimension.

This is the only place we use any specific properties of the nonlinearity, and indeed our results remain valid if the nonlinearity $|u|^{p-1}u$ is replaced by any $f(u) = F'(u)$ such that an estimate like (2.12) holds when $\frac{1}{p+1}|u|^{p+1}$ is replaced by $F(u)$ in the binding energy.

Once uniqueness is granted, it is easy to see that $s^\epsilon(x) = s^1(\frac{x}{\epsilon})$. It is known that there are constants $\alpha, C > 0$ such that

$$(2.13) \quad s^\epsilon(|x|) \leq Ce^{-\alpha|x|/\epsilon}$$

for all x .

2.4. A weak norm. We let $C^1(\mathbb{R}^n)$ denote the space of continuously differentiable, globally bounded and Lipschitz functions on \mathbb{R}^n , with norm

$$\|\phi\|_{C^1} := \|\phi\|_\infty + \|D\phi\|_\infty.$$

We write C^{1*} to denote the corresponding dual space, with the dual norm defined in the standard way. We identify finite Radon measures μ on \mathbb{R}^n with elements of C^{1*} in the natural way, so that

$$\|\mu\|_{C^{1*}} = \sup \left\{ \int_{\mathbb{R}^n} \phi(x) \mu(dx) : \phi \in C^1(\mathbb{R}^n), \|\phi\|_{C^1} \leq 1 \right\}.$$

Also, given an integrable function $f \in L^1(\mathbb{R}^n)$, we write $f dx$ to denote the Radon measure whose density with respect to Lebesgue measure is f .

The C^{1*} norm is of course somewhat weaker than the standard norms on measures or L^1 functions. It is closely related to the length of the minimal connection, as defined in Brezis, Coron, and Lieb [2]. For example, it is not hard to verify that for any $\xi, \eta \in \mathbb{R}^n$,

$$(2.14) \quad \|\delta_\xi - \delta_\eta\|_{C^{1*}} = \frac{2|\xi - \eta|}{2 + |\xi - \eta|}.$$

To see this, suppose $\xi, \eta \in \mathbb{R}^n$ are given, and consider any $f \in C^1(\mathbb{R}^n)$. Then for any $\theta \in [0, 1]$,

$$\begin{aligned} \int f(\delta_\xi - \delta_\eta) &= f(\xi) - f(\eta) \leq (1 - \theta)|f(\xi) - f(\eta)| + \theta|f(\xi) - f(\eta)| \\ &\leq (1 - \theta)2\|f\|_\infty + \theta\|Df\|_\infty|\xi - \eta|. \end{aligned}$$

Selecting $\theta = \frac{2}{2+|\xi-\eta|}$ yields that $\|\delta_\xi - \delta_\eta\|_{C^{1*}} \leq \frac{2|\xi-\eta|}{2+|\xi-\eta|}$. On the other hand, defining $f(x) := \theta \max\{\frac{1}{2}|\xi - \eta| - |x - \eta|, -\frac{1}{2}|\xi - \eta|\}$, for θ as above, it is easy to check that $\|f\|_{C^1} = 1$ and $f(\xi) - f(\eta) = \frac{2|\xi-\eta|}{2+|\xi-\eta|}$.

Note that (2.14) implies that for any $K > 0$ there exists some constant $C = C(K)$ such that

$$(2.15) \quad |\xi - \eta| \leq C\|\delta_\xi - \delta_\eta\|_{C^{1*}} \quad \text{whenever} \quad \|\delta_\xi - \delta_\eta\|_{C^{1*}} \leq K.$$

2.5. Statement of result. We assume throughout this paper that $V : \mathbb{R}^n \rightarrow \mathbb{R}$ is C^2 , and that $\|V\|_{C^2}$ is finite. This assumption could be weakened at the expense of complicating the arguments a little.

