

Exact Solutions of Diffusion-Convection Equations

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ABSTRACT. In the presented paper known (up to the beginning of 2008) Lie- and non-Lie exact solutions of different (1+1)-dimensional diffusion-convection equations of form $f(x)u_t = (g(x)A(u)u_x)_x + h(x)B(u)u_x$ are collected.

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1. Introduction

This is a review paper, where we present a brief summary of known exact solutions of variable coefficient (1 + 1)-dimensional diffusion-convection equations

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of form

$$(1) \quad f(x)u_t = (g(x)A(u)u_x)_x + h(x)B(u)u_x,$$

where $f = f(x)$, $g = g(x)$, $h = h(x)$, $A = A(u)$ and $B = B(u)$ are arbitrary smooth functions of their variables, $f(x)g(x)A(u) \neq 0$.

Our aim is not to give a physical interpretation of the solution of diffusion equations (that is too huge and cannot be reached in the scope of a short paper), but to list the already known exact solutions of equations from the class under consideration. However, in some cases we give a short discussion of the nature of the listed solutions.

The majority of the listed solutions have been obtained by means of different symmetry methods, such as reduction with respect to Lie and non-Lie symmetries, separation of variables, equivalence transformations, etc.

Let us note that the constant coefficient diffusion equations ($f = g = 1$, $B = 0$) are well investigated and some of exact solutions given below were summarized before in [26, 48].

Our paper is organized as follows. First of all we adduce solutions of the linear heat equation obtained by means of various symmetry methods. In Section 3 the linearizable Burgers, Fujita–Storm and Fokas–Yortsos equations are considered. Lie reduction of constant coefficient nonlinear diffusion equation ($hB = 0$, $f = g = 1$) is performed in Section 4. Solutions of constant coefficient diffusion equations with exponential nonlinearity are adduced in Section 5. Solutions of constant coefficient diffusion equations with power nonlinearity are presented in Section 6. The important particular case of such equations, namely, the fast diffusion equation, is studied in more detail in Section 8. Diffusion equations with other nonlinearities are briefly discussed in Section 9. The next considered case (Section 10) covers the nonlinear constant coefficient diffusion–convection equations ($f = g = h = 1$). In Section 11 we adduce a brief analysis of known solutions of n -dimensional radially symmetric nonlinear diffusion equations. In Section 12 exact solutions of some variable coefficient diffusion–convection equations are collected. At last, in Sections 13 and 14 we present a detailed analysis of interesting variable coefficient equations having distinguished invariance properties.

In the Appendix A we adduce the complete results of group classification of equations (1) with respect to the extended group \hat{G}^\sim of equivalence transformations (23).

Below, if it is not indicated separately, α , ε_i , λ , a , b , c , c_i are arbitrary constants, $\varepsilon = \pm 1$. For convenience we use double numeration T.N of classification cases and local equivalence transformations, where T denotes the number of table and N does the number of case (or transformation, or solution) in table T. The notion “equation T.N” is used for the equation of form (1) where the parameter-functions f , g , h , A , B take values from the corresponding case.

2. Linear heat equation

Systematical investigation of invariant solutions of different diffusion equations was started by the case of linear heat equation [32, 33, 39, 42, 44, 45]

$$(2) \quad u_t = u_{xx}$$

which is invariant with respect to the six dimensional symmetry algebra generated by the vector fields

$$\begin{aligned} Q_1 &= \partial_x, & Q_2 &= \partial_t, & Q_3 &= u\partial_u, & Q_4 &= 2t\partial_t + x\partial_x, \\ Q_5 &= 2t\partial_x - xu\partial_u, & Q_6 &= 4t^2\partial_t + 4tx\partial_x - (x^2 + 2t)u\partial_u \end{aligned}$$

(For the moment we are ignoring the trivial infinite-dimensional subalgebras coming from the linearity of the heat equation and corresponding to the linear superposition principle).

The most general solution obtainable from a given solution $u = f(t, x)$ by group transformations is of the form

$$(3) \quad \tilde{u} = \frac{\varepsilon_3}{\sqrt{1 + 4\varepsilon_6 t}} e^{-\frac{\varepsilon_5 x + \varepsilon_6 x^2 - \varepsilon_5^2 t}{1 + 4\varepsilon_6 t}} f\left(\frac{\varepsilon_4^2 t}{1 + 4\varepsilon_6 t} - \varepsilon_2, \frac{\varepsilon_4(x - 2\varepsilon_5 t)}{1 + 4\varepsilon_6 t} - \varepsilon_1\right) + v(t, x),$$

where $v(t, x)$ is an arbitrary solution to the linear heat equation [42]. Considering the higher-order symmetry generators, one can prove that if $u = f(t, x)$ is a solution of the linear heat equation than

$$\begin{aligned} \tilde{u} &= 2tf_x(t, x) + xf(t, x) \quad \text{and} \\ \tilde{u} &= t^2 f_t(t, x) + txf_x(t, x) + \frac{1}{4}(2t + x^2)f(t, x) \end{aligned}$$

are also solutions of the same equation [4].

All possible inequivalent (with respect to inner automorphisms) one-dimensional subalgebras of the given algebra are exhausted by the ones listed in Table 1 [68] together with the corresponding ansatzes and the reduced ODEs.

Table 1. Reduced ODEs for linear heat equation (2)

N	Subalgebra	Ansatz $u =$	ω	Reduced ODE
1	$\langle Q_4 + aQ_3 \rangle$	$t^a \varphi(\omega)$	x/\sqrt{t}	$\varphi'' + \frac{\omega\varphi'}{2} - a\varphi = 0$
2	$\langle Q_2 + Q_6 + aQ_3 \rangle$	$(4t^2 + 1)^{\frac{1}{4}} \varphi(\omega)$ $e^{-(4t^2+1)^{-1}tx^2 - a \arctan(2t)/2}$	$(4t^2 + 1)^{-\frac{1}{2}} x$	$\varphi'' + (a + \omega^2)\varphi = 0$
3	$\langle Q_2 - Q_5 \rangle$	$\varphi(\omega)e^{tx+2t^3/3}$	$x + t^2$	$\varphi'' = \omega\varphi$
4	$\langle Q_2 + aQ_3 \rangle$	$\varphi(\omega)e^{at}$	x	$\varphi'' = a\varphi$
5	$\langle Q_1 \rangle$	$\varphi(\omega)$	t	$\varphi' = 0$
6	$\langle Q_3 \rangle$	—	—	—

Thus we have the following solutions of (2):

$$\begin{aligned} u &= t^a e^{-x^2/(8t)} \left(c_1 U\left(2a + \frac{1}{2}, \frac{x}{\sqrt{2t}}\right) + c_2 V\left(2a + \frac{1}{2}, \frac{x}{\sqrt{2t}}\right) \right), \\ u &= (4t^2 + 1)^{1/4} \left(c_1 W\left(-\frac{a}{2}, \frac{x}{\sqrt{8t^2 + 2}}\right) \right. \\ &\quad \left. + c_2 W\left(-\frac{a}{2}, -\frac{x}{\sqrt{8t^2 + 2}}\right) \right) e^{-\frac{tx^2}{(4t^2+1)} - \frac{a}{2} \arctan(2t)}, \\ u &= c_1 e^{\alpha^2 t} \cosh(\alpha x + c_2), \quad u = c_1 x + c_2, \quad u = c_1 e^{-\alpha^2 t} \cos(\alpha x + c_2), \end{aligned}$$

where $U(b, z)$, $V(b, z)$, $W(c, z)$ are parabolic cylinder functions [1].

Multiplicative separation of variables leads to the solutions invariant with respect to $\langle Q_2 + aQ_3 \rangle$. The additive separation of variables yields an exact solution of form

$$u = c_1 x^2 + c_2 x + 2c_1 t.$$

The known Q -conditional symmetry operators and corresponding reductions are adduced in Table 2. [21]

Table 2. Nonclassical reductions for linear heat equation (2)

N	Operator Q	Ansatz	Reduced equation
1	$-x\partial_t + \partial_x$	$u = \varphi\left(t + \frac{x^2}{2}\right)$	$\varphi'' = 0$
2	$-x\partial_t + \partial_x + x^3\partial_u$	$u = \varphi\left(t + \frac{x^2}{2}\right) + \frac{x^4}{4}$	$\varphi'' = -3$
3	$x^2\partial_t - 3x\partial_x - 3u\partial_u$	$u = x\varphi\left(t + \frac{x^2}{6}\right)$	$\varphi'' = 0$
4	$x^2\partial_t - 3x\partial_x - (3u + x^5)\partial_u$	$u = x\varphi\left(t + \frac{x^2}{6}\right) + \frac{x^5}{12}$	$\varphi'' = -15$
5	$x\partial_x + u\partial_u$	$u = x\varphi(t)$	$\varphi' = 0$
6	$\coth x\partial_x + u\partial_u$	$u = \varphi(t)\cosh x$	$\varphi' - \varphi = 0$
7	$-\cot x\partial_x + u\partial_u$	$u = \varphi(t)\cos x$	$\varphi' + \varphi = 0$
8	$\partial_x - u\partial_u - \frac{u}{2t-x}\partial_u$	$u = (2t-x)e^{-x}\varphi(t)$	$\varphi' - \varphi = 0$
9	$\partial_x - \sqrt{-2(t+u)}\partial_u$	$u = -t - \frac{1}{2}[x + \varphi(t)]^2$	$\varphi' = 0$
10	$\left(t + \frac{x^2}{2}\right)\partial_t - x\partial_x$	$u = \varphi\left(tx + \frac{x^2}{3!}\right)$	$\varphi'' = 0$

If function $f(t, x)$ is an arbitrary solution of the linear heat equation and u is the general integral of the ODE $f_x dt + f dx = 0$, then u satisfies the linear heat equation. This statement can be considered as another algorithm of generating solutions of the linear heat equation [21]. Indeed, even starting from a rather trivial solution of the heat equation $u = 1$ one gets the chain of quite interesting solutions

$$1 \rightarrow x \rightarrow t + \frac{x^2}{2!} \rightarrow tx + \frac{x^3}{3!} \rightarrow \dots,$$

and among them the solutions

$$\begin{aligned} & \frac{x^{2m}}{(2m)!} + \frac{t}{1!} \frac{x^{2m-2}}{(2m-2)!} + \frac{t^2}{2!} \frac{x^{2m-4}}{(2m-4)!} + \dots + \frac{t^{m-1}}{(m-1)!} \frac{x^2}{2!} + \frac{t^m}{m!}, \\ & \frac{x^{2m+1}}{(2m+1)!} + \frac{t}{1!} \frac{x^{2m-1}}{(2m-1)!} + \frac{t^2}{2!} \frac{x^{2m-3}}{(2m-3)!} + \dots + \frac{t^{m-1}}{(m-1)!} \frac{x^3}{3!} + \frac{t^m}{m!} \frac{x}{1!}, \end{aligned}$$

called often the *heat polynomials* [69].

