Symplectic log Calabi–Yau surface  
— deformation class

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Dedicated to Professor Shing-Tung Yau on the occasion of his 65th birthday

We study the symplectic analogue of log Calabi–Yau surfaces and show that the symplectic deformation classes of these surfaces are completely determined by the homological information.

1. Introduction

In [2] and [6], Auroux and Gross–Hacking–Keel proposed a way to interpret mirror symmetry for Looijenga pair $(X, D)$, where $X$ is a smooth projective surface over $\mathbb{C}$ and $D$ is an effective reduced anti-canonical divisor on $X$ with maximal boundary. Under mirror symmetry, certain symplectic invariants of $X − D$ are conjectured to be related to holomorphic invariants of its mirror. In this regard, Pascaleff showed in [24] that the symplectic cohomology of $X − D$ is, as a vector space, isomorphic to the global sections of the structure sheaf of its mirror. A step towards a deeper understanding of mirror symmetry for Looijenga pairs would be to classify them. The moduli spaces of such pairs were studied by Looijenga in [16] and Gross–Hacking–Keel in [7]. Friedman gave an excellent survey in [4]. Since one direction of mirror symmetry concerns about the symplectic invariants of $X − D$ instead of the holomorphic invariants, we would like to establish, in this paper, a classification for ‘symplectic log Calabi–Yau surfaces’ (including ‘symplectic Looijenga pairs’ as a special case). From symplectic point of view, we have the following definition of log Calabi–Yau surfaces.

For a connected closed symplectic 4 dimensional manifold $(X, \omega)$, which we assume throughout the whole paper, a symplectic divisor $D$ is a connected configuration of finitely many closed embedded symplectic surfaces (called irreducible components) $D = C_1 \cup \cdots \cup C_k$. $D$ is further required to have the following two properties: No three different $C_i$ intersect at a point and any intersection between two irreducible components is transversal and
positive. The orientation of each $C_i$ is chosen to be positive with respect to $\omega$.

**Definition 1.1.** A *symplectic log Calabi–Yau surface* $(X,D,\omega)$ is a closed symplectic real dimension four manifold $(X,\omega)$ together with a symplectic divisor $D$ representing the homology class of the Poincare dual of $c_1(X,\omega)$.

A symplectic Looijenga pair $(X,D,\omega)$ is a symplectic log Calabi–Yau surface such that each irreducible component of $D$ is a sphere.

Let $(X,D,\omega)$ be a symplectic log Calabi–Yau surface. By Theorem A of [15] or [22] and the adjunction formula, it is easy to show (Lemma 3.1) that $X$ is uniruled with base genus $0$ or $1$, and $D$ is a torus or a cycle of spheres. And if $(X,D,\omega)$ is a symplectic Looijenga pair then $X$ is rational.

Similar to studying the moduli space under complex deformation in the complex category, we would like to classify symplectic log Calabi–Yau surfaces up to symplectic deformation equivalence.

**Definition 1.2.** A *symplectic homotopy* (resp. *symplectic isotopy*) of $(X,D,\omega)$ is a smooth one-parameter family of symplectic divisors $(X,D_t,\omega_t)$ with $(X,D_0,\omega_0) = (X,D,\omega)$ (resp. such that in addition $\omega_t = \omega$ for all $t \in [0,1]$). $(X',D',\omega')$ is said to be *symplectic deformation equivalent* to $(X,D,\omega)$ if it is symplectomorphic to $(X,D_1,\omega_1)$ for some symplectic homotopy $(X,D_t,\omega_t)$ of $(X,D,\omega)$. The symplectic deformation equivalence is called **strict** if the symplectic homotopy is a symplectic isotopy.

**Definition 1.3.** Two symplectic log Calabi–Yau surfaces $(X^i,D^i,\omega^i)$ for $i = 1, 2$ are said to be *homological equivalent* if there is a diffeomorphism $\Phi : X^1 \to X^2$ such that $\Phi_*[C^1_j] = [C^2_j]$ for all $j = 1, \ldots, k$. The homological equivalence is called **strict** if $\Phi^*[\omega^2] = [\omega^1]$. We call $\Phi$ a (strict) homological equivalence.

Here is the main result of this paper.

**Theorem 1.4.** Let $(X^i,D^i,\omega^i)$ be symplectic log Calabi–Yau surfaces for $i = 1, 2$. Then $(X^1,D^1,\omega^1)$ is (resp. strictly) symplectic deformation equivalent to $(X^2,D^2,\omega^2)$ if and only if they are (resp. strictly) homological equivalent.

Moreover, the symplectomorphism in the (resp. strict) symplectic deformation equivalence has same homological effect as the (resp. strict) homological equivalence.
We remark that when \(D\) is a smooth divisor, the relative Kodaira dimension \(\kappa(X, D, \omega)\) was introduced in [14] and it was noted there that this notion could be extended to nodal divisors. With this extension understood, symplectic Calabi–Yau surfaces have relative Kodaira dimension \(\kappa = 0\) (cf. Theorem 3.28 in [14]). Moreover, Theorem 1.4 is also valid when \(\kappa(X, D, \omega) = -\infty\). This will be treated in the sequel. Coupled with the techniques developed in [11], [12], some applications to Stein fillings will also be treated in the sequel.

The paper is organized as follows. In Section 2 we introduce marked divisors and establish the invariance of their deformation class under blow-up/down in Proposition 2.10. This reduces Theorem 1.4 to the minimal cases. In Section 3, we classify the deformation classes of minimal models and finish the proof of Theorem 1.4.

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2. Symplectic deformation equivalence of marked divisors

We study the symplectic deformation equivalence property in a general setting, which was initiated by Ohta and Ono in [23]. Here we provide details using the notion of marked divisor, which encodes the blow-down information. We will show that the deformation class of marked symplectic divisors is stable under various operations.

2.1. Homotopy and blow-up/down of symplectic divisors

2.1.1. Homotopy. Parallel to the two types of homotopy of a symplectic divisor \((X, D, \omega)\) mentioned in the introduction,

- Symplectic isotopy \((X, D_t, \omega)\), and
- Symplectic homotopy \((X, D_t, \omega_t)\).

We also consider the more restrictive homotopies keeping \(D\) fixed:

- \(D\)–symplectic isotopy \((X, D, \omega_t)\) with constant \([\omega_t]\), and
- \(D\)–symplectic homotopy \((X, D, \omega_t)\).

In particular, \(D\)–symplectic homotopies/isotopies are symplectic homotopies. To compare these notions we introduce the following terminology.

Definition 2.1. Two symplectic homotopies \((X^1, D^1_t, \omega^1_t)\) and \((X^2, D^2_t, \omega^2_t)\) are symplectomorphic if there exist a one parameter family of symplectomorphism \(\Phi_t : (X^1, \omega^1_t) \to (X^2, \omega^2_t)\) such that \(\Phi_t(D^1_t) = D^2_t\) for all \(t \in [0, 1]\).
Lemma 2.2. A symplectic homotopy (resp. isotopy) of a symplectic divisor is symplectomorphic to a \(D^-\)symplectic homotopy (resp. isotopy) and vice versa.

Proof. A \(D^-\)symplectic homotopy is a symplectic homotopy by definition, and by Moser lemma a \(D^-\)symplectic isotopy is symplectomorphic to a symplectic isotopy.

On the other hand, a symplectic homotopy \((X, D_t, \omega_t)\) gives rise to a smooth isotopy \(\Phi : D \times [0, 1] \to X\). Since the intersections of \(D\) are transversal and no three of the components intersect at a common point, we can apply the smooth isotopy extension theorem to extend \(\Phi\) to a smooth ambient isotopy \(\Phi = \{\Phi_t\} : X \times [0, 1] \to X\). Then we get a \(D^-\)symplectic homotopy \((X, D, \Phi_t^* \omega)\) which is symplectomorphic to \((X, D_t, \omega_t)\) via the one parameter family of symplectomorphisms \(\{\Phi_t\}\). Similarly, a symplectic isotopy is symplectomorphic to a \(D^-\)symplectic isotopy. \(\square\)

Lemma 2.2 implies that symplectic isotopies (resp. homotopies) are the same as \(D^-\)symplectic isotopies (resp. homotopies), up to symplectomorphism. This simple observation will be repeatedly used.

2.1.2. Toric and non-toric blow-up/down. Throughout the paper, we use the following terminology for symplectic blow-up/down of \(D \subset (X, \omega)\).

A toric blow-up (resp. non-toric blow-up) of \(D\) is the total (resp. proper) transform of a symplectic blow-up centered at an intersection point (resp. at a smooth point) of \(D\).

Here, for blow-up at a smooth point \(p\) on the divisor \(D\), it means that we first do a \(C^0\) small perturbation of \(D\) to \(D'\) fixing \(p\) and then we do a symplectic blow-up of a ball centered at \(p\) such that \(D'\) coincide, in the local coordinates given by the ball, with a complex subspace. Similarly, for blow-up at an intersection point, a \(C^0\) small perturbation is performed so that \(D'\) is \(\omega\)-orthogonal at \(p\) and \(D'\) coincide, in the local coordinates given by the ball, with two complex subspaces.

To describe the corresponding blow-down operations, recall that an embedded symplectic sphere with self-intersection \(-1\) is called an exceptional sphere. The homology class of an exceptional sphere is called an exceptional class.

A toric blow-down refers to blowing down an exceptional sphere contained in \(D\) that intersects exactly two other irreducible components and exactly once for each of them. Moreover, we require that the intersections are positive and transversal. Such an exceptional sphere is called a toric exceptional sphere.
A **non-toric blow-down** refers to blowing down an exceptional sphere not contained in \( D \) that intersects exactly one irreducible component of \( D \) and exactly once with the intersection being positive and transversal. Such an exceptional sphere is called a non-toric exceptional sphere.

More precisely, for blow-down of a toric or non-toric exceptional sphere \( E \), we first perturb our symplectic divisor \( D \) to another symplectic divisor \( D' \) (or perturbing \( E \)) such that the intersections of \( D' \) and \( E \) are \( \omega \)-orthogonal (In the case that \( E \) is an irreducible component of \( D \), we require \( E \) has \( \omega \)-orthogonal intersections with all other irreducible components). Then, we will do the symplectic blow-down of \( E \) and \( D' \) will descend to a symplectic divisor.