We assume there are $X_0, P_0 \in \mathbb{R}^n$ and $M > 0$ such that

$$(2.16) \quad M^\epsilon(\phi^\epsilon) = M \quad \text{for all } \epsilon \in (0, 1];$$

$$(2.17) \quad P^\epsilon(\phi^\epsilon) \rightarrow P_0;$$

and

$$(2.18) \quad \|m_{\phi^\epsilon}^\epsilon dx - M\delta_{X_0}\|_{C^{1*}} \rightarrow 0 \quad \text{as } \epsilon \rightarrow 0.$$

Informally, this amounts to assuming that ϕ^ϵ looks like a point particle with total mass M and momentum P_0 located at the point X_0 . We also assume that

$$(2.19) \quad E^\epsilon(\phi^\epsilon) \rightarrow I_M + \frac{1}{2M}|P_0|^2 + MV(X_0) \quad \text{as } \epsilon \rightarrow 0.$$

In view of Proposition 1 and Lemma 1, assumptions (2.16) – (2.18) imply that $\liminf E^\epsilon(\phi^\epsilon) \geq I_M + \frac{1}{2M}|P_0|^2 + MV(X_0)$, so the final assumption (2.19) essentially means that the energy of ϕ^ϵ is asymptotically as small as possible, given the constraints imposed by (2.16) – (2.18).

Note that initial data satisfying the above assumptions exist; for example, one could take

$$\phi^\epsilon(x) = s^\epsilon(x - X_0)e^{i\frac{V_0 \cdot x}{\epsilon}}, \quad V_0 = \frac{P_0}{M}.$$

Henceforth, u^ϵ denotes a solution to (1.1) with initial data ϕ^ϵ satisfying the above assumptions.

We will write m^ϵ , p^ϵ , instead of $m_{u^\epsilon}^\epsilon$, $p_{u^\epsilon}^\epsilon$, and so on, and similarly $P^\epsilon(t)$, $E_k^\epsilon(t)$ instead of $P^\epsilon[u^\epsilon(t)]$, $E_k^\epsilon[u^\epsilon(t)]$ etc.

We define $\rho^\epsilon := |u^\epsilon|$. Since the binding energy depends $E_b^\epsilon(v)$ depends only on $|v|$, it is clear that $E_b^\epsilon(\rho^\epsilon) = E_b^\epsilon(u^\epsilon)$.

Also, we will write $X(t)$, $P(t)$ for the classical trajectories, solving the ODE

$$(2.20) \quad M\dot{X} = P, \quad \dot{P} = -MDV(X), \quad X(0) = X_0, \quad P(0) = P_0.$$

Note that

$$(2.21) \quad \frac{|P(t)|^2}{2M} + MV(X(t)) = \frac{|P_0|^2}{2M} + MV(X_0), \quad \forall t > 0.$$

We will prove

Theorem 1. *Suppose that u^ϵ is a solution of (1.1) with initial data satisfying (2.16) – (2.19), and that u^ϵ satisfies (2.8) and (2.9). Suppose also that $X(t)$, $P(t)$ solve (2.20).*

Then

$$(2.22) \quad \|m^\epsilon(t)dx - M\delta_{X(t)}\|_{C^{1*}} + \|p^\epsilon(t)dx - P(t)\delta_{X(t)}\|_{C^{1*}} \rightarrow 0 \quad \text{as } \epsilon \rightarrow 0$$

uniformly for $t \in [0, T]$, for any $T > 0$.

In addition, for $\epsilon > 0$ there exist functions $y^\epsilon : [0, \infty) \rightarrow \mathbb{R}^n$ such that $y^\epsilon(t) \rightarrow X(t)$ as $\epsilon \rightarrow 0$, uniformly for $t \in [0, T]$ for any $T > 0$, and

$$(2.23) \quad \frac{1}{\epsilon^n} \|\rho^\epsilon - \tau_{y^\epsilon} s^\epsilon\|_{L^2}^2 + \frac{1}{\epsilon^{n-2}} \|D(\rho^\epsilon - \tau_{y^\epsilon} s^\epsilon)\|_{L^2}^2 \rightarrow 0 \quad \text{as } \epsilon \rightarrow 0.$$