3. Linearizable equations

Class (1) contains three equations, namely Burgers equation

$$(4) \quad \mathbf{u}_t = \mathbf{u}_{xx} + 2\mathbf{u}\mathbf{u}_x,$$

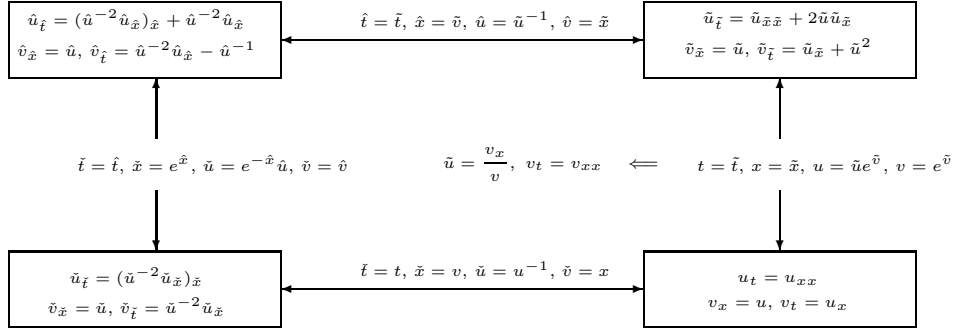
Fujita–Storm equation

$$(5) \quad \mathbf{u}_t = (\mathbf{u}^{-2}\mathbf{u}_x)_x$$

and Fokas–Yortsos equation

$$(6) \quad \mathbf{u}_t = (\mathbf{u}^{-2}\mathbf{u}_x)_x + \mathbf{u}^{-2}\mathbf{u}_x,$$

that are linearizable by the potential equivalence hodograph transformation and additional local equivalence transformations [10, 14, 18, 19, 25, 38, 50, 63, 64]:



Therefore, applying the above transformations to the well-known solutions of the linear heat equation one can easily construct solutions of the linearizable equations.

Thus, e.g., the fundamental (source) solution $u = (4\pi t)^{-1/2} e^{-x^2/(4t)}$ and dipole solution $u = -((4\pi t)^{-1/2} e^{-x^2/(4t)})_x$ are mapped into the separable and self-similar solutions of the Fujita–Storm equation [48]

$$u = (4\pi t)^{1/2} e^{v^2} \quad \text{where} \quad x = \pi^{-1/2} \int_0^v e^{-y^2} dy,$$

$$\text{and} \quad u = x^{-1} (2t)^{1/2} \left(\ln \frac{1}{4\pi t x^2} \right)^{-1/2}.$$

correspondingly.

Other solutions of the linear heat equation presented in the previous section yield the following explicit exact solutions of the Fujita–Storm equation [30]:

$$u = c, \quad u = x^{-1}, \quad u = (x - 2t)^{-\frac{1}{2}}, \quad u = (x^2 \pm e^{2t})^{-\frac{1}{2}},$$

$$u = \pm (e^{-2t} - x^2)^{-\frac{1}{2}}, \quad u = \frac{1}{4\sqrt{24t^2 + x}\sqrt{-6t \pm \sqrt{24t^2 + x}}}, \quad u = \frac{t}{x\sqrt{-t \ln(x\sqrt{t})}},$$

$$u = \frac{1}{\sqrt{c_1^2 e^{-2t} + 2e^{-8t} + 2e^{-4t}x}\sqrt{4 - e^{8t}(-c_1 e^{-t} \pm \sqrt{c_1^2 e^{-2t} + 2e^{-8t} + 2e^{-4t}x})^2}},$$

$$u = \frac{1}{\sqrt{c_1^2 e^{2t} + 2e^{8t} + 2e^{4t}x}\sqrt{e^{-8t}(-c_1 e^{-t} \pm \sqrt{c_1^2 e^{-2t} + 2e^{-8t} + 2e^{-4t}x})^2 - 4}}.$$

In [66] the following formula for deriving exact solutions of the Fujita–Storm equation is derived: if $u(t, x)$ is a solution of the Fujita–Storm equation (5) then

$$v = u + \frac{2tu_t + u + xu_x}{-t(u_x - \frac{1}{2}u^2) - \frac{x}{2}u}$$

is also solution of the same equation.

Similarly [67], if $u(t, x)$ is a solution of the and the Fokas–Yortsos equation (6) then

$$v = \frac{u^2}{u - u_x}$$

is also solution of the same equation. In [67] a new exact solution of the Fokas–Yortsos equation is presented:

$$u = \frac{1}{2} \frac{W(e^{4t+x})}{1 + W(e^{4t+x})},$$

where $W(x)$ is the Lambert W function determined as $W(x)e^{W(x)} = x$. Let us note that other exact solutions of the Fokas–Yortsos equation (6) can be easily recovered from the solution set of the Fujita–Storm equation (5) by means of application of the local transformation of variables shown in the above scheme.

The same tricks can be used for obtaining exact solutions of the remaining linearizable equations. However, since the adduced transformations are nonlocal, sometimes it could be easier to search directly for solutions of the nonlinear equations. Thus, e.g., one can easily find Lie solutions of the Burgers equation:

$$\begin{aligned} u &= \frac{c_1 - x}{2t + c_2}, \quad u = \varepsilon + \frac{1}{x + 2\varepsilon t + c}, \quad u = \frac{2x + c_1}{x^2 + c_1x + 2t + c_2}, \\ u &= \frac{6(x^2 + 2t + c_1)}{2x^3 + 12tx + 6c_1t + c_2}, \quad u = \frac{c_1}{1 + c_2e^{-c_1^2t - c_1x}}, \quad u = -\varepsilon + \frac{a e^{c_1(x-2\varepsilon t)} - c_2}{2 e^{c_1(x-2\varepsilon t)} + c_2}, \\ &u = -\varepsilon + c_1 \tanh(c_1(x - 2\varepsilon t) + c_2), \\ u &= \frac{\lambda}{2(\lambda^2t + c_1)} \left(2 \tanh \frac{\lambda x + c_2}{\lambda^2t + c_1} - \lambda x - c_2 \right), \\ u &= -\varepsilon - c_1 \tan(c_1(x - 2\varepsilon t) + c_2), \quad u = \frac{\lambda \cos(\lambda x + c_1)}{c_2 e^{\lambda^2t} + \sin(\lambda x + c_1)}, \\ u &= \frac{c_1}{\sqrt{\pi(t + c_2)}} \exp\left(-\frac{x + c_3}{4(t + c_2)}\right) \left(c_1 \operatorname{erf} \frac{x + c_3}{2\sqrt{t + c_2}} + c_4 \right)^{-1}, \\ u &= -\frac{\cos 2xe^{-3t} + c_1 \sin x}{-\cos x \sin xe^{-3t} + c_1 \cos x + c_2 e^t}, \\ u &= -\frac{c_1 e^{-t}(\cos x + \sin x) + c_2 e^{t+x}}{c_1 e^{-t}(\cos x - \sin x) - c_2 e^{t+x} + b}. \end{aligned}$$

Here $\operatorname{erf} z = \frac{2}{\sqrt{\pi}} \int_0^z e^{-\xi^2} d\xi$ is the error function (also called the probability integral). The last two solutions were found in [54].

Solutions of the Fujita–Storm and Fokas–Yortsos equations can be singled out from the solutions adduced in Sections 6 and 10 taking $\mu = -2$, $\nu = -2$. (Note that all these solutions can be also reconstructed from ones of the linear heat equation by means of potential equivalence transformations.)

If $u(t, x)$ is a solution of the Burgers equation (4) then

$$v = u + \frac{u_t}{u_x + u^2}, \quad u = u + \frac{u_t + u_x}{u_x + u^2 + u}$$

are also solutions of the same equation [66].

Potential equivalence transformations were used to obtain solutions of some boundary-value problems adduced in [10, 41, 63, 64]

4. Nonlinear diffusion equations. General case

Consider now the class of nonlinear diffusion equations

$$(7) \quad \mathbf{u}_t = (A(\mathbf{u})\mathbf{u}_x)_x,$$

where $A_u \neq 0$. Lie symmetries of this class have been studied in [44]. The Lie symmetry algebra of equation from class (7) with arbitrary value of parameter-function $A(u)$ is three-dimensional and spanned by

$$Q_1 = \partial_t, \quad Q_2 = \partial_x, \quad Q_3 = 2t\partial_t + x\partial_x.$$

Taking into account discrete symmetry transformations of changing signs of independent variables one can formulate the following statement. If $u = f(t, x)$ is a solution of equation (7), then $\tilde{u} = f(\varepsilon_1^2 t + \varepsilon_2, \varepsilon_1 x + \varepsilon_3)$ is also solution of the same equation.