**Definition 2.3.** An exceptional class \( e \) is called **non-toric** if \( e \) has trivial intersection pairing with all but one of the homology classes of the irreducible components of \( D \) and the only non-trivial pairing is 1.

An exceptional class \( e \) is called **toric** if \( e \) is homologous to an irreducible component of \( D \) such that \( e \) pairs non-trivially with the classes of exactly two other irreducible components of \( D \) and these two pairings are 1.

Clearly, the homology class of a toric (non-toric) exceptional sphere is a toric (non-toric) exceptional class. Conversely, we have the following observations.

For a toric exceptional class \( e \), the component of \( D \) with class \( e \) is obviously a toric exceptional sphere in the class \( e \). For a non-toric exceptional class \( e \), we also have an exceptional sphere in the class \( e \), at least when \( D \) is \( \omega \)-orthogonal.

**Lemma 2.4.** (cf. Theorem 1.2.7 of [20]) Let \( D \) be an \( \omega \)-orthogonal symplectic divisor. There is a non-empty subspace \( J(D) \) of the space of \( \omega \)-tamed almost complex structure making \( D \) pseudo-holomorphic such that for any non-toric exceptional class \( e \), there is a residue subset \( J(D,e) \subset J(D) \) so that \( e \) has an embedded \( J \)-holomorphic representative for all \( J \in J(D,e) \).

**Proof.** It is immediate to prove that \( e \) is \( D \)-good in the sense of Definition 1.2.4 in [20] if \( e \) is non-toric. Theorem 1.2.7 of [20] then implies the result. \( \square \)

### 2.2. Deformation of marked divisors

When we blow down an exceptional sphere, we encode the process by marking the descended symplectic divisor.
Definition 2.5. A marked symplectic divisor consists of a five-tuple

\[ \Theta = (X, D, \{p_j\}_{j=1}^l, \omega, \{I_j\}_{j=1}^l) \]

such that
- \( D \subset (X, \omega) \) is a symplectic divisor,
- \( p_j \), called centers of marking, are points on \( D \) (intersection points of \( D \) allowed),
- \( I_j : (B(\delta_j), \omega_{std}) \to (X, \omega) \), called coordinates of marking, are symplectic embeddings sending the origin to \( p_j \) such that \( I_j^{-1}(D) = \{x_1 = y_1 = 0\} \cap B(\delta_j) \) (resp. \( I_j^{-1}(D) = (\{x_1 = y_1 = 0\} \cup \{x_2 = y_2 = 0\}) \cap B(\delta_j) \)) if \( p_j \) is a smooth (resp. an intersection) point of \( D \). Moreover, we require that the image of \( I_j \) are disjoint. Here, \( B(\delta_j) \) is the standard symplectic ball of radius \( \delta_j \).

If \( p_j \) is an intersection point of \( D \), then we define the symplectic embedding \( I_j^e = I_j \circ \text{re} \), where \( \text{re}(x_1, y_1, x_2, y_2) = (-x_2, -y_2, x_1, y_1) \) interchanges the two subspaces \( \{x_1 = y_1 = 0\} \) and \( \{x_2 = y_2 = 0\} \). If \( p_j \) is a smooth point of \( D \), then we define \( I_j^e = I_j \). For simplicity, we denote a marked symplectic divisor as \((X, D, p_j, \omega, I_j)\) or \( \Theta \) and also call it a marked divisor if no confusion would arise.

Definition 2.6. Let \( \Theta = (X, D, p_j, \omega, I_j) \) be a marked divisor. A \( D \)-symplectic homotopy (resp. \( D \)-symplectic isotopy) of \( \Theta \) is a 4-tuple \((X, D, p_j, \omega_t)\) such that \( \omega_t \) is a smooth family of symplectic forms (resp. cohomologous symplectic forms) on \( X \) with \( \omega_0 = \omega \) and \( D \) being \( \omega_t \)-symplectic for all \( t \).

If \( \Theta^2 = (X^2, D^2, p_j^2, \omega^2, I_j^2) \) is another marked symplectic divisor and there is a symplectomorphism sending the 4-tuple \((X^2, D^2, p_j^2, \omega^2)\) to a 4-tuple \((X, D, p_j, \omega_1)\) which is symplectic homotopic (resp. isotopic) to \( \Theta \), then we say that \( \Theta \) and \( \Theta^2 \) are \( D \)-symplectic deformation equivalent (resp. strict \( D \)-symplectic deformation equivalent).

A symplectic divisor can be viewed as a marked divisor without markings.

Lemma 2.7. Two symplectic divisors are (strict) deformation equivalent if and only if they are (strict) \( D \)-deformation equivalent as marked symplectic divisors.

Proof. It follows directly from Lemma 2.2. \( \Box \)
For marked divisors, both $D$–symplectic deformation equivalence and its strict version do not involve the symplectic embeddings $I_j$. We have the following seemingly stronger definition of deformation.

**Definition 2.8.** Let $\Theta = (X, D, p_j, \omega, I_j)$ be a marked divisor. A strong $D$–symplectic homotopy (resp. strong $D$–symplectic isotopy) of $\Theta$ is a 5-tuple $(X, D, p_j, \omega_t, I_{j,t})$ such that

- the 4-tuple $(X, D, p_j, \omega_t)$ is a $D$–symplectic homotopy (resp. isotopy) of $\Theta$,
- $D$ is $\omega_t$-orthogonal, and
- $I_{j,t} : B(\epsilon_j) \to (X, \omega_t)$ are symplectic embedding sending the origin to $p_j$, $I_{j,0} = I_j|B(\epsilon_j)$ and $(I_{j,t})^{-1}(D) = \{x_1 = y_1 = 0\} \cap B(\epsilon_j)$ (resp. $(I_{j,t})^{-1}(D) = (\{x_1 = y_1 = 0\} \cup \{x_2 = y_2 = 0\}) \cap B(\epsilon_j)$ if $p_j$ is a smooth point (resp. $p_j$ is an intersection point), for some $\epsilon_j < \delta_j$.

If $\Theta^2 = (X^2, D^2, p_j^2, \omega^2, I_j^2)$ is another marked symplectic divisor and there is a symplectomorphism sending $(X^2, D^2, p_j^2, \omega^2, (I_j^2)^\#)$ to $(X, D, p_j, \omega, I_j)$, where $(I_j^2)^\#$ is the unique choice between $I_j^2$ and $(I_j^2)^{re}$ such that the existence of symplectomorphism is possible, then we say that $\Theta$ and $\Theta^2$ are strong $D$–symplectic deformation equivalent (resp. strong strict $D$–symplectic deformation equivalent).

**Lemma 2.9.** If $\Theta = (X, D, \{p_j\}_{j=1}^l, \omega, \{I_j\}_{j=1}^l)$ and $\Theta^2 = (X^2, D^2, \{p_j^2\}_{j=1}^l, \omega^2, \{I_j^2\}_{j=1}^l)$ are (strict) $D$–symplectic deformation equivalent, then they are strong (strict) $D$–symplectic deformation equivalent.

*Proof.* We will only do the case when $l = 1$. The general case is similar. We denote $p_1$ as $p$, $I_1$ as $I$ and $I_1^2$ as $I^2$.

By assumption, there is a $D$–symplectic homotopy $(X, D, p, \omega_t)$ of $\Theta$ such that there is a symplectomorphism sending $(X, D, p, \omega_1)$ to $(X^2, D^2, p_1^2, \omega^2)$. Therefore, without loss of generality, we can assume $(X, D, p, \omega_1) = (X^2, D^2, p_1^2, \omega^2)$.

The proof is easier when $p$ is a smooth point of $D$ so we only prove the case when $p$ is an intersection point of $D$. Moreover, by possibly replacing $I^2$ with $(I^2)^{re}$, we can assume the irreducible component of $D$ corresponding to $\{x_1 = y_1 = 0\}$ in chart $I$ is the same as that of $I^2$.

The idea of the proof goes as follows. First, we find a smooth family of symplectic embeddings of small ball $\Phi_t : (B(\delta), \omega_{std}) \to (X, \omega_t)$ sending the origin to $p$ such that $\Phi_0 = I|_{B(\delta)}$ and $\Phi_1 = I^2|_{B(\delta)}$. Then, we find another family of symplectic forms $\omega'_t$ such that the 4-tuple $(X, D, p, \omega'_t)$ is still a $D$–symplectic homotopy of $\Theta$ with $\omega'_1 = \omega_1$ and $D$ is $\omega'_t$-orthogonal.
for all $t$. A corresponding symplectic embeddings $I'_t$ for $(X, D, p, \omega)'$ will be constructed based on $\Phi_t$ such that the 5-tuple $(X, D, p, \omega'_t, I'_t)$ is a strong $D-$symplectic homotopy between $\Theta$ and $\Theta^2$ and this will finish the proof.

We begin our construction of $\Phi_t$. By the one-parameter family version of Moser lemma, there exist a sufficiently small $\epsilon > 0$ and a smooth family of symplectic embeddings $\Phi = \{\Phi_t\} : (B(\epsilon), \omega_{std}) \to (X, \omega_t)$ sending the origin to $p$ for all $t \in [0, 1]$. Moreover, $\Phi_0$ can be chosen to coincide with $I|_{B(\epsilon)}$. This is not yet the $\Phi_t$ we want.

Notice that $\Phi_1$ is a symplectic embedding of $(B(\epsilon), \omega_{std})$ to $(X, \omega_1)$ sending the origin to $p$ and so is $I^2|_{B(\epsilon)}$. By possibly choosing a smaller $\epsilon$, there is a symplectic isotopy of embeddings from $\Phi_1$ to $I^2|_{B(\epsilon)}$ sending the origin to $p$ for all time, by the trick in Exercise 7.22 of [18] (This is the trick to prove the space of symplectic embeddings of small balls is connected). By smoothing the concatenation of $\Phi_t$ with this symplectic isotopy, we can assume that $\Phi_1 = I^2|_{B(\epsilon)}$.