Also, $P^\epsilon(t) \rightarrow P(t)$ uniformly for $t \in [0, T]$, and

$$(2.24) \quad \frac{1}{\epsilon^n} \left\| \epsilon \frac{i u^\epsilon \cdot Du^\epsilon}{\rho^\epsilon} - \frac{P^\epsilon(t)}{M} \rho^\epsilon \right\|_{L^2}^2 \rightarrow 0 \quad \text{as } \epsilon \rightarrow 0.$$

Remark 1. Since $\|m^\epsilon dx\|_{C^{0*}}, \|p^\epsilon dx\|_{C^{0*}}$ are uniformly bounded, (2.22) immediately implies a slightly stronger result: $m^\epsilon(t)dx \rightharpoonup M\delta_{X(t)}$ and $p^\epsilon(t)dx \rightharpoonup P(t)\delta_{X(t)}$ in the weak-* topology of measures as the dual of C^0 .

Remark 2. The assertion $u^\epsilon(x, t) \sim s^\epsilon(x - y^\epsilon)e^{i\frac{P^\epsilon \cdot x}{M^\epsilon}}$ is made precise in (2.23) and (2.24).

3. Proofs

Let $\zeta \in C_c^\infty$ be a smooth function such that

$$\zeta(x) = 1 \text{ if } |x| \leq R, \quad \zeta(x) = 0 \text{ if } |x| \geq 2R.$$

Here R is some large number that will be chosen in the proof of Lemma 5 below. The choice of R will depend only on T , the initial data, and the potential V . The choice of R will imply, among other things, that $|X(t)| \leq R$ for all $t \in [0, T]$.

We define

$$X^\epsilon(t) = \frac{1}{M} \int x \zeta(x) m^\epsilon(x) dx.$$

Define

$$\eta^\epsilon(t) = |X^\epsilon(t) - X(t)| + |P^\epsilon(t) - P(t)| + |MV(X(t)) - E_p(t)|.$$

Theorem 1 will follow from a simple argument involving Grönwall's inequality, and the following

Proposition 2. *There exist positive constants C , h_0 and ϵ_0 such that if*

$$T_\epsilon^* := \sup\{t \in [0, T] : \eta^\epsilon(s) < h_0 \quad \forall s \in (0, t)\}.$$

then

$$\|m^\epsilon(t)dx - M\delta_{X(t)}\|_{C^1(\mathbb{R}^n)^*} + \|p^\epsilon(t)dx - P^\epsilon(t)\delta_{X(t)}\|_{C^1(\mathbb{R}^n)^*} \leq C\eta^\epsilon(t) + o_\epsilon(1)$$

whenever $t \leq T_\epsilon^$ and $0 < \epsilon < \epsilon_0$.*

We first assume Proposition 2, as well as several other lemmas which will be established below, and present the proof of our main result.

Proof of Theorem 1. 1. We claim that to prove Theorem 1 it suffices to show that

$$(3.1) \quad \frac{d\eta^\epsilon}{dt} \leq C\eta^\epsilon(t) + o_\epsilon(1)$$

for all $t \leq T_\epsilon^*$. Indeed, the assumptions on the initial data imply that $\eta^\epsilon(0) = o_\epsilon(1)$, so that (3.1) readily implies that

$$\eta^\epsilon(t) \leq o_\epsilon(1)e^{ct}$$

for all $t < T_\epsilon^*$. In view of the definition of T_ϵ^* and the (obvious) continuity of η^ϵ , this implies that $T_\epsilon^* = T$ for all sufficiently small ϵ , and thus that $\eta^\epsilon(t) \rightarrow 0$ uniformly for $t \in [0, T]$. Then (2.22) follows immediately from Proposition 2.

Once we know that $\eta^\epsilon(t)$ vanishes, the existence of $y^\epsilon(t)$ satisfying (2.23) follows from Lemma 2 and Proposition 1, and Lemma 5 implies that $y^\epsilon(t) \rightarrow X$ as $\epsilon \rightarrow 0$. Finally, (2.24) follows from Lemmas 1 and 2, both proven below.