All possible inequivalent (with respect to inner automorphisms) one-dimensional subalgebras of the given symmetry algebra, the corresponding ansatzes and the reduced ODEs are exhausted by the ones listed in Table 3.

Table 3. Reduced ODEs for nonlinear diffusion equations (7), $A_u \neq 0$.

N	Subalgebra	Ansatz $u =$	ω	Reduced ODE
1	$\langle Q_1 \rangle$	$\varphi(\omega)$	x	$(A(\varphi)\varphi)' = 0$
2	$\langle Q_2 \rangle$	$\varphi(\omega)$	t	$\varphi' = 0$
3	$\langle Q_1 + \varepsilon Q_2 \rangle$	$\varphi(\omega)$	$x - \varepsilon t$	$\varepsilon\varphi' = -(A(\varphi)\varphi)'$
4	$\langle Q_3 \rangle$	$\varphi(\omega)$	x/\sqrt{t}	$\omega\varphi' = -2(A(\varphi)\varphi)'$

The first three equations can be easily integrated for all values of $A(u)$. Solutions of the last equation are known for many functions $A(u)$ (see Section 9).

Consider now in more detail equations with wider symmetry algebras. Up to the group of equivalence transformations

$$\tilde{t} = \varepsilon_1 t + \varepsilon_4, \quad \tilde{x} = \varepsilon_2 x + \varepsilon_5, \quad \tilde{u} = \varepsilon_3 u + \varepsilon_6, \quad \tilde{A} = \varepsilon_1^{-1} \varepsilon_2^2 A$$

there exist three inequivalent cases of extensions of Lie symmetry algebra [44]: $a = e^u$, $a = u^\mu$, $\mu \neq -4/3$ and $a = u^{-4/3}$.

5. Nonlinear diffusion equations. Exponential nonlinearity

We start from the equation with exponential nonlinearity

$$(8) \quad \mathbf{u}_t = (e^u \mathbf{u}_x)_x,$$

having the four-dimensional Lie algebra spanned by the operators

$$Q_1 = \partial_t, \quad Q_2 = t\partial_t - \partial_u, \quad Q_3 = \partial_x, \quad Q_4 = x\partial_x + 2\partial_u.$$

The only non-zero commutators of these operators are $[Q_1, Q_2] = Q_1$ and $[Q_3, Q_4] = Q_3$. Therefore A^{\max} is a realization of the algebra $2A_{2,1}$ [40]. All the possible inequivalent (with respect to inner automorphisms) one-dimensional subalgebras of $2A_{2,1}$ [46] are exhausted by the ones listed in Table 4.

Table 4. Reduced ODEs for (8). $\alpha \neq 0$, $\varepsilon = \pm 1$, $\delta = \text{sign } t$.

N	Subalgebra	Ansatz $u =$	ω	Reduced ODE
1	$\langle Q_3 \rangle$	$\varphi(\omega)$	t	$\varphi' = 0$
2	$\langle Q_4 \rangle$	$\varphi(\omega) + 2 \ln x $	t	$\varphi' = 2e^\varphi$
3	$\langle Q_1 \rangle$	$\varphi(\omega)$	x	$(e^\varphi)'' = 0$
4	$\langle Q_2 \rangle$	$\varphi(\omega) - \ln t $	x	$(e^\varphi)'' = -\delta$
5	$\langle Q_1 + \varepsilon Q_3 \rangle$	$\varphi(\omega)$	$x - \varepsilon t$	$(e^\varphi)'' = -\varepsilon\varphi'$
6	$\langle Q_2 + \varepsilon Q_3 \rangle$	$\varphi(\omega) - \ln t $	$x - \varepsilon \ln t $	$(e^\varphi)'' = -\delta(\varepsilon\varphi' + 1)$
7	$\langle Q_1 + \varepsilon Q_4 \rangle$	$\varphi(\omega) + 2\varepsilon t$	$x e^{-\varepsilon t}$	$(e^\varphi)'' = -\varepsilon\omega\varphi' + 2\varepsilon$
8	$\langle Q_2 + \alpha Q_4 \rangle$	$\varphi(\omega) + (2\alpha - 1) \ln t $	$x t ^{-\alpha}$	$(e^\varphi)'' = \delta(-\alpha\omega\varphi' + 2\alpha - 1)$

Solving the equations 4.1–4.5 we have the following solutions of (8):

$$u = \ln |c_1 x + c_0|, \quad u = \ln \left(\frac{-x^2}{2t} + \frac{c_1 x + c_0}{t} \right),$$

$$u = \varphi(x - \varepsilon t) \quad \text{where} \quad \int \frac{e^\varphi}{c_1 - \varepsilon \varphi} d\varphi = x - \varepsilon t + c_0.$$

Equation (8) admits an additive separation of variable that leads to the solution invariant with respect to scale transformation.

If $u = f(t, x)$ is a solution of equation (8), then

$$\tilde{u} = f(\varepsilon_1 t + \varepsilon_3, \varepsilon_2 x + \varepsilon_4) - \varepsilon_1 + 2\varepsilon_2$$

is also solution of the same equation.

6. Nonlinear diffusion equations. Power nonlinearities

Another case of equations admitting extension of the Lie symmetry algebra is the one having power nonlinearity

$$(9) \quad u_t = (|u|^\mu u_x)_x.$$

As in the previous cases the invariance algebra of (9)

$$A^{\max} = \langle Q_1 = \partial_t, Q_2 = t\partial_t - \mu^{-1}u\partial_u, Q_3 = \partial_x, Q_4 = x\partial_x + 2\mu^{-1}u\partial_u \rangle$$

is a realization of the algebra $2A_{2,1}$.

If $u = f(t, x)$ is a solution of equation (9), then

$$\tilde{u} = \varepsilon_1^{-1} \varepsilon_2^2 f(\varepsilon_1^\mu t + \varepsilon_3, \varepsilon_2^\mu x + \varepsilon_4)$$

is also solution of the same equation.

The result of reduction (9) under inequivalent subalgebras of A^{\max} is written down in Table 5.

Table 5. Reduced ODEs for (9). $\mu \neq 0$, $\alpha \neq 0$, $\varepsilon = \pm 1$, $\delta = \text{sign } t$.

N	Subalgebra	Ansatz $u =$	ω	Reduced ODE
1	$\langle Q_3 \rangle$	$\varphi(\omega)$	t	$\varphi' = 0$
2	$\langle Q_4 \rangle$	$\varphi(\omega) x ^{2/\mu}$	t	$\varphi' = 2\mu^{-2}(2 + \mu)\varphi^{\mu+1}$
3	$\langle Q_1 \rangle$	$\varphi(\omega)$	x	$(\varphi^\mu \varphi')' = 0$
4	$\langle Q_2 \rangle$	$\varphi(\omega) t ^{-1/\mu}$	x	$(\varphi^\mu \varphi')' = -\delta\mu^{-1}\varphi$
5	$\langle Q_1 + \varepsilon Q_3 \rangle$	$\varphi(\omega)$	$x - \varepsilon t$	$(\varphi^\mu \varphi')' = -\varepsilon\varphi'$
6	$\langle Q_2 + \varepsilon Q_3 \rangle$	$\varphi(\omega) t ^{-1/\mu}$	$x - \varepsilon \ln t $	$(\varphi^\mu \varphi')' = -\delta\varepsilon\varphi' - \delta\mu^{-1}\varphi$
7	$\langle Q_1 + \varepsilon Q_4 \rangle$	$\varphi(\omega)e^{2\varepsilon\mu^{-1}t}$	$xe^{-\varepsilon t}$	$(\varphi^\mu \varphi')' = -\varepsilon\omega\varphi' + 2\mu^{-1}\varepsilon\varphi$
8	$\langle Q_2 + \alpha Q_4 \rangle$	$\varphi(\omega) t ^{(2\alpha-1)/\mu}$	$x t ^{-\alpha}$	$(\varphi^\mu \varphi')' = \delta\mu^{-1}(2\alpha - 1)\varphi - \delta\alpha\omega\varphi'$

For some of the reduced equations the general solutions are known. For other ones we succeeded to find only particular solutions. These solutions are following:

$$(10) \quad \begin{aligned} u &= |c_1 x + c_0|^{\frac{1}{\mu+1}}, \quad u = (c_0 - \varepsilon \mu(x - \varepsilon t))^{\frac{1}{\mu}}, \\ u &= \left(-\frac{\mu}{\mu+2} \frac{(x+c_0)^2}{2t} + c_1 |t|^{-\frac{\mu}{\mu+2}} \right)^{\frac{1}{\mu}}, \\ u &= \left(-\frac{\mu}{\mu+2} \frac{(x+c_0)^2}{2t} + c_1 (x+c_0)^{\frac{\mu}{\mu+1}} |t|^{-\frac{\mu(2\mu+3)}{2(\mu+1)^2}} \right)^{\frac{1}{\mu}}, \end{aligned}$$

$$(11) \quad u = \varphi(x - \varepsilon t) \quad \text{where} \quad \int \frac{\varphi^\mu}{c_1 - \varepsilon \varphi} d\varphi = x - \varepsilon t + c_0.$$

Equation (9) admits multiplicative separation of variables. Namely, for all values of μ one can find solution in form of the product of two functions of different arguments:

$$(12) \quad u(t, x) = (b_1 t + b_0)^{-1/\mu} f(x),$$

where the function $f = f(x)$ is given implicitly

$$\int \frac{f^\mu df}{\sqrt{c_1 - \lambda f^{\mu+2}}} = \pm x + c_0, \quad \lambda = \frac{2b_1}{\mu(\mu+2)}.$$

These could be found also in [2, 5, 6, 15, 24, 26, 48, 52, 58, 72, 74]. The most studied cases are equations with $\mu = \pm 1, -2, -4/3, -3/2$. Below we adduce their exact solutions that are inequivalent to (11) with respect to the Lie symmetry transformations.