We need to further modify $\Phi_t$ by another concatenation. We consider the family of local divisors Let $F_t = \Phi_t^{-1}(D)$ in the standard coordinates in $(B(\epsilon), \omega_{std})$. Let $M_t$ be the ordered 2-tuple of the symplectic tangent spaces to the two branches of $F_t$ at the origin. Since $\Phi_0 = I|_{B(\epsilon)}$ and $\Phi_1 = I^2|_{B(\epsilon)}$, $M_t$ is a loop. Let $-M_t$ be the inverse loop of $M_t$ in the space of ordered 2-tuples of positively transversal intersecting two dimensional symplectic vector subspaces. We can find an isotopy of symplectic embeddings $\Psi_t$ from $\Phi_1$ to $\Phi_1$ in $(X, \omega_1)$ such that the corresponding ordered 2-tuple of the symplectic tangent spaces of $\Psi_t^{-1}(D)$ at the origin is $-M_t$. By concatenating $\Phi_t$ with $\Psi_t$, we can assume at the beginning that the $\Phi_t$ we chose is such that $M_t$ is null-homotopic. This is the $\Phi_t$ we want which gives a nice family of Darboux balls in $(X, \omega_t)$.

To construct $\omega'_t$, we will isotope the one parameter family of local divisors $F_t$ (fixing both ends) to another one parameter family of symplectic divisors $F_{1,t}$ such that it coincides with $F_0 = F_1$ near the origin for all $t$. First, we perform a one-parameter family of $C^1$ small perturbations to make $F_t$ coincide with a symplectic vector subspace in a sufficiently small ball $(B(\epsilon_2), \omega_{std})$, where $\epsilon_2 < \epsilon$. In other words, $F_t$ coincides with $M_t$ in $B(\epsilon_2)$. Since $M_t$ is null-homotopic, there is a homotopy $W_{r,t}$ between $M_t$ ($r = 0$) and the constant path $M_0 = M_1$ ($r = 1$) such that $W_{r,0} = W_{r,1} = M_0$ for all $r$. Hence, we can perform a one-parameter family of Lemma 5.10 of [21] (See its proof) to obtain a 3-parameter family of submanifolds $U_{r,s,t}$ in $B(\epsilon_2)$ such that $U_{r,s,t} = W_{s,t}$ outside a fixed small compact set containing the origin, $U_{r,s,t} = W_{r,t}$ close to the origin and $U_{r,r,t} = W_{r,t}$. As in the proof of
Lemma 5.10 of [21], from $U_{r,s,t}$ one can construct an $s$--parameter of symplectic isotopy $F_{s,t} \subset B(\epsilon_2)$ such that

- $F_{0,t} = F_t$,
- $F_{s,t}$ is a pair of symplectic submanifolds positively intersecting at the origin for all $s, t \in [0, 1]$,
- $F_{1,t} = F_0 = F_1 = M_0 = M_1$ inside $B(\epsilon_4)$ for all $t$,
- $F_{s,0} = F_{s,1} = F_0 = F_1$, and
- the isotopy is supported inside $B(\epsilon_2)$,

where $0 < \epsilon_4 < \epsilon_3 < \epsilon_2$.

Due to the last bullet, we obtain a $2$--parameter family of marked divisors $D_{s,t}$ with $D_{0,t} = D_t, D_{s,0} = D_{s,1} = D$, and satisfying the bullets 2 and 3 above near the marked point (recall we assume there is only one marking for simplicity).

The effect of the symplectic isotopy from $D_t$ ($s = 0$) to $D_{1,t}$ ($s = 1$) can be converted through symplectomorphism, as in Lemma 2.2, to replace $(X, D, p, \omega_t)$ ($s = 0$) by another $D$--symplectic homotopy $(X, D, p, \omega'_t)$ ($s = 1$). More precisely, for the 1-parameter family of isotopy $D_{s,t}$ parameterized by $t$, we can find a 1-parameter family of ambient isotopy $\Delta = \{\Delta_{s,t}\}_{t \in [0,1]} = \{\Delta_{s,t}\}, \Delta_{s,t} : X \to X$ extending the 1-parameter family of isotopy $D_{s,t}$ (in particular, for fixed $t_0$, $\Delta_{s,t_0}$ is an ambient isotopy extension of $D_{s,t_0}$) such that $\Delta_{0,t} = \Delta_{s,0} = \Delta_{s,1} = Id_X$. Then we define $\omega'_t = \Delta_{1,t}^* \omega_t$.

By construction, we have

- $\omega'_t = \omega_i$ for $i = 0, 1$,
- $D$ is positively $\omega'_t$-orthogonal for all $t$
- there is a family of symplectic embedding $\Phi'_t : B(\epsilon_4) \to (X, \omega_t)$ such that $\Phi'^{-1}_t(D) = F_0$ for all $t$, and
- $\Phi'_0 = I|_{B(\epsilon_4)}$ and $\Phi'_1 = I^2|_{B(\epsilon_4)}$

In particular, if we let $I'_t = \Phi'_t$, then $(X, D, p, \omega'_t, I'_t)$ is a strong $D$--symplectic homotopy between $\Theta$ and $\Theta^2$. The strict version follows similarly.$\square$

The ultimate goal for this section is the following proposition, which will be proved after discussing various operations for marked divisors in the next subsection.

**Proposition 2.10.** Let $\Theta = (X, D, p_j, \omega, I_j)$ and $\Theta^2 = (X^2, D^2, p'_j, \omega^2, I'_j)$ be two marked divisors both with $l$ marked points.

(i) Up to moving inside the $D$--symplectic deformation class, we can blow down a toric or non-toric exceptional class in $\Theta$ (and $\Theta^2$) to obtain a marked divisor $\hat{\Theta}$ (resp. $\hat{\Theta}^2$) with an extra marked point (For toric exceptional class,
original marked points on the exceptional sphere will be removed after blow-
down).

(ii) Moreover, if the blow down divisors $\hat{\Theta}$ and $\hat{\Theta}^2$ are $D-$symplectic
deformation equivalent such that the extra marked points correspond to each
other via the equivalence, then $\Theta$ and $\Theta^2$ are $D-$symplectic deformation
equivalent.

2.3. Operations on marked divisors

This subsection studies various operations on marked divisors as well as their
stability properties with respect to $D-$symplectic deformation.

- Perturbations

The following fact will be frequently used.

**Lemma 2.11.** Perturbations of a marked divisor preserve the strict $D-$
symplectic deformation class.

*Proof.* A perturbation of a marked divisor is determined by a symplectic
isotopy of the corresponding underlying unmarked divisor and isotopies of
the centers (points) on the symplectic isotopy. By Lemma 2.2, the perturbed
divisor is symplectomorphic to the original divisor, up to a $D-$symplectic
isotopy. The result follows. \(\square\)

- Marking addition

A marking addition of a marked divisor $(X, D, \{p_j\}_{j=1}^l, \omega, \{I_j\}_{j=1}^l)$ is an-
other marked divisor $(X, D, \{p_j\}_{j=1}^{l+1}, \omega, \{I_j\}_{j=1}^{l+1})$ with the additional marking
$(p_{l+1}, I_{l+1})$.

**Lemma 2.12.** Let $(X, D, \{p_j\}_{j=1}^l, \omega, \{I_j\}_{j=1}^l)$ be a marked divisor. If the
two marked divisors $(X, D, \{p_j\}_{j=1}^l \cup \{q_1\}, \omega, \{I_j\}_{j=1}^l \cup \{I_{q_1}\})$ together with
$(X, D, \{p_j\}_{j=1}^l \cup \{q_2\}, \omega, \{I_j\}_{j=0}^l \cup \{I_{q_2}\})$ are obtained by adding markings
$(q_1, I_{q_1})$ and $(q_2, I_{q_2})$ respectively, then they are strict $D-$symplectic defor-
mation equivalent if

- the centers $q_1$ and $q_2$ coincide (intersection points of $D$ allowed), or
- $q_1$ and $q_2$ are distinct smooth points of the same irreducible component.

*Proof.* If $q_1$ and $q_2$ are the same point of $D$, then the claim is trivial since
Definition 2.6 only involves the centers of marking, but not the coordinates
of markings.
If $q_1$ and $q_2$ are smooth points of the same irreducible component, say $C_1$, then we need to show that the 4-tuple $(X, D, \{p_j\}_{j=1}^l \cup \{q_2\}, \omega)$ is symplectomorphic to a $D$–symplectic isotopy of $(X, D, \{p_j\}_{j=1}^l \cup \{q_1\}, \omega)$. For this purpose, we find a symplectic isotopy of $D$ fixing $C_1$ setwise, fixing intersection points and $\{p_j\}$ pointwise and moving $q_1$ to $q_2$. Using the smooth isotopy extension theorem as in Lemma 2.2, this isotopy of symplectic divisor gives rise to a smooth isotopy $\Phi_t$ of $X$. The desired $D$–symplectic isotopy is obtained by taking the $D$–symplectic isotopy to be $(X, D, \{p_j\}_{j=1}^l \cup \{q_1\}, \Phi_t^* \omega)$ and the symplectomorphism to be $\Phi_1: (X, D, \{p_j\}_{j=1}^l \cup \{q_2\}, \omega) \rightarrow (X, D, \{p_j\}_{j=1}^l \cup \{q_1\}, \omega)$.

We note that marking addition at an intersection point of a marked divisor is not always possible because the intersection might not be $\omega$-orthogonal. However, by Lemma 2.11, marking addition at a non-marked intersection point is always possible at the cost of choosing another representative in the strict $D$–symplectic deformation class because a $C^0$ small perturbation of a symplectic divisor is sufficient to make the intersection points $\omega$-orthogonal ([5]).

- Marking moving

Sometimes, it is useful to be able to move an intersection point.