2. So we estimate $\dot{\eta}^\epsilon$. Note that

$$\dot{\eta}^\epsilon \leq \left| \dot{X}^\epsilon - \dot{X} \right| + \left| \dot{P}^\epsilon - \dot{P} \right| + \left| MDV(X) \cdot \dot{X} - \dot{E}_p \right|.$$

First, we compute the derivative of the i th component $X^{\epsilon,i}$ of $X^\epsilon(t)$:

$$\begin{aligned} \dot{X}^{\epsilon,i} &= \frac{1}{M} \int x_i \zeta(x) m_t^\epsilon(x, t) dx \\ &= -\frac{1}{M} \int x_i \zeta(x) \operatorname{div} p^\epsilon(x, t) dx \\ &= \frac{1}{M} \int (\delta_{ij} \zeta(x) + x_i \zeta_{x_j}(x)) p^{\epsilon,j}(x, t) dx \\ &= \frac{1}{M} \int (\delta_{ij} \zeta(x) + x_i \zeta_{x_j}(x)) P^{\epsilon,j}(t) \delta_{X(t)} + C\eta^\epsilon(t) + o_\epsilon(1), \end{aligned}$$

using Proposition 2 and the fact that $\|\delta_{ij} \zeta + x_i \zeta_{x_j}\|_{C^1} < \infty$. The integral then simplifies to $P^{\epsilon,i}(t)$, in view of the definition of ζ and the fact that $|X(t)| \leq R$. Thus

$$|\dot{X}^\epsilon - \dot{X}| \leq \frac{1}{M} |P^\epsilon(t) - P(t)| + C\eta^\epsilon(t) + o_\epsilon(1) \leq C\eta^\epsilon(t) + o_\epsilon(1).$$

3. Next we use (2.9), the ODE (2.20) and Proposition 2 to compute

$$\begin{aligned} \left| \dot{P}^\epsilon(t) - \dot{P}(t) \right| &= \left| - \int DV m^\epsilon(t) dx + MDV(X(t)) \right| \\ &\leq \|DV\|_{C^1} \|m^\epsilon(t) dx - M\delta_{X(t)}\|_{C^{1*}} \\ &\leq C\eta^\epsilon(t) + o_\epsilon(1). \end{aligned}$$

4. Finally,

$$\dot{E}_p^\epsilon(t) = \int V(x) m_t^\epsilon dx = - \int V(x) \operatorname{div} p^\epsilon dx = \int DV \cdot p^\epsilon(x) dx,$$

and Proposition 2 implies that

$$\left| \int DV \cdot p^\epsilon dx - P^\epsilon \cdot DV(X(t)) \right| \leq C\eta^\epsilon(t) + o_\epsilon(1).$$

This completes the proof of the theorem. \square

In the remainder of this paper, we give the proof of Proposition 2 and several auxilliary results. We first remark that

Lemma 1. $E_k^\epsilon(t) = \int \frac{|p^\epsilon|^2}{2m^\epsilon} \geq \frac{|P^\epsilon|^2}{2M}.$

Proof. We compute

$$\begin{aligned}
 (3.2) \quad \frac{1}{2} \int \left| \frac{p^\epsilon}{\sqrt{m^\epsilon}} - \frac{P^\epsilon(t)}{M} \sqrt{m^\epsilon} \right|^2 \\
 = \int \frac{|p^\epsilon|^2}{2m^\epsilon} dx - \frac{P^\epsilon(t)}{M} \cdot \int p^\epsilon dx + \frac{|P^\epsilon(t)|^2}{2M^2} \cdot \int m^\epsilon dx \\
 = E_k^\epsilon(t) - \frac{|P^\epsilon(t)|^2}{2M}.
 \end{aligned}$$

□

It is not hard to check that, for initial data as specified, the constant C_ϵ in the estimate (2.10) may be taken to be $C\epsilon^{n-2}$ for some fixed C . Then (2.7) and (2.10) imply that $E_k^\epsilon(t) \leq \epsilon^{2-n} \|Du^\epsilon\|_{L^2}^2 \leq C$, where C is independent of ϵ . Lemma 1 then implies that

$$(3.3) \quad |P^\epsilon(t)| \leq C$$

for all $t > 0$.