Equation with the singular value of the parameter $\mu = -1$ called often the *fast diffusion equation*, is distinguished by the reduction procedure. Lie invariant solutions of it will be adduced in separate section together with non-Lie solutions obtained from invariance of the fast diffusion equation with respect to the nonclassical potential reduction operators.

Fujita–Storm equation (5) is linearizable and has been considered in a separate section.

Equation

$$(13) \quad \mathbf{u}_t = \left(\mathbf{u}^{-4/3} \mathbf{u}_x \right)_x$$

admits the five-dimensional Lie symmetry algebra generated by

$$Q_1 = \partial_t, \quad Q_2 = t\partial_t - \mu^{-1}u\partial_u, \quad Q_3 = \partial_x, \quad Q_4 = x\partial_x + \frac{3}{2}u\partial_u, \quad Q_5 = -x^2\partial_x + 3xu\partial_u.$$

An optimal system of one-dimensional subalgebras of this algebra is

$$\langle Q_1 + Q_4 \rangle, \langle aQ_3 + Q_4 \rangle, \langle Q_5 \rangle, \langle Q_2 + Q_5 \rangle, \langle Q_3 + Q_5 \rangle.$$

One can easily construct the corresponding ansatzes and the reduced ODEs. However, to the best of our knowledge all the found solutions of these equations are equivalent to (11) with particular value of parameter $\mu = -4/3$. Solutions of (13) invariant with respect to dilatation operators can be found also in [35]. Besides the already adduced Lie invariant solutions, equation (13) has functional separated solution [22, 57]

$$u = (\varphi_4(t)x^4 + \varphi_3(t)x^3 + \varphi_2(t)x^2 + \varphi_1(t)x + \varphi_0(t))^{-3/4},$$

where the functions $\varphi_i = \varphi_i(t)$ are determined by the system of ordinary differential equations

$$\begin{aligned}\varphi'_0 &= -\frac{3}{4}\varphi_1^2 + 2\varphi_0\varphi_2, & \varphi'_1 &= -\varphi_1\varphi_2 + 6\varphi_0\varphi_3, & \varphi'_2 &= -\varphi_2^2 + \frac{3}{2}\varphi_1\varphi_3 + 12\varphi_0\varphi_4, \\ \varphi'_3 &= -\varphi_2\varphi_3 + 6\varphi_1\varphi_4, & \varphi'_4 &= -\frac{3}{4}\varphi_3^2 + 2\varphi_2\varphi_4.\end{aligned}$$

The general form of exact solutions of (13) obtained from the known ones $u = f(t, x)$ with action of group transformations is

$$\tilde{u} = \frac{\varepsilon_1^{-1}\varepsilon_2^2}{(\varepsilon_5x + 1)^3} f\left(\varepsilon_1^{-4/3}t + \varepsilon_3, \frac{\varepsilon_2^{-4/3}x}{\varepsilon_5x + 1} + \varepsilon_4\right).$$

Equation

$$\mathbf{u}_t = \left(\mathbf{u}^{-3/2}\mathbf{u}_x\right)_x,$$

admits also the functional separation of variables. The corresponding exact solution is

$$u = (3c_1x^3 + f_2(t)x^2 + f_1(t)x + f_0(t))^{-2/3}.$$

Here

$$\begin{aligned}f_2(t) &= 3\int\varphi(t)dt + 3c_2, & f_1(t) &= \frac{1}{c_1}(\int\varphi(t)dt + c_2)^2 + \frac{1}{2c_1}\varphi(t), \\ f_0(t) &= \frac{1}{9c_1^2}(\int\varphi(t)dt + c_2)^3 + \frac{1}{6c_1^2}\varphi(t)(\int\varphi(t)dt + c_2) + \frac{1}{36c_1^2}\varphi'(t),\end{aligned}$$

where the function $\varphi = \varphi(t)$ is defined implicitly by $\int(c_3 - 8\varphi^3)^{-1/2}d\varphi = \pm t + c_4$.

T.K. Amerov [3] and J.R. King [36] suggested to look for solutions of the equation

$$\mathbf{u}_t = (\mathbf{u}^{-1/2}\mathbf{u}_x)_x$$

in the form $u = (\varphi^1(x)t + \varphi^0(x))^2$ where the functions $\varphi^1(x)$ and $\varphi^0(x)$ satisfy the system of ODEs $\varphi_{xx}^1 = (\varphi^1)^2$, $\varphi_{xx}^0 = \varphi^0\varphi^1$. A particular solution of this system is

$$\varphi^1 = \frac{6}{x^2}, \quad \varphi^0 = \frac{c_1}{x^2} + \frac{c_2}{x^3}.$$

7. Porous medium equation $\mathbf{u}_t = (\mathbf{u}\mathbf{u}_x)_x$

Another important subclass of diffusion equations is a special case of equation (9) with $\mu = 1$

$$(14) \quad \mathbf{u}_t = (\mathbf{u}\mathbf{u}_x)_x,$$

called also *porous medium equation*. Its first exact solution has been obtained by Boussinesq [13]. He was looking for a solution in a separated form $u(t, x) = X(x)T(t)$ satisfying conditions

$$u(t, 0) = 0, \quad u_x|_{x=L} = 0.$$

Thus constructed solution reads as

$$u = \frac{H_0F(\xi)}{1 + (3b^2H_0/2L^2)t},$$

where H_0 is a constant, $\xi = x/L$ and the function $F = F(\xi)$ is defined implicitly

$$\xi = \frac{1}{b} \int_0^F \frac{\lambda d\lambda}{\sqrt{1 - \lambda^3}}, \quad b = \int_0^1 \frac{\lambda d\lambda}{\sqrt{1 - \lambda^3}} = \frac{1}{3}B\left(\frac{2}{3}, \frac{1}{2}\right).$$

The next exact solution of the porous medium equation (14) was found much later by Barenblatt [6] and written in the present form by Sokolov [59] (the instant source solution):

$$u = \frac{1}{6t}((9t)^{2/3} - x^2), \quad 0 \leq x \leq (9t)^{1/3} = l.$$

It is easy to become convinced of the fact that both Boussinesq and Barenblatt solutions correspond to the Lie symmetry of the porous medium equation (14) [73]. Indeed, the Boussinesq solution is a particular case of the ansatz

$$u = (1 + \alpha t)^{-1} \phi(x), \quad \alpha = \frac{3b^2 H_0}{2L^2},$$

that is invariant with respect to the one-parameter Lie symmetry group generated by $Q = (1 + \alpha t)\partial_t - u\partial_u$. Barenblatt solution is invariant with respect to the one-parameter Lie symmetry group generated by $Q = 3t\partial_t + x\partial_x - u\partial_u$.

Besides (11), its exact solutions in parametric form are known [48]:

$$\begin{aligned} x &= (6t + c_1)\xi + c_2\xi^2 + c_3, & u &= -(6t + c_1)\xi^2 - 2c_2\xi^3, \\ x &= tf(\omega) + g(\omega), & u &= tf'(\omega) + g'(\omega), \end{aligned}$$

where the functions $f = f(\omega)$ and $g = g(\omega)$ are determined by the system of ODEs:

$$(f')^2 - ff'' = f''', \quad f'g' - fg'' = g'''.$$

It is obvious, that the second equation has two linearly independent particular solutions $g = 1$ and $g = f$. The general solution of these equations can be represented in form

$$g = c_1 + c_2f + c_3(f \int \psi d\omega - \int f\psi d\xi), \quad f = f(\omega), \quad \psi = \frac{1}{(f')^2} e^{-\int f d\omega}.$$

It is not difficult to verify, that it has the following particular solutions

$$f = \frac{6}{\omega + c_1} \quad \text{and} \quad f = c_1 e^{c_2 \omega}.$$

One can see, that the first solution leads to the previously given implicit solution.

8. Fast diffusion equation $u_t = (u^{-1}u_x)_x$

All invariant solutions of fast diffusion equation

$$(15) \quad u_t = (u^{-1}u_x)_x,$$

which were earlier constructed in closed forms with the classical Lie method, were collected e.g. in [48–51]. A complete list of G_1 -inequivalent solutions of such type is exhausted by the following ones:

$$(16) \quad \begin{aligned} 1) \ u &= \frac{1}{1 + \varepsilon e^{x+t}}, & 2) \ u &= e^x, & 3) \ u &= \frac{1}{x - t + \mu t e^{-x/t}}, \\ 4) \ u &= \frac{2t}{x^2 + \varepsilon t^2}, & 5) \ u &= \frac{2t}{\cos^2 x}, & 6) \ u &= \frac{-2t}{\cosh^2 x}, & 7) \ u &= \frac{2t}{\sinh^2 x}. \end{aligned}$$

The below arrows denote the possible transformations of solutions (16) to each other by means of the potential hodograph transformation (17) up to translations

with respect to x [50]:

$$\begin{aligned} \circlearrowleft 1)_{\varepsilon=0}; \quad 1)_{\varepsilon=1} \longleftrightarrow 1)_{\varepsilon=-1, x+t<0}; \quad \circlearrowright 1)_{\varepsilon=-1, x+t>0}; \quad 2) \longleftrightarrow 3)_{\mu=0, x>t}; \\ \circlearrowleft 4)_{\varepsilon=0}; \quad 5) \longleftrightarrow 4)_{\varepsilon=4}; \quad 6) \longleftrightarrow 4)_{\varepsilon=-4, |x|<2|t|}; \quad 7) \longleftrightarrow 4)_{\varepsilon=-4, |x|>2|t|}. \end{aligned}$$

The sixth connection can be found also in [20, 53]. If $\mu \neq 0$ solution 3) from list (16) is mapped by (17) to the solution

$$8) \quad u = t\vartheta(\omega) - t + \mu t e^{-\vartheta(\omega)}, \quad \omega = x - \ln|t|,$$

which is invariant with respect to the algebra $\langle t\partial_t + \partial_x + u\partial_u \rangle$. Here ϑ is the function determined implicitly by the formula $\int(\vartheta - 1 + \mu e^{-\vartheta})^{-1} d\vartheta = \omega$.