**Lemma 2.13.** Let $(X, D = C_1 \cup C_2 \cup \cdots \cup C_k, \{p_j\}_{j=1}^l, \omega, \{I_j\}_{j=1}^l)$ be a marked divisor. Let $[C_2]^2 = -1$ and $p_1 = C_1 \cap C_2$. For any smooth point $\overline{p}_1$ on $C_2$, there is a marked divisor $(\overline{X}, \overline{D} = \overline{C_1} \cup C_2 \cup \cdots \cup C_k, \{\overline{p}_1\} \cup \{p_j\}_{j=2}^l, \omega', \{\overline{I}_j\}_{j=1}^l)$ such that $\overline{p}_1 = \overline{C_1} \cap C_2$, where $\omega' = \omega$ and $C_1 = \overline{C_1}$ away from a small open neighborhood of $C_2$. Moreover, these two marked divisors are in the same $D$–symplectic deformation equivalence class.

**Proof.** By Lemma 2.11 we may assume that the intersection points of $D$ are $\omega$-orthogonal. In particular, if $C_j$ intersects $C_2$, then $C_j$ coincides with a fiber of the symplectic normal bundle of $C_2$ when identifying the symplectic normal bundle with a tubular neighborhood of $C_2$.

Choose an $\omega$-compatible almost complex structure $J$ integrable near $C_2$ which coincides with $(I_j)_* (J_{std})$ for all $j$ and making the symplectic normal bundle a holomorphic vector bundle. We blows down $C_2$ and identify the ball obtained by blowing down $C_2$ as a chart $(B(\epsilon), \omega_{std}, J_{std})$. In this chart, $C_j$ descends to the union of complex vector subspaces $V_j$ each of which corresponds to an intersection point of $C_2 \cap C_j$. On the other hand, $\overline{p}_1$ being a point on $C_2$ represents a complex vector subspace $V_{\overline{p}_1}$ in this chart. We take a
smooth family of complex vector subspaces $W_t$ from $V_1$ to $V_{P_1}$ avoiding $V_j$ for all $j \neq 1$. Applying the trick in Lemma 5.10 of [21] with $N = N' = \emptyset$, $i = 1$, $S$ being the center of $B(\epsilon)$, $S_1$ being the descended $C_1$, $W_t = W'_1$, we obtain an isotopy of symplectic manifolds $C^t$ supported in $B(\epsilon)$ from the descended $C_1$ (i.e. $C^{t=0}$) to some $C^{t=1} = \tilde{C}_1$ such that $C^t$ coincides with $W_t$ near the origin of $B(\epsilon)$ for all $t$. By blowing up $B(\epsilon_2) \subset B(\epsilon)$ for some sufficiently small $\epsilon_2$, we can lift this symplectic isotopy to a $D$–symplectic deformation from $(X, D = C_1 \cup C_2 \cup \cdots \cup C_k, \{p_j\}_{j=1}^l, \omega, \{I_j\}_{j=1}^l)$ to $(X, \overline{D} = \overline{C_1} \cup C_2 \cup \cdots \cup C_k, \{\overline{p}_1\} \cup \{p_j\}_{j=2}^l, \omega', \{\overline{I}_j\}_{j=1}^l)$ such that $\overline{p}_1 = \overline{C_1} \cap C_2$, where $\overline{C_1}$ is the proper transform of $\tilde{C}_1$. □

• Canonical blow-up

Given a marked divisor with $l$ markings, there are $l$ canonical blow-ups we can do, namely, blow-ups using the symplectic embeddings $I_j$ and hence the blow-up size is $B(\delta_j)$. A canonical blow-up of a marked divisor is still a marked divisor with one less the number of $p_j$’s.

Lemma 2.14. If $\Theta = (X, D, \{p_j\}_{j=1}^l, \omega, \{I_j\}_{j=1}^l)$ and $\Theta^2 = (X^2, D^2, \{p_j^2\}_{j=1}^l, \omega^2, \{I_j^2\}_{j=1}^l)$ are $D$–symplectic deformation equivalent, then so are the marked divisors obtained by canonical blow-ups using $I_1$ and $I_1^2$.

Proof. By Lemma 2.9, $\Theta$ and $\Theta^2$ are strong $D$–symplectic deformation equivalent. By blowing up using $I_{1,t}$, we obtain a $D$–symplectic deformation equivalence between the blown-up marked divisors. □

2.4. Proof of Proposition 2.10

Proof of Proposition 2.10. For a non-toric class $e$, we can find by Lemma 2.4, a pseudo-holomorphic representative $E$ such that $D$ is at the same time pseudo-holomorphic, after possibly applying Lemma 2.11 to deform $\Theta$ within the strict $D$–symplectic deformation class. By positivity of intersection, $E$ intersects exactly one irreducible component of $D$ and the intersections is positively transversally once and hence a non-toric exceptional curve. By perturbing $E$, we can assume $E$ has $\omega$-orthogonal intersection with $D$. We can get a marked divisor after blowing down $E$ with a marked point corresponds to the contracted $E$.

For a toric class $e$, we again apply Lemma 2.11 to deform $\Theta$ within its strict $D$–symplectic deformation class such that every intersection is $\omega$-orthogonal. The irreducible component $E$ of $D$ in the class $e$ is a toric
exceptional sphere. Hence, \( E \) intersects two other irreducible components of \( D \) once. We apply Lemma 2.13 to find another representative of \( \Theta \) in the \( D \)–symplectic deformation class such that after we blow down the exceptional curve, the intersection point corresponding to the exceptional curve is an \( \omega \)-orthogonal intersection point so this descended divisor is still a marked divisor (recall, a marking for a marked divisor at an intersection point requires the intersection point is an \( \omega \)-orthogonal intersection).

Finally, suppose the blow down divisors are \( D \)–symplectic deformation equivalent. We want to do canonical blow-ups and marking additions to recover our original divisor \( D \) and \( D^2 \). Notice that, marking additions are needed because when one blow down a divisor which originally has markings on it, the marking will not persist after the blow-down. Therefore, when we blow up the symplectic ball back, we need marking additions to get back the original marked divisor. We remark that we may not get back exactly the pair of \( D \) and \( D^2 \) by just canonical blow-ups and marking additions but we can get some pair in the same \( D \)–symplectic deformation equivalence classes by Lemma 2.11.

Since \( D \)–symplectic deformation equivalence is stable under canonical blow-ups (Lemma 2.14) and marking additions (Lemma 2.12), we conclude that \( \Theta \) is \( D \)–symplectic deformation equivalent to \( \Theta^2 \).

\[ \square \]

3. Minimal models

We first collect some facts, which should be well known to experts.

Lemma 3.1. Let \((X, D, \omega)\) be a symplectic log Calabi–Yau surface. Then \(X\) is rational or an elliptic ruled surface, and \(D\) is either a torus or a cycle of spheres. If \((X, D, \omega)\) is a symplectic Looijenga pair, then \((X, \omega)\) is rational.

Proof. Since \(D\) is symplectic and \([D] = PD(c_1(X, \omega))\), we have \(c_1(X, \omega) \cdot [\omega] = [D] \cdot [\omega] > 0\). By Theorem A of [15] or [22], \(X\) is rational or ruled.

Write \(D = C_1 \cup C_2 \cdots \cup C_k\), where each \(C_i\) is a smoothly embedded closed symplectic genus \(g_i\) surface. By adjunction, we have \([C_i] \cdot [D] = [C_i]^2 + 2 - 2g_i\). Therefore, we have

\[
[C_i] \cdot \left( \sum_{j \neq i} [C_j] \right) = 2 - 2g_i \geq 0.
\]

In particular, we have \(g_i \leq 1\) for all \(i\). Since we assumed \(D\) is connected (we always assume a symplectic divisor is connected), \(D\) is either a torus or a
cycle of spheres. Here a cycle of spheres means that the dual graph is a circle and each vertex has genus 0.

If $X$ is not rational, then $X$ admits an $S^2$–fibration structure over a Riemann surface of positive genus. After possibly smoothing, we get a torus $T$ representing the class $c_1(X)$. Moreover, $c_1(X)(f) = 2$ where $f$ is the fiber class. The projection from $T$ to the base is of non-zero degree. Therefore, the base genus of $X$ is at most 1.

If $(X, D, \omega)$ is a symplectic Looijenga pair, then at least one of the sphere component pairs positively with the fiber class (by $c_1(X)(f) = 2$ again). Hence, the base genus is 0 and $X$ is rational. □

For a cycle with $k$ spheres we will also call it a $k$–gon, and a torus a 1–gon. If we allow some $C_i$ to be positively immersed, then by adjunction we see that the only possibility is a single sphere with one positive double point, which we call a degenerated 1-gon.

The following observations are straightforward.

**Lemma 3.2.** The operations of toric blow-up, non-toric blow-up, toric blow-down and non-toric blow-down all preserve being symplectic log Calabi–Yau.

In the next subsection it is convenient to apply a slightly more general version of toric blow-down: Suppose a component $C$ of a bi-gon $D$ is an exceptional sphere. The generalized toric blow down of $D$ along $C$ is blowing down $C$, which results in a degenerated 1-gon. Notice that the homology class of a degenerated 1-gon is still Poincare dual to the first Chern class.

### 3.1. Minimal reductions

**Definition 3.3.** A symplectic log Calabi–Yau surface $(X, D, \omega)$ is called a **minimal model** if either $(X, \omega)$ is minimal, or $(X, D, \omega)$ is a symplectic Looijenga pair with $X = \mathbb{C}P^2 \# \mathbb{C}P^2$.

**Lemma 3.4.** Every symplectic log Calabi–Yau surface can be transformed to a minimal model via a sequence of non-toric blow-downs followed by a sequence of toric blow-downs.

**Proof.** **Non-toric blow-down.** Suppose $e$ is an exceptional class intersecting each component of $D$ non-negatively. Then $e$ is a non-toric exceptional class by adjunction.

By Lemma 2.4, there is an $\omega$-compatible almost complex structure $J$ such that $D$ is $J$-holomorphic (possibly after perturbation of $D$) and $e$ has
an embedded $J$-holomorphic sphere representative $E$. Thus we can perform non-toric blow-down along $E$.

By iterative non-toric blow-downs, we end up with a symplectic log Calabi–Yau surface $(X_0, D_0, \omega_0)$ such that any exceptional class pairs negatively with some component of $D$.