Next we prove a lemma showing that certain quantities can be estimated solely in terms of η . This lemma uses only the fact that energy is conserved for both the PDE (1.1) and the limiting ODE (2.20).

Lemma 2. *There exists some constant $C > 0$ such that*

$$(3.4) \quad E_b^\epsilon(t) - E_b^\epsilon(s^\epsilon) \leq C\eta^\epsilon + o_\epsilon(1),$$

and

$$(3.5) \quad E_k^\epsilon(t) - \frac{|P^\epsilon(t)|^2}{2M} \leq C\eta^\epsilon + o_\epsilon(1).$$

Proof. By the assumptions on the initial data and conservation of energy,

$$\begin{aligned}
 E_b^\epsilon(t) + E_k^\epsilon(t) &= E^\epsilon(t) - E_p^\epsilon(t) \\
 &= E^\epsilon(0) - E_p^\epsilon(t) \\
 &= E_b^\epsilon(s^\epsilon) + \frac{1}{2M} |P_0|^2 + MV(X_0) - E_p(t) + o_\epsilon(1) \quad \text{by (2.19)} \\
 &= E_b^\epsilon(s^\epsilon) + \frac{1}{2M} |P(t)|^2 + MV(X(t)) - E_p(t) + o_\epsilon(1) \quad \text{by (2.21)} \\
 &\leq E_b^\epsilon(s^\epsilon) + \frac{1}{2M} (|P^\epsilon(t)|^2 + |P(t)|^2 - |P^\epsilon(t)|^2) + \eta(t) + o_\epsilon(1).
 \end{aligned}$$

In the last line we have used the definition of η . Note also that

$$\begin{aligned}
 \frac{1}{2M} (|P(t)|^2 - |P^\epsilon(t)|^2) &= \frac{1}{2M} (P(t) + P^\epsilon(t)) \cdot (P(t) - P^\epsilon(t)) \\
 &\leq C\eta(t)
 \end{aligned}$$

using (3.3). Thus

$$(E_b^\epsilon(t) - E_b^\epsilon(s^\epsilon)) + \left(E_k^\epsilon(t) - \frac{|P^\epsilon(t)|^2}{2M} \right) \leq C\eta + o_\epsilon(1).$$

Since both terms in parentheses on the left-hand side are nonnegative, (3.4) and (3.5) follow. \square

The next two lemmas show that if $\eta^\epsilon(t)$ is small, then $m^\epsilon(t)$ is approximately a point mass $M\delta_{y^\epsilon(t)}$ in an appropriate weak norm, for some point $y^\epsilon(t)$, and similarly the momentum density $p^\epsilon(t)$ is roughly the (vector) point mass $P^\epsilon(t)\delta_{y^\epsilon(t)}$. The proof of Proposition 2 will be completed when we prove later that $|y^\epsilon(t) - X(t)| \leq C\eta^\epsilon(t) + o_\epsilon(1)$.

The first proof relies mainly on Proposition 1.

Lemma 3. *There exist constants $C, h_0 > 0$ independent of $\epsilon \in (0, 1]$ such that, if $\eta^\epsilon(t) < h_0$ then there exists some point $y^\epsilon(t) \in \mathbb{R}^n$ such that*

$$(3.6) \quad \|m^\epsilon(t)dx - M\delta_{y^\epsilon(t)}\|_{C^1(\mathbb{R}^n)^*} \leq C\eta^\epsilon(t) + o_\epsilon(1).$$

Proof. 1. Let $h_0 = \frac{h}{C}$, where h is the constant from Proposition 1 and C is the constant from Lemma 2. Fix any $t > 0$. Recall that we are writing $\rho^\epsilon = |u^\epsilon|$. Note that $\rho^\epsilon \in H^1$, ρ^ϵ is a nonnegative function, and $M^\epsilon[\rho^\epsilon] = M$. According to Lemma 2, if $\eta^\epsilon(t) < h_0$ then $E_b^\epsilon(\rho^\epsilon(t)) - E_b^\epsilon(s^\epsilon) \leq C\eta \leq Ch_0 \leq h$. Then Proposition 1 implies that there exists some $y^\epsilon(t) \in \mathbb{R}^n$ such that

$$(3.7) \quad \frac{1}{\epsilon^n} \int (\rho^\epsilon(t) - \tau_{y^\epsilon} s^\epsilon)^2 dx \leq C(E_b^\epsilon(\rho^\epsilon(t)) - E_b^\epsilon(s^\epsilon)) \leq C\eta^\epsilon(t).$$

In the rest of this proof of this lemma we will assume for notational simplicity that $y^\epsilon(t) = 0$, and we will write s^ϵ instead of $\tau_{y^\epsilon} s^\epsilon$. This does not involve any loss of generality.