Some non-Lie exact solutions of (15) were obtained in [23, 55, 56]. Thus, P. Rosenau [56] found that potential equation $v_t = v_x^{-1}v_{xx}$ corresponding to (15) admits, in addition to the usual variable separation $v = T(t)X(x)$, the additive one $v = Y(x + \lambda t) + Z(x - \lambda t)$ which is a potential additive variable separation for the fast diffusion equation (15). (The classical multiplicative separation of variables is given by (12) with $\mu = -1$.) To construct nonclassical solutions of (15), C. Qu [55] made use of generalized conditional symmetry method, looking for the conditional symmetry operators in the special form $Q = (u_{xx} + H(u)u_x^2 + F(u)u_x + G(u))\partial_u$. M.L. Gandarias [23] investigated some families of usual and potential nonclassical symmetries of (9). In particular, using an ansatz for the coefficient η , she found non-trivial reduction operators in the so-called “no-go” case when the coefficient of ∂_t vanishes, i.e. operators can be reduced to the form $Q = \partial_x + \eta(t, x, u)\partial_u$. These solutions and the ones similar to them were represented uniformly over the complex field as compositions of two simple waves which move with the same “velocities” in opposite directions in [51]. Using such representation the following solutions of fast diffusion equation (15) were obtained [51]:

$$\begin{aligned} 1') \quad u &= \cot(x-t) - \cot(x+t) = \frac{2 \sin 2t}{\cos 2t - \cos 2x}, \\ 2') \quad u &= \coth(x-t) - \coth(x+t) = \frac{2 \sinh 2t}{\cosh 2x - \cosh 2t}, \\ 3') \quad u &= \coth(x-t) - \tanh(x+t) = \frac{2 \cosh 2t}{\sinh 2x - \sinh 2t}, \\ 4') \quad u &= \tanh(x-t) - \tanh(x+t) = -\frac{2 \sinh 2t}{\cosh 2x + \cosh 2t}, \\ 5') \quad u &= \cot(ix+t) - \cot(ix-t) = \frac{2 \sin 2t}{\cosh 2x - \cos 2t}, \\ 6') \quad u &= i \cot(x+it) - i \cot(x-it) = \frac{2 \sinh 2t}{\cosh 2t - \cos 2x}. \end{aligned}$$

Transformation (17) acts on the set of solutions 1')–6') in the following way [51]:

$$\begin{aligned} 1')_{\cos 2t < \cos 2x} \longleftrightarrow 5')_{|t \rightarrow t + \pi/2, x \rightarrow x/2, v \rightarrow 2v}; \\ 1')_{\cos 2t > \cos 2x} \longleftrightarrow 5')_{|x \rightarrow x/2, v \rightarrow 2v - \pi}; \\ 2')_{|x| < |t|} \longleftrightarrow 4')_{|x \rightarrow x/2, v \rightarrow 2v}; \quad \circlearrowleft 2')_{|x| > |t|} |_{x \rightarrow x/2, v \rightarrow 2v}; \\ \circlearrowleft 3')_{x < t} |_{x \rightarrow x/2, v \rightarrow 2v}; \quad 3')_{x > t} \longleftrightarrow 3')_{x > t} |_{x \rightarrow -x/2, v \rightarrow -2v}; \\ \circlearrowleft 6')_{|x \rightarrow x/2, v \rightarrow 2v}. \end{aligned}$$

These actions can be interpreted in terms of actions of transformation (17) on the nonclassical symmetry operators which correspond to solutions 1')–6').

In [56] P. Rosenau considered additive separation of variables for the potential fast diffusion equation (15) and constructed solution 4'). Using the generalized conditional symmetry method, C. Qu [55] found solutions which can be written in forms 1') and 6'). After rectifying computations in two cases from [55], one can find also solutions 2') and 5'). Solutions 1'), 3') and 4') were obtained in [23]. The remaining solutions from the above list were found in [51].

One of techniques which can be applied for finding the above solutions is reduction by conditional symmetry operators of the form $Q = \partial_x + (\eta^1(t, x)u + \eta^2(t, x))u\partial_u$ (see [23] for details). All reductions performed with reduction operators of such type result in solutions which are equivalent to the listed Lie solutions 1)–7) or solutions 1')–6').

9. Nonlinear diffusion equations. Other nonlinearities

Known exact solutions of the reduced equation 3.4 corresponding to $\langle Q_3 = 2t\partial_t + x\partial_x \rangle$ (which are self-similar solutions of (7)) are adduced in Table 6 [48].

Table 6. Self-similar solutions for nonlinear diffusion equations (7), $\omega = x/\sqrt{t}$

N	$A(u)$	Solution $\omega = \omega(u)$	Conditions
1	$\frac{n}{2}u^n - \frac{n}{2(n+1)}u^{2n}$	$1 - u^n$	$n > 0$
2	$\frac{n}{2(n+1)}((1-u)^{n-1} - (1-u)^{2n})$	$(1-u)^n$	$n > 0$
3	$\frac{n}{2(1-n)}u^{-2n} - \frac{n}{2}u^{-n}$	$u^{-n} - 1$	$0 < n < 1$
4	$\frac{1}{2}\sin^2 \frac{\pi u}{2}$	$\cos \frac{\pi u}{2}$	
5	$\frac{1}{8}\sin \pi u (\pi u + \sin \pi u)$	$\cos^2 \frac{\pi u}{2}$	
6	$\frac{1}{16}\sin^2 \pi u (5 + \cos \pi u)$	$\cos^3 \frac{\pi u}{2}$	
7	$\frac{1}{2}\cos \frac{\pi u}{2} \left(\cos \frac{\pi u}{2} + \frac{\pi u}{2} - 1 \right)$	$1 - \sin \frac{\pi u}{2}$	
8	$\frac{u \arccos u + 1}{2\sqrt{1-u^2}} - \frac{1}{2}$	$\arccos u$	
9	$\frac{\pi - 2(1-u)\arcsin(1-u)}{4\sqrt{2u-u^3}} - \frac{1}{2}$	$\arcsin(1-u)$	
10	$\frac{u \arcsin u}{4\sqrt{1-u^2}} + \frac{1}{4}u^2$	$\sqrt{1-u^2}$	
11	$\frac{1}{2}(1 - \ln u)$	$-\ln u$	

Let us give some more examples of travelling wave solutions [26, 48, 58]:

$$\begin{aligned} \mathbf{u}_t &= (\sinh^2 \mathbf{u} \mathbf{u}_x)_x, & u &= \operatorname{arccosh}^2 \frac{\pm x + c_1}{\sqrt{c_2 - 2t}}, \\ \mathbf{u}_t &= (\cosh^2 \mathbf{u} \mathbf{u}_x)_x, & u &= \operatorname{arcsinh}^2 \frac{\pm x + c_1}{\sqrt{c_2 - 2t}}, \\ \mathbf{u}_t &= ((\mathbf{u}^{2\mu} + b\mathbf{u}^\mu) \mathbf{u}_x)_x, & u &= \left(\sqrt{\frac{c_1}{a(c_1 + 1)(c_2 - t)}} (x + c_1) - \frac{2bc_1}{a(c_1 + 1)} \right)^{\frac{1}{\mu}}, \\ \mathbf{u}_t &= ((e^{2u} + bu e^u) \mathbf{u}_x)_x, & u &= \ln \left(\frac{\pm x + c_1}{\sqrt{c_2 - 2t}} - b \right), \\ \mathbf{u}_t &= (\mathbf{u} e^{\mathbf{u}} \mathbf{u}_x)_x, & u &= \ln(c_1 x + c_1^2 t + c_0). \end{aligned}$$

For equation with logarithmical nonlinearity

$$\mathbf{u}_t = (\ln \mathbf{u} \mathbf{u}_x)_x$$

travelling wave and self-similar solutions are known:

$$u = \exp \left(\pm \sqrt{2c_1 x + 2c_1^2 t + c_2} \right), \quad u = \exp \left(\frac{\pm x + c_1}{c_2 - 2t} - 1 \right).$$

A number of exact solution for equations of class (7) were constructed with nonlocal (quasilocal or potential) symmetries [2, 11, 12, 60–62].