**Toric blow-down.** If $X_0$ is not minimal and not diffeomorphic to $\mathbb{C}P^2 \# \overline{\mathbb{C}P^2}$, then for any $\omega_0$-compatible $J_0$ making $D_0$ $J_0$-holomorphic, the exceptional class with minimal $\omega_0$-area has an embedded $J_0$-holomorphic representative, by Lemma 1.2 of [25]. Therefore, this embedded representative must coincide with an irreducible component $C$ of $D_0$.

Therefore if $D_0$ is a torus then $X_0$ must be minimal. So from now on we assume that $D_0$ is a cycle of spheres, ie. $(X_0, D_0, \omega_0)$ is a Looijenga pair.

Suppose that $C$ intersects two other components of $D_0$ and hence a toric exceptional sphere. In this case we perform toric blow down along $C$ to get another symplectic Looijenga pair $(X', D'_0, \omega'_0)$. We claim that there is no exceptional class in $X'_0$ that intersects $D'_0$ non-negatively. If there were one, by Lemma 2.4, after possibly perturbing $D'_0$ to be $\omega'_0$-orthogonal, then there would be an embedded pseudo-holomorphic representative $E'_0$ intersecting exactly one irreducible component of $D'_0$ transversally at a smooth point. This $E'_0$ can be lifted to the symplectic log Calabi–Yau surface $(X_0, D_0, \omega_0)$ because the contraction of $C$ becomes an intersection point of $D'_0$, which is away from $E'_0$. Contradiction.

Therefore, we can continue to perform toric blow-down until the ambient manifold is minimal, diffeomorphic to $\mathbb{C}P^2 \# \overline{\mathbb{C}P^2}$ or the minimal area exceptional sphere intersect only one irreducible component of the divisor.

We now consider the case that the minimal area exceptional sphere $C$ only intersects with one component of the divisor $D_0$, then $D_0$ must be a bigon. We claim that $X_0 = \mathbb{C}P^2 \# \overline{\mathbb{C}P^2}$ in this case, and hence $(X_0, D_0, \omega_0)$ is minimal, according to Definition 3.3. To see why $X_0 = \mathbb{C}P^2 \# \overline{\mathbb{C}P^2}$, we apply a generalized toric blow-down along $C$ to obtain $(X'_0, D'_0, \omega'_0)$ where $D'_0$ is a degenerated 1-gon. We next show that $(X'_0, \omega'_0)$ is minimal. After possibly perturbing the nodal point of $D'_0$ to be $\omega'_0$-orthogonal so $D'_0$ can be made a pseudo-holomorphic nodal sphere, the analysis above also shows that there is no exceptional class in $X'_0$ that intersects $\lfloor D'_0 \rfloor$ non-negatively. Since $D'_0$ represents the Poincaré dual of $c_1(X'_0, \omega'_0)$, there are also no exceptional class intersecting $\lfloor D'_0 \rfloor$ negatively. Thus, it means that $X'_0 = \mathbb{C}P^2$ or $\mathbb{S}^2 \times \mathbb{S}^2$. If $X'_0$ is $\mathbb{S}^2 \times \mathbb{S}^2$, then $D'_0$ is obtained by blowing down a component of a bi-gon $D_0$ in $X_0 = \mathbb{C}P^2 \# 2 \overline{\mathbb{C}P^2}$. In this case there are three exceptional class in $(X_0, \omega_0)$ with pairwise intersecting number 1. It is simple to check by
adjunction that any exceptional class not represented by any of the two components of $D_0$ is non-toric. But this situation would not appear due to our procedure which performs non-toric blow down first. Hence the only possibility is that $X_0' = \mathbb{C}P^2$, from which it follows that $X_0 = \mathbb{C}P^2 \# \mathbb{C}P^2$.

In summary, we can do iterative toric blow-downs from $(X_0, D_0, \omega_0)$ to obtain a symplectic Looijenga pair $(X_b, D_b, \omega_b)$ such that either $(X_b, \omega_b)$ is minimal or $X_b$ is diffeomorphic to $\mathbb{C}P^2 \# \mathbb{C}P^2$. □

From Lemma 3.1, Lemma 3.2, Lemma 3.4 and adjunction formula, we can enumerate the minimal symplectic log Calabi–Yau surfaces up to the homology of the irreducible components.

- Case (A): The base genus of $X$ is 1. $D$ is a torus.
- Case (B): $X = \mathbb{C}P^2$, $c_1 = 3H$. Then the symplectic log Calabi–Yau are
  
  (B1) $D$ is a torus,
  
  (B2) $D$ consists of a $H$–sphere and a $2H$–sphere, or
  
  (B3) $D$ consists of three $H$–spheres.

- Case (C): $X = \mathbb{S}^2 \times \mathbb{S}^2$, $c_1 = 2f + 2s$, where $f$ and $s$ are the homology classes of the two factors. By adjunction, the homology $af + bs$ of any embedded symplectic sphere satisfies $a = 1$ or $b = 1$. Symplectic log Calabi–Yau surfaces are
  
  (C1) $D$ is a torus.
  
  (C2) If $D$ has two irreducible components $C_1$ and $C_2$, then the only possible case (modulo obvious symmetry) is $[C_1] = f + bs$ and $[C_2] = f + (2 - b)s$. Its graph is given by

  \[
  \begin{array}{c}
  \bullet 2b \\
  \bullet 4-2b
  \end{array}
  \]

  (C3) If $D$ has three irreducible components $C_1$, $C_2$ and $C_3$, then the only possible case (modulo obvious symmetry) is $[C_1] = f + bs$, $[C_2] = f + (1 - b)s$ and $[C_3] = s$. Its graph is given by

  \[
  \begin{array}{c}
  \bullet 2b \\
  \bullet 2-2b \\
  \bullet 0
  \end{array}
  \]

  (C4) If $D$ has four irreducible components, then the only possible case (modulo obvious symmetry) is $[C_1] = f - bs$, $[C_2] = f + bs$, $[C_3] = s$ and
$[C_3] = s$. Its graph is given by

```
\[
\begin{array}{c}
\bullet^{2b} \\
\bullet^0 \\
\bullet^0 \\
\bullet^{-2b}
\end{array}
\]
```

It is not hard to draw contradiction if $D$ has 5 or more irreducible components.

- Case (D): $X = \mathbb{CP}^2 \# \overline{\mathbb{CP}^2}$, $c_1 = f + 2s$, where $f$ and $s$ are fiber class and section class, respectively, such that $f^2 = 0$, $f \cdot s = 1$ and $s^2 = 1$. By adjunction, the homology $af + bs$ of an embedded symplectic sphere satisfies $b = 1$ or $b = 2 - 2a$.

  (D1) $D$ cannot be a torus because it would not be minimal.

  (D2) If $D$ has two irreducible components $C_1$ and $C_2$, then the only two possible cases (modulo obvious symmetry) are $([C_1], [C_2]) = (af + s, (1 - a)f + s)$ and $([C_1], [C_2]) = (f, 2s)$. The graphs are given by

```
\[
\begin{array}{c}
\bullet^{2a+1} \\
\bullet^{-2a+1} \\
\bullet^0 \\
\bullet^{3-2a}
\end{array}
\]
```

and

```
\[
\begin{array}{c}
\bullet^4 \\
\bullet^0
\end{array}
\]
```

(D3) If $D$ has three irreducible components, then the only possible case (modulo obvious symmetry) is $[C_1] = af + s$, $[C_2] = -af + s$ and $[C_3] = f$.

```
\[
\begin{array}{c}
\bullet^{2a+1} \\
\bullet^{-2a+1} \\
\bullet^0
\end{array}
\]
```

(D4) If $D$ has four irreducible components, then the only possible case (modulo obvious symmetry) is $[C_1] = af + s$, $[C_2] = -(a + 1)f + s$, $[C_3] = f$ and $[C_4] = f$.

```
\[
\begin{array}{c}
\bullet^{2a_1+1} \\
\bullet^0 \\
\bullet^0 \\
\bullet^{-2a_1-1}
\end{array}
\]
```

It is not hard to draw contradiction if $D$ has 5 or more irreducible components.


3.2. Deformation classes of minimal models

In this section, we study the symplectic deformation classes of minimal symplectic log Calabi–Yau surfaces.

Proposition 3.5. Let \((X, D = C_1 \cup \cdots \cup C_k, \omega)\) be a minimal symplectic log Calabi–Yau surface. If \(\overline{D} = C_1 \cup \cdots \cup C_k \subset (X, \omega)\) is another symplectic divisor representing the first Chern class such that \([C_i] = [\overline{C}_i]\) for all \(i\). Then \((X, D, \omega)\) is symplectic deformation equivalent to \((X, \overline{D}, \omega)\).

The proof of Proposition 3.5 is separated into two cases, Proposition 3.6 and Proposition 3.9.

3.2.1. Isotopy in rational surfaces.

Proposition 3.6. Suppose \((X, D, \omega)\) and \((X, \overline{D}, \omega)\) satisfy the assumptions of Proposition 3.5 such that, in addition, \(X\) is rational, then \(D\) is symplectic isotopic to \(\overline{D}\).

The proof of Proposition 3.6 when \(D\) is a torus is given by [28] and Theorem B and Theorem C of [27]. We only need to deal with symplectic Looijenga pairs.

Recall that cohomologous symplectic forms on a rational or ruled 4-manifold are symplectomorphic (cf. [29], [10] and the survey [26]). Therefore it suffices to consider the following ‘standard symplectic models’ for \(S^2 \times S^2\), \(\mathbb{C}P^2\) and \(\mathbb{C}P^2 \# \overline{\mathbb{C}P^2}\).

- \(S^2 \times S^2\) model:
  
  When \(X\) is diffeomorphic to \(S^2 \times S^2\), we define the product symplectic form \(\omega_\lambda = (1 + \lambda)\sigma \times \sigma\) with \(\sigma\) a symplectic form on the second factor with area 1 and \(\lambda \geq 0\). Let \(E_0\) be the class of the first factor, \(F\) be the class of the second factor and \(E_{2k} = E_0 - kF\) for \(0 \leq k \leq l\), where \(l\) is the integer with \(l - 1 < \lambda \leq l\). For \(0 \leq k \leq l\), let \(U_k\) be the set of \(\omega_\lambda\)-compatible almost complex structure such that \(E_{2k}\) is represented by an embedded pseudo-holomorphic sphere.