To prove the lemma, we now need to show that

$$\left| \int_{\mathbb{R}^n} \psi m^\epsilon dx - M\psi(0) \right| \leq C\eta^\epsilon(t) + o_\epsilon(1) \quad \text{as } \epsilon \rightarrow 0.$$

for all $\psi \in C^1(\mathbb{R}^n)$ such that $\|\psi\|_{C^1} \leq 1$. For any such ψ ,

$$\begin{aligned} \int \psi(x) m_{s^\epsilon}^\epsilon(dx) - M\psi(0) &= \frac{1}{\epsilon^n} \int (\psi(x) - \psi(0)) (s^\epsilon(x))^2 (dx) \\ &\leq \frac{1}{\epsilon^n} \int |x| \left(s^1\left(\frac{x}{\epsilon}\right) \right)^2 dx \\ &= C\epsilon, \end{aligned}$$

after a change of variables. So it suffices to show that

$$\left| \int_{\mathbb{R}^n} \psi m^\epsilon dx - \int_{\mathbb{R}^n} \psi m_{s^\epsilon}^\epsilon dx \right| = \left| \frac{1}{\epsilon^n} \int_{\mathbb{R}^n} \tilde{\psi} ((\rho^\epsilon)^2 - (s^\epsilon)^2) (dx) \right| \leq C\eta^\epsilon(t) + o_\epsilon(1),$$

for $\tilde{\psi}(x) := \psi(x) - \psi(0)$.

2. The elementary inequality $a^2 - b^2 \leq 2(a - b)^2 + b^2$ and (3.7) imply that

$$(3.8) \quad \frac{1}{\epsilon^n} \int_{\mathbb{R}^n \setminus B_r} \tilde{\psi} ((\rho^\epsilon)^2 - (s^\epsilon)^2) dx \leq C \|\tilde{\psi}\|_{L^\infty} (\eta^\epsilon(t) + F(r/\epsilon)),$$

where

$$F(R) := \frac{1}{\epsilon^n} \int_{\mathbb{R}^n \setminus B_{\epsilon R}(0)} (s^\epsilon)^2 dx.$$

Note also that F is independent of ϵ since, as remarked earlier, $s^\epsilon(x) = s^1(\frac{x}{\epsilon})$. One easily verifies from (2.13) that

$$(3.9) \quad F(r) \leq C e^{-\tilde{\alpha} r}$$

for some $C, \tilde{\alpha} > 0$.

Also, since $\|\psi\|_{C^1} \leq 1$, $|\tilde{\psi}(x)| = |\psi(x) - \psi(0)| \leq |x|$, so

$$\frac{1}{\epsilon^n} \int_{B_r} \tilde{\psi} ((\rho^\epsilon)^2 - (s^\epsilon)^2) dx \leq \frac{r}{\epsilon^n} \int_{\mathbb{R}^n} ((\rho^\epsilon)^2 + (s^\epsilon)^2) dx = 2Mr.$$

Combining this with (3.8) and noting that $\|\tilde{\psi}\|_{L^\infty} \leq 2\|\psi\|_{L^\infty} \leq 2$, we find that

$$\frac{1}{\epsilon^n} \int_{\mathbb{R}^n} \tilde{\psi} ((\rho^\epsilon)^2 - (s^\epsilon)^2) dx \leq C (\eta^\epsilon(t) + r + F(r/\epsilon)).$$

In view of (3.9), the result follows by selecting $r = \epsilon \log \epsilon$. \square

The argument of the next proof is very similar to the preceeding one, except that here we use Lemma 1 to control the momentum, whereas before we used Proposition 1 to control the mass.