Thus, e.g., reductions with respect to the optimal system of subalgebras of Lie algebra of potential/quasilocal symmetries of equation

$$\mathbf{u}_t = ((1 + \mathbf{u}^2)^{-1} \mathbf{u}_x)_x$$

give rise to exact solutions of form

$$\begin{aligned} u &= ce^{t-x} (1 - c^2 e^{2(t-x)})^{-1/2}, & u &= -x(c - 2t - x^2)^{-1/2}, \\ u &= \tan(\varphi(\omega) + \arctan(\lambda(\omega)) + \varepsilon t), \\ \text{where } \omega &= x^2 + v^2, & v &= \tan(\varphi(\omega) + \varepsilon t), \quad \text{and} \\ u &= x \tan(\varphi(\omega) + \arctan(\lambda(\omega)) + \varepsilon t), \\ \text{where } \omega &= \frac{x^2 + v^2}{t}, & v &= x \tan \left(\varphi(\omega) + \frac{\alpha}{2} \varepsilon t \right). \end{aligned}$$

Here $\varphi(\omega)$ and $\lambda(\omega)$ are arbitrary solutions of the system $\varphi' = \omega^{-1} \lambda/2$, $\lambda' = (1 + \lambda^2)(\varepsilon - \omega^{-1} \lambda)/2$. The list of known exact solutions of this equation (called often the Fujita's equation) involves also the following ones [2, 16, 26, 48]:

$$\begin{aligned} u &= \tan(c_1 x + c_2), & u &= \pm x(c_1 - 2t - x^2)^{-1/2}, \\ u &= \frac{\pm e^{t-x}}{\sqrt{1 - e^{2(t-x)}}}, & \varepsilon(x + \varepsilon t) + c_2 &= \frac{1}{c_1^2 + 1} \left(\ln \frac{|u + c_1|}{\sqrt{u^2 + 1}} + c_1 \arctan u \right), \\ u &= \frac{v}{\sqrt{1 - v^2}}, & \text{where } v &= \frac{c_1 e^{\lambda x} + c_2 e^{-\lambda x}}{\sqrt{4c_1 c_2 + c_3 e^{-2\lambda^2 t}}} \quad \text{or} \\ v &= \frac{c_1 \sin \lambda x + c_2 \cos \lambda x}{\sqrt{c_1^2 + c_2^2 + c_3 e^{2\lambda^2 t}}}, \\ u &= \frac{\sinh x}{\sqrt{-\cosh^2 x - e^{-2t}}}, & u &= \frac{\pm \cosh x}{\sqrt{-\sinh^2 x + e^{-2t}}}, & u &= \frac{\sin x}{\sqrt{\cos^2 x \pm e^{2t}}}. \end{aligned}$$

We adduce also some exact solutions of another equation with Fujita's type nonlinearity

$$u_t = ((1 - u^2)^{-1} u_x)_x,$$

namely [16]:

$$\begin{aligned} u = c, \quad u = \tanh x, \quad u = \frac{x}{\sqrt{x^2 + 2t}} \quad (t > 0), \\ u = \frac{\pm e^{t-x}}{\sqrt{1 + e^{2(x-t)}}}, \quad u = \frac{\sinh x}{\sqrt{\cosh^2 x + e^{-2t}}}, \\ u = \frac{\sinh x}{\sqrt{\cosh^2 x - e^{-2t}}} \quad (t > 0), \quad u = \frac{\pm \cosh x}{\sqrt{\sinh^2 x + e^{-2t}}} \quad (t < 0), \\ u = \frac{\sin x}{\sqrt{-\cos^2 x + e^{2t}}} \end{aligned}$$

The third similarity solution converges (pointwise) to a step function as $t \rightarrow 0^+$, and to zero as $t \rightarrow \infty$. The fourth solutions are bounded travelling waves. The fifth and sixth solutions converge to the time independent second solution as $t \rightarrow \infty$. The sixth solution converge to a step function as $t \rightarrow 0^+$. The seventh solution converges to the values ± 1 as $t \rightarrow 0^-$. The last solution converges to a square wave as $t \rightarrow 0+$, and to zero as $t \rightarrow \infty$.

One more example of solution obtained with application of potential symmetry is $u = \tan(\varphi(\omega) + \arctan(2\omega\varphi') - \lambda^{-1} \ln t)$ for the equation

$$u_t = ((1 + u^2)^{-1} e^{\lambda \arctan u} u_x)_x.$$

Here

$$\omega = x^2 + v^2, \quad \varphi = \frac{1}{\lambda} \ln \frac{c - \omega}{2} - \arctan \psi(\omega), \quad \frac{\psi'}{1 + \psi^2} + \frac{\psi}{2\omega} + \frac{2}{\lambda(c - \omega)} = 0.$$

All the potential symmetries of equations from class (18) can be obtained from Lie symmetries of (18) by means of prolongation to the potential variable v and application of potential equivalence transformations [50]

$$\tilde{t} = t, \quad \tilde{x} = x + \varepsilon v, \quad \tilde{u} = \frac{u}{1 + \varepsilon u}, \quad \tilde{v} = v, \quad \tilde{A} = (1 + \varepsilon u)^2 A$$

and hodograph transformation

$$(17) \quad \tilde{t} = t, \quad \tilde{x} = v, \quad \tilde{u} = u^{-1}, \quad \tilde{v} = x, \quad \tilde{A} = u^2 A,$$

where $v_x = u, v_t = Au_x$.

Therefore, these transformations can be used for obtaining potentially invariant exact solutions from the Lie ones. The complete list of nonlinear constant coefficient diffusion and diffusion-convection equations having potential symmetries together with the transformations mapping them to the equations with power and exponential nonlinearities can be found in [50].

In [65] non-point nonclassical symmetry operators are used to obtain exact solutions of evolution equations. In particular, it is shown that equation

$$u_t = (u^{-2} e^{1/u} u_x)_x$$

admits an exact solution in implicit form $u = (z^2 + c)/(2t)$, where

$$z = \frac{z}{\ln \frac{z^2+c}{2e^{2t}} + \frac{2\sqrt{c}}{z} \arctan \frac{z}{\sqrt{c}} + \frac{c_1}{z}}, \quad \text{if } c > 0, \quad \text{and}$$

$$z = \frac{z}{\ln \frac{z^2+c}{2e^{2t}} + \frac{2\sqrt{-c}}{z} \ln \frac{z-\sqrt{-c}}{z+\sqrt{-c}} + \frac{c_1}{z}}, \quad \text{if } c < 0.$$

A number of authors considered additive separated solutions of diffusion equations (7), i.e., solutions of form

$$u(t, x) = \varphi(t) + \psi(x).$$

Usually such solutions are Lie invariant. They were adduced in previous sections. So, here we adduce only list of equations admitting such kind of separation of variables. Namely, a diffusion equation (7) admits separation of variables if and only if it is G^\sim -equivalent to equation with the diffusion coefficient being of the following functions [16]:

$$A = |u|^\mu, \quad A = e^u, \quad A = (u^2 \pm 1)^{-1},$$

$$A = z(u)e^{z(u)}, \quad u = \int_1^z s^{-3/2} e^{-s/2} ds, \quad z > 0,$$

$$A = e^{\sigma z(u)} \cosh z(u), \quad \sigma \neq \pm 1, \quad u = \int_0^z \cosh^{-3/2} s e^{-\sigma s/2} ds, \quad -\infty < z < \infty$$

$$A = e^{\sigma z(u)} \sinh z(u), \quad \sigma \neq \pm 1, \quad u = \int_1^z \sinh^{-3/2} s e^{-\sigma s/2} ds, \quad z > 0,$$

$$A = e^{\sigma z(u)} \cos z(u), \quad u = \int_0^z \cos^{-3/2} s e^{-\sigma s/2} ds, \quad -\pi/2 < z < \pi/2.$$

10. Constant coefficient diffusion–convection equations

Lie symmetries of the constant coefficient diffusion–convection equation

$$(18) \quad \mathbf{u}_t = (\mathbf{A}(\mathbf{u})\mathbf{u}_x)_x + \mathbf{B}(\mathbf{u})\mathbf{u}_x,$$

$B \neq 0$ and corresponding Lie reductions were considered by a number of authors, see for example, [17, 32, 33, 43, 71]. However the complete group classification of class (18) was presented only recently in [49].

Any equivalence transformation of class (18) has the form:

$$(19) \quad \begin{aligned} \tilde{t} &= t\varepsilon_4^2\varepsilon_5 + \varepsilon_1, & \tilde{x} &= x\varepsilon_4 + \varepsilon_7 t + \varepsilon_2, & \tilde{u} &= u\varepsilon_6 + \varepsilon_3, \\ \tilde{A} &= A\varepsilon_5^{-1}, & \tilde{B} &= B\varepsilon_4^{-1}\varepsilon_5^{-1} - \varepsilon_7, \end{aligned}$$

where $\varepsilon_1, \dots, \varepsilon_7$ are arbitrary constants, $\varepsilon_4\varepsilon_5\varepsilon_6 \neq 0$. Note, that all the equations with $B(u) = \text{const}$ are reducible to diffusion equation (7). Besides such ‘trivial’ cases, Burgers equation and Fokas–Yortsos equation, only few Lie invariant solutions for equations with non-zero convectivity are found. Thus, e.g., in [71] scale-invariant solution

$$xu^{-\mu/2} - (1 + 2/\mu) \ln(xu^{-\mu/2} - 1 - 2/\mu) = c_1 t + c_0$$

in implicit form is found for the equation with power nonlinearities

$$\mathbf{u}_t = (\mathbf{u}^\mu \mathbf{u}_x)_x + \mathbf{u}^{\mu/2} \mathbf{u}_x.$$

was found.

M. Edwards [17] investigated Lie symmetries of (18) and constructed optimal subalgebras of the symmetry algebras for some of equations from the class. Here we supplement her results and adduce the complete list of Lie reductions of equations from class (18). (The linearizable Fokas–Yortsos and Burgers equations have been considered separately in Section 3.)

Table 7. Reduced ODEs for $u_t = (e^{\mu u} u_x)_x + e^u u_x$ ($\mu \neq 0$)

Subalgebra	Ansatz $u =$	ω	Reduced ODE
$\langle \partial_x \rangle$	$\varphi(\omega)$	t	$\varphi' = 0$
$\langle \partial_t \rangle$	$\varphi(\omega)$	x	$(e^{\mu\varphi} \varphi')' + e^\varphi \varphi' = 0$
$\langle \partial_t + \varepsilon \partial_x \rangle$	$\varphi(\omega)$	$x - \varepsilon t$	$-\varepsilon \varphi' = (e^{\mu\varphi} \varphi')' + e^\varphi \varphi'$
$\langle (\mu t - 2t + \varepsilon) \partial_t$ $+ (\mu - 1)x \partial_x + \partial_u \rangle$ ($\mu \neq 2$)	$\varphi(\omega) +$ $+\frac{\ln((\mu - 2)t + \varepsilon)}{\mu - 2}$	$x((\mu - 2)t$ $+ \varepsilon) \frac{1-\mu}{\mu-2}$	$\varphi'(1 - \mu)\omega + 1$ $= (e^{\mu\varphi} \varphi')' + e^\varphi \varphi'$
$\langle \varepsilon \partial_t + x \partial_x + \partial_u \rangle$ ($\mu = 2$)	$\varphi(\omega) + \frac{t}{\varepsilon}$	$x e^{-t/\varepsilon}$	$\frac{1}{\varepsilon} - \varphi' \omega = (e^{2\varphi} \varphi')' + e^\varphi \varphi'$

If $u = f(t, x)$ is an exact solution of equation $u_t = (e^{\mu u} u_x)_x + e^u u_x$, then

$$u = f(e^{(\mu-2)\varepsilon_1 t + \varepsilon_3}, e^{(\mu-1)\varepsilon_1 + \varepsilon_2} x + \varepsilon_4) + \varepsilon_1 + \varepsilon_2$$

is also solution of the same equation.