- \(\mathbb{C}P^2\) model:
  
  When \(X\) is diffeomorphic to \(\mathbb{C}P^2\), we use a multiple of the Fubini–Study form, \(c\omega_{FS}\).

- \(\mathbb{C}P^2 \# \overline{\mathbb{C}P^2}\) model:
  
  When \(X\) is diffeomorphic to \(\mathbb{C}P^2 \# \overline{\mathbb{C}P^2}\), we use \(\omega_\lambda\) to denote a form obtained by blowing up \((\mathbb{C}P^2, (2 + \lambda)\omega_{FS})\) with size \(1 + \lambda\). So the line class \(H\) has area \(2 + \lambda\) and the exceptional class \(E_1\) has area \(1 + \lambda\), where \(\lambda > 0\).
Proof. By Proposition 3.7, we can find a symplectic isotopy 
$-C$ ded symplectic spheres

Lemma 3.8.

Let (X, $\omega_\lambda$) be as in Proposition 3.7. Assume $C_0, C_1 \subset X$ are two embedded symplectic spheres representing the same class $E_j$ for some $0 \leq j \leq 2l + 1$. Then there is a Hamiltonian diffeomorphism of (X, $\omega_\lambda$) sending $C_0$ to $C_1$.

Proof. By Proposition 3.7, we can find a symplectic isotopy $C_t \subset X$ from $C_0$ to $C_1$. We can extend this symplectic isotopy from a neighborhood of $C_0$ to a neighborhood of $C_1$ by a Moser type argument (See e.g. Chapter 3 of [18]). Our aim is to extend this symplectic isotopy to an ambient symplectic isotopy in order to obtain the result.

We first extend this symplectic isotopy to an ambient diffeomorphic isotopy $\Phi: X \times [0, 1] \rightarrow X$. By considering the pull-back form $\Phi^*\omega_\lambda$, we can identify $C_0 = \Phi_t^{-1}(C_t)$ for all $t$ in the family of symplectic manifold $(X \times \{t\}, \Phi^*\omega_\lambda|_{X \times \{t\}})$, as in Lemma 2.2. We denote $\Phi^*\omega_\lambda|_{X \times \{t\}}$ as $\omega_\lambda^t$. By definition, $\omega_\lambda^t$ is fixed near $C_0$ for all $t$. Identify a tubular neighborhood of $C_0$ with a symplectic normal bundle. Then, choose a smooth family of $\omega_\lambda^t$-compatible almost complex structure $J_t$ on $X$ such that $J_t$ is fixed near $C_0$ and the fibers of the normal bundle of $C_0$ are $J_t$-holomorphic. Pick a point $p_0$ on $C_0$. Let the $J_t$ holomorphic sphere representing the fiber class $F$ and passing through $p_0$ be $C_t^F$. Since the fiber class with a single point constraint has Gromov–Witten invariant one or minus one, $C_t^F$ forms a symplectic isotopy by Gromov compactness. By Lemma 3.2.1 of [20] (let $C_0$ be $C^{S_1}$ and $[C_t^F]$ be $B_1$), we can assume that the intersection between $C_0$ and $C_t^F$ is $\omega_\lambda^t$-orthogonal, after possibly perturbing $J_t$.

Now, $\Phi(C_0, t) \cup \Phi(C_t^F, t) = C_t \cup \Phi(C_t^F, t)$ is an $\omega_\lambda$ orthogonal symplectic isotopy in $(X, \omega_\lambda)$ (Strictly speaking, $C_t^F$ is the image of another diffeomorphic isotopy $\Psi$ such that $C_t^F = \Psi(C_0^F, t)$ and $C_0 = \Psi(C_0, t)$, then the isotopy we want is $\Phi(\Psi(, t), t))$. We can extend this symplectic isotopy to a neighborhood of it by another Moser type argument since $\Phi(C_0, t)$ intersects $\Phi(C_t^F, t)$
\( \omega \)-orthogonally. We have the exact sequence

\[
H^1(C_0 \cup C_0^F, \mathbb{R}) = 0 \rightarrow H^2(X, C_0 \cup C_0^F, \mathbb{R}) \rightarrow H^2(X, \mathbb{R}) \rightarrow H^2(C_0 \cup C_0^F, \mathbb{R})
\]

where the last arrow is an isomorphism and hence \( H^2(X, C_0 \cup C_0^F, \mathbb{R}) = 0 \).

By Banyaga extension theorem (See e.g. [18]), there is an ambient symplectic isotopy extending the symplectic isotopy \( C_t \cup \Phi(C_0^F, t) \). Finally, this ambient symplectic isotopy is a Hamiltonian isotopy because \( H^1(X) = 0 \).

**Proof of Proposition 3.6.** As seen in the previous section, \( D \) and \( \overline{D} \) have at most four irreducible components. We are going to prove Proposition 3.6 by dividing it into the cases of two, three or four irreducible components. The proof for bigons is written with details, while the proof for triangles or rectangles being similar to that of bigons will be sketched.

- **Bigons**

  First, let \( (X, \omega) = (\mathbb{S}^2 \times \mathbb{S}^2, c \omega \lambda) \) for some constant \( c \), \( D = C_1 \cup C_2, \overline{D} = \overline{C_1} \cup \overline{C_2} \) and \( [C_i] = [\overline{C}_i] \) for \( i = 1, 2 \). Without loss of generality, we may assume \( [C_1]^2 \leq [C_2]^2 \). From the enumeration, we have \( [C_1] = F + (2 - b_1)E_0 \) and \( [C_2] = F + b_1E_0 \) for some \( b_1 \geq 1 \), or \( [C_1] = (2 - a_1)F + E_0 \) and \( [C_2] = a_1F + E_0 \) for some \( a_1 \geq 1 \). We consider the latter case and the first case can be treated similarly.

We first consider \( a_1 \geq 2 \). By Lemma 3.8, after composing a Hamiltonian diffeomorphism, we can assume \( C_1 \) and \( \overline{C}_1 \) completely coincide. Fix an \( \omega \)-tamed almost complex structure \( J_0 \) making \( C_1 = \overline{C}_1 \) pseudo-holomorphic and integrable near \( C_1 \). Consider the set of \( \omega \)-tamed almost complex structure \( J \) agree with \( J_0 \) near \( C_1 \). Fix \( J \in J \), we want to inspect all possible degenerations of \( J \)-holomorphic nodal curve representing \( [C_2] \). By positivity of intersection, positivity of area and adjunction, the homology class \( aF + bE_0 \) of any \( J \)-holomorphic curve has non-negative coefficient for the \( E_0 \) factor (i.e. \( b \geq 0 \)). Therefore, the irreducible components (possibly not simple) of any \( J \)-holomorphic curve representing \( [C_2] \) give rise to a decomposition \( [C_2] = (s_1F + E_0) + s_2F + \cdots + s_mF \), where \( s_j > 0 \) for \( 2 \leq j \leq m \) (by positivity of intersection with \( [C_1] \)). If \( s_1 \leq 0 \), then \( s_1F + E_0 = [C_1] \) by positivity of intersection with \( [C_1] \). The sum of non-negative Fredholm index of the underlying curve of each individual component is given by \( \text{Ind}_{\text{nodal}} = (4s_1 + 2) + 2(m - 1) \) when \( s_1 \geq 0 \), and \( \text{Ind}_{\text{nodal}} = 2(m - 1) \) when \( s_1 < 0 \) because the class \( s_1F + E_0 \) is primitive and the underlying curve for \( s_jF \) has homology \( F \) (the index formula for a pseudo-holomorphic curve with class \( A \) is \( 2c_1(A) - 2 \)). On the other hand, the index of the class \( [C_2] \) is given by \( \text{Ind}_{C_2} = 2(2a_1 + 2) - 2 = 4(\sum_{i=1}^m s_i) + 2 = (4s_1 + 2) + 4(\sum_{i=2}^m s_i) \).
If $s_1 \geq 0$ and $m \geq 2$, we have

$$Ind_{\text{nodal}} + 2 \leq (4s_1 + 2) + 4 \left( \sum_{i=2}^{m} s_i \right) = Ind_{C_2}$$

If $s_1 < 0$, we have $s_1 = 2 - a_1$ and hence

$$Ind_{\text{nodal}} + 2 = 2(m - 1) + 2 \leq 2 \left( \sum_{i=2}^{m} s_i \right) + 2$$

$$= 2(a_1 - (2 - a_1)) + 2 = 4a_1 - 2 < Ind_{C_2}$$

Therefore, any degeneration happens in codimension two or higher.

Then we can apply the standard pseudo-holomorphic curve argument to obtain a symplectic isotopy from $C_2$ to $\overline{C_2}$ transversal to $C_1$ for all time along the isotopy and finish the proof. Since we could not find a reference that fits exactly to our situation (Proposition 1.2.9(ii) of [20] is a very closely related one), we provide some details here. We will basically follow [19] together with Lemma 3.2.2 and Proposition 3.2.3 of [20].

We perturb $C_2$ and $\overline{C_2}$ so that they have $2a_1 + 1$ distinct intersection points and call these intersection points $\{p_j\}_{j=1}^{2a_1+1}$. We form the universal moduli space for genus 0 curve representing the class $[C_2]$ with $2a_1 + 1$ point constraints $\{p_j\}_{j=1}^{2a_1+1}$ with respect to the space of almost complex structures $J$. We want to pick $J, \overline{J} \in J$ that are regular for all underlying (marked) simple curves appearing in a degeneration of $[C_2]$ except $C_1 = \overline{C_1}$ such that $C_2$ is $J$-holomorphic and $\overline{C_2}$ is $\overline{J}$-holomorphic.