Lemma 4. *There exists a constant $C > 0$, independent of ϵ , such that if $\eta^\epsilon(t) < h_0$ then*

$$\|p^\epsilon(t)dx - P^\epsilon(t)\delta_{y^\epsilon(t)}\|_{C^1(\mathbb{R}^n)^*} \leq C\eta^\epsilon(t) + o_\epsilon(1).$$

Here h_0 is the small constant from Lemma 3.

Proof. Write $g^\epsilon(t) := \frac{p^\epsilon(t)}{\sqrt{m^\epsilon(t)}} - \frac{P^\epsilon(t)}{M} \sqrt{m^\epsilon(t)}$, and note that Lemmas 1 and 2 imply that

$$\|g^\epsilon(t)\|_{L^2}^2 \leq C\eta^\epsilon(t) + o_\epsilon(1).$$

Taking $\tilde{\psi}$ to equal the characteristic function of $\mathbb{R}^n \setminus B_r$ in (3.8), we obtain

$$\int_{\mathbb{R}^n \setminus B_r} m^\epsilon = \frac{1}{\epsilon^n} \int_{\mathbb{R}^n \setminus B_r} ((\rho^\epsilon)^2 - (s^\epsilon)^2) dx + F(r/\epsilon) \leq C (\eta^\epsilon(t) + F(r/\epsilon)).$$

The previous two estimates and Cauchy's inequality imply that

$$\int_{\mathbb{R}^n \setminus B_r} |g^\epsilon| \sqrt{m^\epsilon} dx \leq C (\eta^\epsilon(t) + F(r/\epsilon) + o_\epsilon(1))$$

for any $r > 0$. It is easy to check that $\int_{\mathbb{R}^n} g^\epsilon \sqrt{m^\epsilon} = 0$, so we see that

$$\left| \int_{B_r} g^\epsilon \sqrt{m^\epsilon} dx \right| \leq C (\eta^\epsilon(t) + F(r/\epsilon) + o_\epsilon(1)).$$

Thus for any $\psi \in C^1$ such that $\|\psi\|_{C^1} \leq 1$,

$$\begin{aligned} \left| \int_{\mathbb{R}^n} \psi \left(p^\epsilon(t) - \frac{P^\epsilon(t)}{M^\epsilon(t)} m^\epsilon \right) dx \right| &= \left| \int_{\mathbb{R}^n} \psi g^\epsilon \sqrt{m^\epsilon} dx \right| \\ &\leq \int_{\mathbb{R}^n \setminus B_r} |g^\epsilon| \sqrt{m^\epsilon} + |\psi(0)| \left| \int_{B_r} g^\epsilon \sqrt{m^\epsilon} \right| \\ &\quad + \sup_{y \in B_r} |\psi(0) - \psi(y)| \int_{B_r} |g^\epsilon| \sqrt{m^\epsilon} \\ &\leq C (\eta^\epsilon(t) + F(r/\epsilon) + r) + o_\epsilon(1). \end{aligned}$$

Choosing $r = \epsilon \log \epsilon$, we deduce that $\|p^\epsilon(t)dx - \frac{P^\epsilon(t)}{M} m^\epsilon(t)dx\|_{C^{1*}} \leq C\eta^\epsilon + o_\epsilon(1)$. Now the conclusion follows from Lemma 3 and the triangle inequality. \square

Combining Lemmas 3 and 4 we find that

$$\|m^\epsilon dx - M\delta_{y^\epsilon(t)}\|_{C^1(\mathbb{R}^n)^*} + \|p^\epsilon dx - P^\epsilon(t)\delta_{y^\epsilon(t)}\|_{C^1(\mathbb{R}^n)^*} \leq C\eta^\epsilon(t) + o_\epsilon(1)$$

whenever $\eta^\epsilon(t) \leq h_0$. To complete the proofs of Proposition 2 and Theorem 1 it therefore only remains to prove

Lemma 5. *There exists some $\epsilon_0 > 0$ such that if $\eta^\epsilon(t) \leq h_0$ and $\epsilon < \epsilon_0$, then*

$$\|\delta_{y^\epsilon(t)} - \delta_{X(t)}\|_{C^{1*}} \leq |y^\epsilon(t) - X(t)| \leq C\eta^\epsilon(t) + o_\epsilon(1).$$

Proof. 1. The first inequality follows from (2.14), so we only need to prove the second one.