Table 8. Reduced ODEs for $u_t = (e^u u_x)_x + u u_x$.

Subalgebra	Ansatz $u =$	ω	Reduced ODE
$\langle \partial_x \rangle$	$\varphi(\omega)$	t	$\varphi' = 0$
$\langle \partial_t \rangle$	$\varphi(\omega)$	x	$(e^\varphi \varphi')' + \varphi \varphi' = 0$
$\langle \partial_t + \varepsilon \partial_x \rangle$	$\varphi(\omega)$	$x - \varepsilon t$	$-\varepsilon \varphi' = (e^\varphi \varphi')' + \varphi \varphi'$
$\langle (t + \varepsilon) \partial_t + (x - t) \partial_x + \partial_u \rangle$	$\varphi(\omega)$ $+ \ln t + \varepsilon $	$\frac{x + \varepsilon}{t + \varepsilon}$ $+ \ln t + \varepsilon $	$1 + \varphi'(1 - \omega) = (e^\varphi \varphi')' + \varphi \varphi'$

If $u = f(t, x)$ is an exact solution of equation $u_t = (e^u u_x)_x + u u_x$, then

$$u = f(e^{\varepsilon_1 t + \varepsilon_2}, e^{\varepsilon_1} (x - \varepsilon_1 t + \varepsilon_3)) + \varepsilon_1$$

is also solution of the same equation.

Table 9. Reduced ODEs for $u_t = (u^\mu u_x)_x + u^\nu u_x$.

Subalgebra	Ansatz $u =$	ω	Reduced ODE
$\langle \partial_x \rangle$	$\varphi(\omega)$	t	$\varphi' = 0$
$\langle \partial_t \rangle$	$\varphi(\omega)$	x	$(\varphi^\mu \varphi)' + \varphi^\nu \varphi' = 0$
$\langle \partial_t + \varepsilon \partial_x \rangle$	$\varphi(\omega)$	$x - \varepsilon t$	$-\varepsilon \varphi' = (\varphi^\mu \varphi)' + \varphi^\nu \varphi'$
$\langle (\mu t - 2\nu t + \varepsilon) \partial_t$ $+ (\mu - \nu)x \partial_x + u \partial_u \rangle$, ($\mu \neq 2\nu$)	$\varphi(\omega)((\mu - 2\nu)t$ $+ \varepsilon) \frac{1}{\mu - 2\nu}$	$x((\mu - 2\nu)t$ $+ \varepsilon) \frac{\nu - \mu}{\mu - 2\nu}$	$\varphi + \varphi' \omega = (\varphi^\mu \varphi)' + \varphi^\nu \varphi'$
$\langle \varepsilon \partial_t + \nu x \partial_x + u \partial_u \rangle$, ($\mu = 2\nu$)	$\varphi(\omega) e^{t/\varepsilon}$	$x e^{-\nu t/\varepsilon}$	$\varphi - \varphi' \omega = (\varphi^{2\nu} \varphi')' + \varphi^\nu \varphi'$

If $u = f(t, x)$ is an exact solution of equation $u_t = (u^\mu u_x)_x + u^\nu u_x$, then

$$u = e^{\varepsilon_1 + \varepsilon_2} f(e^{(\mu-2\nu)\varepsilon_1 t + \varepsilon_3}, e^{(\mu-\nu)\varepsilon_1 + \nu\varepsilon_2} x + \varepsilon_4)$$

is also solution of the same equation.

For equations with $\nu = \mu$ the generalized travelling wave solution is known:

$$u = \left(\frac{c_2 - x}{t + c_1} + \frac{\ln |t + c_1|}{\mu(t + c_1)} \right)^{1/\mu}.$$

If $\mu = 2, \nu = 1$ then the generalized travelling wave solution in implicit form is the following:

$$2 \int \frac{u^2 du}{-u^2 - 2\epsilon u + c_1} = x - \epsilon t + c_2.$$

For such values μ and ν the degenerate solution linear in x has the form $u = \tau(t)(x + c_1)$, where function τ is given in implicit form

$$-\frac{1}{\tau} + 2 \ln \left| \frac{2\tau + 1}{\tau} \right| = t + c_2.$$

Table 10. Reduced ODEs for $u_t = (u^\mu u_x)_x + \ln uu_x$.

Subalgebra	Ansatz $u =$	ω	Reduced ODE
$\langle \partial_x \rangle$	$\varphi(\omega)$	t	$\varphi' = 0$
$\langle \partial_t \rangle$	$\varphi(\omega)$	x	$(\varphi^\mu \varphi)' + \ln \varphi \varphi' = 0$
$\langle \partial_x + \epsilon \partial_t \rangle$	$\varphi(\omega)$	$x - \epsilon t$	$-\epsilon \varphi' = (\varphi^\mu \varphi)' + \ln \varphi \varphi'$
$\langle (\mu t + \epsilon) \partial_t \rangle$	$\varphi(\omega)(\mu t + \epsilon)^{1/\mu}$	$\frac{\mu^2 x + \epsilon}{\mu^2(\mu t + \epsilon)} + \frac{\ln \mu t + \epsilon }{\mu^2}$	$\frac{1}{\mu} \varphi - \mu \omega \varphi'$
$\langle (\mu x - t) \partial_x + u \partial_u \rangle$			$= (\varphi^\mu \varphi)' + \ln \varphi \varphi'$

If $u = f(t, x)$ is an exact solution of equation $u_t = (u^\mu u_x)_x + \ln uu_x$, then

$$u = e^{\epsilon_1} f(e^{\mu \epsilon_1} t + \epsilon_2, e^{\mu \epsilon_1} (x - \epsilon_1 t + \epsilon_3))$$

is also solution of the same equation.

In particular, if $\mu = 0$, we obtain $u_t = u_{xx} + \ln uu_x$. This equation has two known travelling wave solutions (usual and generalized ones):

$$u(t, x) = \exp(c_1 e^{-x+c_2 t} + 1 - c_2), \quad u(t, x) = \exp\left(\frac{c_1 - x}{t + c_2} + \frac{\ln |t + c_2|}{t + c_2}\right).$$

Generalized travelling wave solution are known for the following equations:

$$u_t = ((u^{2\mu} + bu^\mu)u_x)_x + u^\mu u_x, \quad u = \left(x\varphi(t) + c_1\varphi(t) + \frac{b}{n}\varphi(t) \int \varphi(t) dt\right)^{1/\mu}.$$

$$u_t = ((ae^{2u} + be^u)u_x)_x + e^u u_x, \quad u = \ln(x\varphi(t) + c_1\varphi(t) + b\varphi(t) \int \varphi(t) dt),$$

where $\varphi = \varphi(t)$ is determined by the equation $\varphi' = a\varphi^3 + \varphi^2$.

11. n -dimensional radially symmetric nonlinear diffusion equations

Class (1) contains a subclass of physically important n -dimensional radially symmetric nonlinear diffusion equations. Preserving the common terminology we use for them the notation

$$(20) \quad u_t = r^{1-n}(r^{n-1}A(u)u_r)_r.$$

Equations of the form (20), especially for power nonlinearity

$$(21) \quad u_t = r^{1-n}(r^{n-1}u^\mu u_r)_r.$$

have a large number of applications, for both $\mu > 0$ (slow diffusion) and $\mu < 0$ (fast diffusion).

To the best of our knowledge, first similar solutions of (20) were instantaneous source-type solutions [6, 47] namely, solutions of form

$$u = t^{-n/(\mu n+2)} f(\xi), \quad \xi = rt^{-1/(\mu n+2)}$$

if $\mu \neq -2/N$ and

$$u = e^{-\lambda nt} f(\xi), \quad \xi = re^{\lambda t},$$

where λ is an arbitrary constant, in case $\mu = -2/N$. Substituting these values into (21) yields (assuming $t > 0$ in the first three cases):

$$\begin{aligned} \mu > 0 : \quad u &= \begin{cases} t^{-\frac{n}{\mu n+2}} \left[\frac{\mu}{2(\mu n+2)} (a^2 - r^2 t^{-\frac{2}{\mu n+2}}) \right]^{\frac{1}{\mu}}, & r < at^{\frac{1}{\mu n+2}} \\ 0, & r \geq at^{\frac{1}{\mu n+2}} \end{cases}, \\ \mu = 0 : \quad u &= At^{-n/2} e^{-r^2/4t}, \\ 0 > \mu > -\frac{2}{n} : \quad u &= t^{-\frac{n}{\mu n+2}} \left[\frac{-\mu}{2(\mu n+2)} (a^2 + r^2 t^{-2/(\mu n+2)}) \right]^{\frac{1}{\mu}}, \\ \mu = -\frac{2}{n} : \quad u &= e^{-\lambda nt} \left[\frac{\lambda}{n} (a^2 + r^2 e^{-2\lambda t}) \right]^{-n/2}, \\ \mu < -\frac{2}{n} : \quad u &= \begin{cases} (-t)^{-\frac{n}{\mu n+2}} \left[\frac{\mu}{2(\mu n+2)} (a^2 + r^2 (-t)^{-\frac{2}{\mu n+2}}) \right]^{\frac{1}{\mu}}, & t < 0 \\ 0, & t \geq 0 \end{cases}. \end{aligned}$$