To find $J$ and $\overline{J}$, we note the following two facts. For any $J \in J$ (resp. $\overline{J} \in \overline{J}$) making $C_2$ $J$-holomorphic (resp. making $\overline{C_2}$ $\overline{J}$-holomorphic), the Fredholm operator taking the point constraints $\{p_j\}_{j=1}^{2a_1+1}$ into account is regular by automatic transversality (See Theorem 3.1 and Proposition 3.2 of [13], and also [8], [9]). On the other hand, for a generic choice of $J$ (resp. $\overline{J}$) making $C_1$ and $C_2$ $J$-holomorphic (resp. $C_1 = \overline{C_1}$ and $\overline{C_2}$ $\overline{J}$-holomorphic), each simple curve other than $C_1$ and $C_2$ (resp. other than $C_1$ and $\overline{C_2}$) in any degeneration has a somewhere injective point away from $C_1$ and $C_2$ (resp. away from $C_1$ and $\overline{C_2}$) and hence is regular (See Chapter 3.4 of [19]). As a result, we can find $J, \overline{J} \in J$ as desired.

For such $J, \overline{J}$, there is a regular smooth path $J_t \in J$ (regular in the sense of Definition 6.2.10 of [19]) such that the parametrized moduli space of $J_t$–holomorphic curves representing $[C_2]$ and passing through $\{p_j\}_{j=1}^{2a_1+1}$ forms a non-empty one dimensional smooth manifold. Since degeneration happens in codimension 2 or higher, if we choose $J_t$ to be also regular with
respect to the lower dimensional strata, the one dimensional moduli space is also compact.

Thus, there is a family of embedded $J_t$-holomorphic spheres $C^t$ all of which passing through $\{p_j\}_{j=1}^{2a_1+1}$. By positivity of intersection, $C^t$ is the only $J_t$-holomorphic family passing through $\{p_j\}_{j=1}^{2a_1+1}$, hence we have a symplectic isotopy from $C_2$ to $\overline{C}_2$. Finally, by applying Lemma 3.2.1 of [20] to $\{C^t\}$ to get another symplectic isotopy $\{C^t\}$ transversal to $C_1$, we get that the intersection pattern of $\{C^t\} \cup C_1$ is unchanged along the symplectic isotopy. This finishes the proof when $a_1 \geq 2$.

The case that $a_1 = 1$ can be treated similarly, which is easier and only requires an analogue of Proposition 3.7 and Lemma 3.8 for symplectic sphere with non-negative self-intersection (See e.g Proposition 3.2 of [13]).

Now, we consider $(X, \omega) = (\mathbb{C}P^2\#\overline{\mathbb{C}P^2}, c\omega_\lambda)$ for some constant $c$, $D = C_1 \cup C_2$, $\overline{D} = \overline{C}_1 \cup \overline{C}_2$ and $[C_i] = [\overline{C}_i]$ for $i = 1, 2$. By the enumeration, there are two possible cases.

The first one is when $[C_1] = [\overline{C}_1] = (1 - a_1)f + s = (2 - a_1)F + E_1$ and $[C_2] = [\overline{C}_2] = a_1f + s = (a_1 + 1)F + E_1$. By symmetry, it suffices to consider $a_1 \geq 1$. If $a_1 \geq 2$, we apply Lemma 3.8 and assume $C_1$ completely coincides with $\overline{C}_1$. Again, we inspect all possible $J$-holomorphic degenerations of $C_2$ for $J$ making $C_1$ $J$-holomorphic. A direct index count as before shows that any degeneration of $C_2$ has at least codimension two. Therefore, the same method applies. The case that $a_1 = 1$ is dealt similarly.

The other case is $[C_1] = [\overline{C}_1] = f = F$ and $[C_2] = [\overline{C}_2] = 2s = 2F + 2E_1$. This cannot cause additional trouble as they have non-negative self-intersection numbers. One can deal with this similar to the previous cases.

The case that $X = \mathbb{C}P^2$ is analogous and easier.

- Triangles and Rectangles

Now, we consider $X = S^2 \times S^2$ or $X = \mathbb{C}P^2\#\overline{\mathbb{C}P^2}$ and assume $D, \overline{D}$ has three or four irreducible components. We observe that, there is at most one component with negative self-intersection number and one with positive self-intersection numbers in all cases. Moreover, the homology class of the component with negative self-intersection number is of the form $E_i + jF$ for some $j$ and $i = 0, -1$. If there is a negative self-intersection component, we can apply Lemma 3.8 and assume the negative self-intersection components for $D$ and $\overline{D}$ completely coincide. Then we study all the possible $J$-holomorphic degeneration of the positive curve for $J$ making the negative component $J$-holomorphic. One can show that the degeneration happens in at least codimension two by index count. Therefore, we can find a relative pseudo-holomorphic isotopy $\Phi_t$ from the positive self-intersection component of $D$.
to the positive self-intersection component of $\overline{D}$. At the same time, since the remaining components of $D$ and $\overline{D}$ are sphere fibers, which cannot have any pseudo-holomorphic degeneration, the pseudo-holomorphic isotopy $\Phi_t$ can be extended to a pseudo-holomorphic isotopy from $D$ to $\overline{D}$. Hence, the result follows when there is a negative self-intersection component. The remaining cases are all similar and simpler, including the case when $X = \mathbb{C}P^2$. □

3.2.2. Elliptic ruled surfaces. In this subsection, we want to finish the proof of Proposition 3.5 for the torus type.

**Proposition 3.9.** Suppose $(X, D, \omega)$ and $(X, \overline{D}, \omega)$ are minimal symplectic log Calabi–Yau surfaces such that $X$ is elliptic ruled. Then they are symplectic deformation equivalent to each other.

We first describe the complement of $D$ following [30]. Any $\omega$-compatible almost complex structure $J$ provides us a $J$-holomorphic ruling, meaning that there is a sphere bundle map $\pi : X \to \mathbb{T}^2$ such that fibers are $J$-holomorphic. Usher proves in [30] (Lemma 3.5) that, if $D$ is $J$-holomorphic, $\pi|_D$ is a two to one covering and in particular $D$ is transversal to the $J$-holomorphic sphere foliation. If a tubular neighborhood of $D$ is taken out, we have a $J$-holomorphic annulus foliation, which defines an annulus bundle $X - P(D)$ over the torus $\mathbb{T}^2$. We want to identify this annulus bundle.

Equip the orientation of $\mathbb{T}^2$ such that $\pi|_D$ is orientation preserving, where the orientation of $D$ is determined by $J$. Choose a positively oriented basis $\{t, u\} \in H_1(D, \mathbb{Z})$ and $\{v, w\} \in H_1(\mathbb{T}^2, \mathbb{Z})$ such that $\pi_*t = v$ and $\pi_*u = 2w$. Let $A = \{z \in \mathbb{C} | \frac{1}{2} \leq |z| \leq 2\}$. The monodromy of this annulus bundle around the loop corresponding to $v$ is orientation preserving and does not flip the boundary. Therefore, the monodromy is isotopic to the identity. Similarly, the monodromy of this annulus bundle around the loop corresponding to $w$ is orientation preserving but flip the boundary components due to $\pi_*u = 2w$. Therefore, the monodromy is isotopic to the map sending $z$ to $z^{-1}$. This annulus bundle is isomorphic as an annulus bundle to (See the paragraph before Lemma 3.6 of [30])

$$\mathbb{S}^1 \times \mathbb{R} \times A \frac{(x + 1, z)}{(x + 1, z^{-1})} \sim (x, z^{-1})$$

if $X$ is the smoothly trivial sphere bundle, and isomorphic to

$$\mathbb{R} \times \mathbb{S}^1 \times A \frac{(x + 1, e^{i\theta}, z)}{(x + 1, e^{i\theta}, e^{i\theta} z^{-1})} \sim (x, e^{i\theta} z^{-1})$$

if $X$ is the smoothly non-trivial sphere bundle.
Let $\mathcal{D}$ be another connected symplectic torus representing $c_1(X)$. For $\mathcal{D}$, we can also define $J, \pi, \overline{\mathbb{T}^2}, \overline{t}, \overline{u}, \overline{v}, \overline{w}$ as above. Let $\tau: \mathbb{T}^2 \to \overline{\mathbb{T}^2}$ be a diffeomorphism sending $v$ and $w$ to $\overline{v}$ and $\overline{w}$, respectively. By construction, the pull-back annulus bundle $\tau^*(\overline{X} - P(\overline{\mathcal{D}})) \to \mathbb{T}^2$ has the same monodromy (up to isotopy) as $X - P(D) \to \mathbb{T}^2$ over the one-skeleton. The existence of an annulus bundle isomorphism from $X - P(D)$ to $\tau^*(\overline{X} - \overline{\mathcal{D}})$ covering the identity of $\mathbb{T}^2$ reduces to whether $X - P(D)$ and $\tau^*(\overline{X} - \overline{\mathcal{D}})$ are isomorphic annulus bundle (covering some diffeomorphism of the base), which is true because there is only one class of isomorphic annulus bundle for a choice of monodromies over one skeleton (and it is explicitly described above in our case). Therefore, we have a bundle isomorphism $F: X - P(D) \to X - P(\overline{\mathcal{D}})$ covering $\tau$. On the other hand, since the image of $\tau_* \circ \pi_*|_{H^1(D, \mathbb{Z})}$ equals the image of $\overline{\pi_*}|_{H^1(D, \mathbb{Z})}$, there are two lifts of $\tau$ to $\tilde{\tau}_i: \mathcal{D} \to \overline{\mathcal{D}}$ such that $\overline{\pi} \circ \tilde{\tau}_i = \tau \circ \pi$, for $i = 1, 2$. Then, there is a unique way, up to isotopy, to get a sphere bundle isomorphism $\tilde{F}: X \to X$ extending $F$ and $\tilde{\tau}_1$ (or, $F$ and $\tilde{\tau}_2$) by following the pseudo-holomorphic foliation. In particular, we have $\tilde{F}(D) = \overline{\mathcal{D}}$.

Using $\tilde{F}$, we can identify $\overline{\mathcal{D}} \subset (X, \omega)$ with $D \subset (X, \tilde{F}^*\omega)$. Proposition 3.9 will follow if we can find a symplectic deformation equivalence from $(X, D, \omega)$ to $(X, D, \tilde{F}^*\omega)$, which can be obtained by the following lemma.