Recall that $\zeta(x) \equiv 1$ if $|x| \leq R$, where R is some large constant that we have not yet chosen. So if $|y^\epsilon(t)| \leq R$,

$$\begin{aligned} |X(t) - y^\epsilon(t)| &\leq |X^\epsilon(t) - y^\epsilon(t)| + \eta^\epsilon(t) \\ &= \left| \frac{1}{M} \int x \zeta(x) (m^\epsilon(t) - M\delta_{y^\epsilon(t)}) (dx) \right| + \eta^\epsilon(t) \\ &\leq C \|x\zeta\|_{C^1} \|m^\epsilon(t)dx - M\delta_{y^\epsilon(t)}\|_{C^{1*}} + \eta^\epsilon(t) \\ &\leq C\eta^\epsilon(t) + o_\epsilon(1). \end{aligned}$$

It therefore suffices to show that we can choose R such that $|y^\epsilon(t)| \leq R$ for all $t \leq T_\epsilon^*$, when $\epsilon < \epsilon_0$. Thus in effect we need to bound the mobility of the particle.

2. Fix any $\psi \in C_c^1(\mathbb{R}^n)$ and times $t_1, t_2 \in [0, T_\epsilon^*]$ such that $t_1 < t_2$, and use (2.4) to calculate

$$\begin{aligned} \int \psi(m^\epsilon(t_2) - m^\epsilon(t_1))dx &= \int_{\mathbb{R}^n} \int_{t_1}^{t_2} \psi m_t^\epsilon dx dt \\ &= \int_{\mathbb{R}^n} \int_{t_1}^{t_2} -\psi \operatorname{div} p^\epsilon dt dx \\ &= \int_{\mathbb{R}^n} \int_{t_1}^{t_2} D\psi \cdot p^\epsilon dt dx \\ &\leq \|D\psi\|_\infty \int_{t_1}^{t_2} \left(2 \int_{\mathbb{R}^n} m^\epsilon dx \right)^{1/2} \left(\int_{\mathbb{R}^n} \frac{|p^\epsilon|^2}{2m^\epsilon} dx \right)^{1/2} \\ &\leq C|t_2 - t_1| \|\psi\|_{C^1}, \end{aligned}$$

where the constant depends on M and on the uniform bound (3.3). Thus the triangle inequality and (3.6) imply that

$$\|M\delta_{y^\epsilon(t_2)} - M\delta_{y^\epsilon(t_1)}\|_{C^{1*}} \leq C(\eta^\epsilon(t_1) + \eta^\epsilon(t_2) + |t_2 - t_1| + o_\epsilon(1)).$$

Since $t_i \leq T_\epsilon^* \leq T$ for $i = 1, 2$,

$$C(\eta^\epsilon(t_1) + \eta^\epsilon(t_2) + |t_2 - t_1| + o_\epsilon(1)) \leq C(2h + T + 1) := K,$$

for ϵ small enough that $o_\epsilon(1) \leq 1$. It then follows from (2.15) that there exists some $C = C(K)$ such that

$$|y^\epsilon(t_2) - y^\epsilon(t_1)| \leq C(K)\|M\delta_{y^\epsilon(t_2)} - M\delta_{y^\epsilon(t_1)}\|_{C^{1*}} \leq KC(K).$$

Also, it is clear from the definition of y^ϵ and the assumption (2.18) about the initial data that $|y^\epsilon(0) - X_0| \leq 1$ for all ϵ sufficiently small, so if we define $R := KC(K) + |X_0| + 1$, we obtain

$$|y^\epsilon(t)| \leq R,$$

for all $t \leq T_\epsilon^*$ and all small ϵ , as desired. \square

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