Lemma 3.10. Let $\pi: (X, \omega_i, J_i) \to B$ be a symplectic surface bundle over surface such that $J_i$ is $\omega_i$-compatible and fibers are $J_i$ holomorphic for both $i = 0, 1$. Moreover, we assume the orientation of fibers induced by $J_0$ and $J_1$ are the same and the orientation of the total space induced by $\omega_0^2$ and $\omega_1^2$ are the same. Assume $D \subset (X, \omega_i)$ is a $J_i$ holomorphic surface for $i = 0, 1$. and $\pi|_D$ is submersive. Then there is a smooth family of (possibly non-homologous) symplectic forms $\omega_t$ on $X$ making $D$ symplectic for all $t \in [0, 1]$ joining $\omega_0$ and $\omega_1$.

Proof. Fix a point $p \in X$ and consider a non-zero tangent vector $v \in T_pX$ which does not lie in the vertical tangent sub-bundle $T_pX^{vert}$. Since fibers are $J_i$ holomorphic, we have $Span\{v, J_i v\} \cap T_pX^{vert} = \{0\}$. Choose a volume form (symplectic form) $\omega_B$ on $B$. Since $\pi$ is a submersion, $\pi_*Span\{v, J_i v\} = T_{\pi(p)}B$. Therefore, we have $\omega_B(\pi_*(v), \pi_*(J_i v)) \neq 0$. By possibly changing the sign of $\omega_B$, we can assume $\omega_B(\pi_*(v), \pi_*(J_i v)) > 0$. Moreover, this inequality is true for any $v \in T_pX$ not lying in $T_pX^{vert}$. By continuity, $\omega_B(\pi_*(v), \pi_*(J_i v)) > 0$ for any $p \in X$ and any $v \in T_pX - T_pX^{vert}$ for both $i = 0, 1$. 


Now, we apply the Thurston trick. For any $K \geq 0$, we let $\omega^K_i = \omega_i + K\pi^*\omega_B$, which is clearly closed. It is also non-degenerate because it is non-degenerate for the vertical tangent sub-bundle and for any $p \in X$, and any $v \in T_pX - T_pX^{vert}$, we have $\omega^K_i(v, J_i v) = \omega_i(v, J_i v) + K\omega_B(\pi_*v, \pi_*(J_i v)) > 0$. The first term being greater than zero is by compatibility and the second term being non-negative is due to $K \geq 0$ and the first paragraph. Notice that $D$ is symplectic with respect to $\omega^K_i$ for both $i = 0, 1$ because $\pi|_D$ is submersive and $D$ is $J_1$-holomorphic.

Now, we consider $\omega^K_i = (1 - t)\omega^K_0 + t\omega^K_1$, which is clearly closed and non-degenerate for $TX^{vert}$. For $v \in T_pX - T_pX^{vert}$, we have $\omega^K_i(v, J_0 v) = (1 - t)\omega_0(v, J_0 v) + t\omega_1(v, J_0 v) + K\omega_B(\pi_*v, \pi_*J_0 v)$. We know that the first and the third terms on the right hand side are non-negative but we have no control on the second term. However, there is a sufficiently large $K$ such that $\omega^K_i(v, J_0 v) > 0$ for all $p \in X$ and $v \in T_pX - T_pX^{vert}$ and for all $t$ because the sphere subbundle of $TX$ is compact. By smoothening out the piecewise smooth family from $\omega_0$ to $\omega^K_0$, $\omega^K_i$ and from $\omega^K_1$ to $\omega_1$, we finish the proof.

We remark that Lemma 3.10 can be viewed as a relative version of Proposition 4.4 in [17] in dimension four.

### 3.3. Proof of Theorem 1.4

We are ready to prove Theorem 1.4.

**Proof of Theorem 1.4.** Let $(X^i, D^i, \omega^i)$ be symplectic log Calabi–Yau surfaces for $i = 1, 2$, which are homological equivalent via a diffeomorphism $\Phi$.

Let $\{e_1, \ldots, e_\beta\}$ be a maximal set of pairwisely orthogonal non-toric exceptional classes in $X$. We can choose an almost complex structure $J^1$ (possibly after deforming $D^1$) such that $D^1$ is $J^1$-holomorphic and all $e_j$ has embedded $J^1$-holomorphic representative, by Lemma 2.4. Since $(X^1, D^1, \omega^1)$ and $(X^2, D^2, \omega^2)$ are homological equivalent via $\Phi$, $\{\Phi_*(e_j)\}$ is a maximal set of pairwisely orthogonal non-toric exceptional classes. We can find an $\omega^2$-tamed almost complex structure (possibly after deforming $D^2$) $J^2$ such that $D^2$ is $J^2$-holomorphic and the $\Phi_*(e_j)$ has embedded $J^2$-holomorphic representative. After blowing down the $J^2$-holomorphic representatives of $e_j$, and $\Phi_* (e_j)$ for all $1 \leq j \leq \beta$, we obtain two symplectic log CY surfaces $(\overline{X^1}, \overline{D^1}, \overline{\omega}^1)$ and $(\overline{X^2}, \overline{D^2}, \overline{\omega}^2)$.

Clearly, $(\overline{X^1}, \overline{D^1}, \overline{\omega}^1)$ and $(\overline{X^2}, \overline{D^2}, \overline{\omega}^2)$ are homological equivalent for some natural choice of diffeomorphism $\overline{\Phi}$. Now, a component in $\overline{D^1}$ is exceptional if and only if the corresponding component in $\overline{D^2}$ is exceptional.
By Lemma 3.4, we pass to minimal models $(\overline{X}_b^1, \overline{D}_b^1, \overline{\omega}_b^1)$ by toric blow-downs. By identifying $\overline{X}_b^1$ and $\overline{X}_b^2$ with a natural choice of diffeomorphism $\Phi_b$, the homology classes of the components of $\overline{D}_b^1$ and $\overline{D}_b^2$ are the same.

By Proposition 1.2.15 of [20] or Theorem 2.9 of [3], up to a D-symplectic homotopy (ie. a deformation of $\Phi_b$ keeping $\overline{D}_b^2$ symplectic), we can assume $[\overline{\omega}_b^1] = \Phi_b^* [\overline{\omega}_b^2]$. Therefore, $\overline{X}_b^1$ and $\overline{X}_b^2$ are actually symplectomorphic ([29], [10]) and we thus can choose $\Phi_b$ to be a symplectomorphism from $(\overline{X}_b^1, \Phi_b^{-1}(\overline{D}_b^2), \overline{\omega}_b^1)$ to $(\overline{X}_b^2, \overline{D}_b^2, \overline{\omega}_b^2)$. Therefore, we conclude that $(\overline{X}_b^1, \overline{D}_b^1, \overline{\omega}_b^1)$ and $(\overline{X}_b^2, \overline{D}_b^2, \overline{\omega}_b^2)$ are symplectic deformation equivalent, by applying Proposition 3.5 to $(\overline{X}_b^1, \overline{D}_b^1, \overline{\omega}_b^1)$ and $(\overline{X}_b^1, \Phi_b^{-1}(\overline{D}_b^2), \overline{\omega}_b^2)$. Further, by Lemma 2.7, they are $D-$symplectic deformation equivalent.

Now we record the sequence of non-toric and toric blow-downs by markings $\overline{D}_b^1$ and $\overline{D}_b^2$. As marked divisors, they are $D-$symplectic deformation equivalent by Lemma 2.12. Finally, by Proposition 2.10 (and viewing un-marked divisors as marked divisors without markings), $(X^1, D^1, \omega^1)$ is $D-$symplectic deformation equivalent to $(X^2, D^2, \omega^2)$, and hence symplectic deformation equivalent to $(X^2, D^2, \omega^2)$ by Lemma 2.7. Tracing the steps, we see that the symplectomorphism in the symplectic deformation equivalence between $(X^1, D^1, \omega^1)$ and $(X^2, D^2, \omega^2)$ has the same homological effect as $\Phi$.

Now, assume $(X^1, D^1, \omega^1)$ is strictly homological equivalent to $(X^2, D^2, \omega^2)$ via a diffeomorphism $\Phi$. It means that $\Phi$ is a homological equivalence and $\Phi^*[\omega^2] = [\omega^1]$. We first note that, up to symplectic isotopy of $D^1$ and $D^2$, which preserves the strict $D$-symplectic deformation class (Lemma 2.11), we can assume $D^i$ are $\omega^i$-orthogonal. We have shown that there is a $D-$symplectic homotopy $(X^1, D^1, \omega^1)$ of $(X^1, D^1, \omega^1)$ and a symplectomorphism $\Psi : (X^1, D^1, \omega^1) \to (X^2, D^2, \omega^2)$ with the same homological effect as $\Phi$. Therefore, we have $[\omega^1] = \Phi^*[\omega^2] = \Psi^*[\omega^2] = [\omega^1]$. By Theorem 1.2.12 of [20], $\omega^1_t$ can be chosen such that $[\omega^1_t]$ is constant for all $t$. By Corollary 1.2.13 of [20], there is a symplectic isotopy $(X^1, D^1_t, \omega^1)$ such that $D^1_b = D^1_t$ and $(X^1, D^1_t, \omega^1)$ is symplectomorphic to $(X^1, D^1_t, \omega^1)$ and hence to $(X^2, D^2, \omega^2)$. Therefore, the result follows.

\[\square\]

In the case $X^1 = X^2 = X$, Theorem 1.4 implies the symplectic deformation class of $(X, D, \omega)$ is uniquely determined by the homology classes $\{[C_j]\}_{j=1}^k$ modulo the action of diffeomorphism on $H_2(X, \mathbb{Z})$. The fact the homology classes of $D$ completely determine the symplectic deformation equivalent class can be regarded as in the same spirit of Torelli type theorems in a weak sense.
If \((X^1, \omega^1) = (X^2, \omega^2) = (X, \omega)\) and \([C^1_j] = [C^2_j]\) for all \(j\), we can take the strict homological equivalence to be identity and hence the symplectomorphism from \((X, D^1, \omega)\) to the time-one end of the symplectic isotopy of \((X, D^2, \omega)\) in Theorem 1.4 has trivial homological action. Therefore, the number of symplectic isotopy classes of homological equivalent log Calabi–Yau surfaces in \((X, \omega)\) is bounded above by the number of connected components of Torelli part of the symplectomorphism group of \((X, \omega)\).

References


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