The following instantaneous source-type solutions for equations (21) were obtained by King [34]:

$$\text{Case } \mu = -1, n \neq -2: \quad f = (\mu n + 2) \exp\left(-\frac{\alpha \xi^{-2-n}}{2-n}\right) / \int \xi \exp\left(-\frac{\alpha \xi^{-2-n}}{2-n}\right) d\xi.$$

$$\text{Case } \mu = -1, n = 1: \quad f = 1/(\beta e^{-\alpha \xi} - \alpha^{-2}(\mu n + 2)^{-1}(1 + \alpha \xi)).$$

$$\begin{aligned} \text{Case } \mu = -1, n = 2: \quad f &= 1/(\beta \xi^\alpha + \xi^2(\mu n + 2)^{-1}(2 - \alpha)^{-1}), \text{ if } \alpha \neq 2 \text{ and} \\ f &= 1/(\beta \xi^2 + \xi^2(\mu n + 2)^{-1} \ln \xi), \text{ if } \alpha = 2. \end{aligned}$$

$$\text{Case } \mu = -1, n = 3: \quad f = 2/(2\beta e^{-\alpha/\xi} + (\xi(\alpha + \xi) + \alpha^{-2}e^{-\alpha/\xi} E_1(-\alpha/\xi))(\mu n + 2)^{-1}), \text{ where } E_1(z) = \int_z^\infty e^{-t} t^{-1} dt \text{ is the exponential integral.}$$

$$\text{Case } \mu = -2/n: \quad f = \xi^{-n} g, \text{ where } \int (ng - \alpha g^{2/n} - \lambda g^{1+2/n}) dg = \ln \xi.$$

Case $\mu = -1/2$:

$$\begin{aligned} f &= \alpha(\mu n + 2)\xi^{-n} \left(\beta J_{\nu-1} \left(\frac{\alpha^{1/2} \xi^{(4-n)/2}}{(\mu n + 2)^{1/2}(4-n)} \right) + \right. \\ &\quad \left. + (1 - \beta) Y_{\nu-1} \left(\frac{\alpha^{1/2} \xi^{(4-n)/2}}{(\mu n + 2)^{1/2}(4-n)} \right) \right)^2 \\ &\quad \times \left(\beta J_\nu \left(\frac{\alpha^{1/2} \xi^{(4-n)/2}}{(\mu n + 2)^{1/2}(4-n)} \right) + (1 - \beta) Y_\nu \left(\frac{\alpha^{1/2} \xi^{(4-n)/2}}{(\mu n + 2)^{1/2}(4-n)} \right) \right)^{-2}, \end{aligned}$$

where $\nu = 2/(4-n)$, $J_\nu(z)$ and $Y_\nu(z)$ are Bessel functions of the first and the second type correspondingly.

We now consider solutions [34] that generalize the one-dimensional dipole solutions given for $\mu > 0$ in [7]. The similarity variables are chosen to fix $\int_o^\infty r u dr$

in time (if the integral exists). In one dimension this corresponds to the centre of mass. The appropriate similarity solution to (21) then takes the form

$$\begin{aligned} u &= t^{-1/(\mu+1)} f(\xi), \quad \xi = rt^{-1/(2(\mu+1))}, \quad n \neq -1, \\ u &= e^{-2\lambda t} f(\xi), \quad \xi = re^{-\lambda t}, \quad n = -1. \end{aligned}$$

For different values n and μ the following solutions are known [7, 34]:

$$\text{Case } \mu \neq 0, -2/n: \quad f = \xi^{(2-n)/(\mu+1)} \left(\frac{n}{2(\mu n+2)} (\beta - \xi^{(\mu n+2)/(\mu+1)}) \right)^{1/n}.$$

$$\text{Case } \mu = 0: \quad f = \beta \xi^{2-n} e^{-\xi^2/4}.$$

$$\text{Case } \mu = -2/n: \quad f = \left(\frac{\xi^2}{n-2} \ln \frac{\xi}{\beta} \right)^{-n/2}.$$

Case $\mu = -1/2$: (here $\nu = 2 - n/2$)

$$\begin{aligned} f &= \frac{\alpha}{\xi^2} \left[\beta J_{\nu-1} \left(\frac{\alpha^{1/2} \xi}{2} \right) + (1 - \beta) Y_{\nu-1} \left(\frac{\alpha^{1/2} \xi}{2} \right) \right]^2 \times \\ &\quad \times \left[\beta J_{\nu} \left(\frac{\alpha^{1/2} \xi}{2} \right) + (1 - \beta) Y_{\nu} \left(\frac{\alpha^{1/2} \xi}{2} \right) \right]^{-2}. \end{aligned}$$

$$\begin{aligned} \text{Case } \mu = -1/2, n = 3 \text{ (cr [70]): } \quad f &= \frac{\alpha}{\xi^2} \tan^2 \left(\frac{\alpha^{1/2}}{2} (\xi - c) \right) \\ \text{or } f &= \frac{\alpha}{\xi^2} \tanh^2 \left(\frac{\alpha^{1/2}}{2} (\xi - c) \right). \end{aligned}$$

$$\begin{aligned} \text{Case } \mu = -1/2, n = 1: \quad f &= \frac{\alpha^2}{(2 - \alpha^{1/2} \xi \cot[\alpha^{1/2}(\xi - c)/2])^2} \\ \text{or } f &= \frac{\alpha^2}{(2 - \alpha^{1/2} \xi \coth[\alpha^{1/2}(\xi - c)/2])^2}. \end{aligned}$$

Case $\mu = n/2 - 2$: $f = \xi^{(2-n)/(\mu+1)} g$, where

$$\int \frac{g^{n/2-2}}{g + (n-2)\alpha} dg = -\frac{1}{(n-2)^2} \xi^{n-2}.$$

12. Variable coefficient diffusion–convection equations

To obtain invariant solutions of the variable coefficient diffusion–convection equations of form (1) two approaches were used. The first one is the direct finding of solutions invariant with respect to a subalgebra of the Lie invariance algebra, and the second one is reconstructing of new solutions from the known ones using equivalence transformations.

As an example of implementation of the first approach we adduce some of the invariant solutions of equation [24, 48].

$$(22) \quad |x|^p u_t = (|u|^\mu u_x)_x.$$

Namely,

$$u = |c_1x + c_0|^{1/(\mu+1)},$$

$$u = \left(\frac{-c_1\mu}{(p+2)(2+\mu+p+\mu p)} \right)^{1/\mu} (c_1t + c_0)^{-1/\mu} x^{(2+p)/\mu}$$

$$u = t^{(p+1)\beta} \left(\frac{\mu\beta}{2+p} x^{2+p} t^{(p+2)\beta} + c_0 \right)^{1/\mu}, \quad \text{where } \beta = -\frac{1}{p\mu + p + \mu + 2}.$$

For equation (22) with $p = -(\mu+2)/(\mu+1)$ solution obtained with multiplicative separation of variables is known:

$$u = e^{-c_1t} \left(c_1(\mu+1)^2 x^{\mu/(\mu+1)} e^{c_1\mu t} + c_2 \right)^{1/\mu}$$

See also the next two sections for invariant solutions of essentially variable coefficient equations.

Another possible way of finding exact solutions is based on application of equivalence transformations. The complete extended equivalence group \hat{G}^\sim of class (1) is formed by the transformations [27, 28]

$$\tilde{t} = \delta_1 t + \delta_2, \quad \tilde{x} = X(x), \quad \tilde{u} = \delta_3 u + \delta_4,$$

$$(23)$$

$$\tilde{f} = \frac{\varepsilon_1 \delta_1 \varphi}{X_x} f, \quad \tilde{g} = \varepsilon_1 \varepsilon_2^{-1} X_x \varphi g, \quad \tilde{h} = \varepsilon_1 \varepsilon_3^{-1} \varphi h, \quad \tilde{A} = \varepsilon_2 A, \quad \tilde{B} = \varepsilon_3 (B + \varepsilon_4 A),$$

where δ_j ($j = \overline{1,4}$) and ε_i ($i = \overline{1,4}$) are arbitrary constants, $\delta_1 \delta_3 \varepsilon_1 \varepsilon_2 \varepsilon_3 \neq 0$, X is an arbitrary smooth function of x , $X_x \neq 0$, $\varphi = e^{-\varepsilon_4 \int \frac{h(x)}{g(x)} dx}$.

It appears also, that class (1) contains equations being mutually equivalent with respect to point transformations which do not belong to this group. In particular, it is proved in [28, 31, 49] that if an equation of form (1) is invariant with respect to a Lie algebra of dimension not less than 4 then it can be reduced by point transformations to a constant coefficient diffusion-convection equation (18). All such equations and corresponding transformations were found in [28, 31, 49]. Some of them were known previously [41]. For the convenience of the readers we adduce the results of group classification up to the extended equivalence group (23) in Appendix A.

Up to equivalence transformations (23) the list of equations of form (1) reducible to the constant coefficient form together with corresponding transformations is exhausted by the following ones [28]:

1. $u_t = (e^u u_x)_x + \varepsilon x u_x \rightarrow (8): \quad \tilde{t} = e^{2\varepsilon t}/(2\varepsilon), \tilde{x} = x e^{\varepsilon t}, \tilde{u} = u;$
2. $x^{-3} u_t = (e^u u_x)_x \rightarrow (8): \quad \tilde{t} = t \operatorname{sign} x, \tilde{x} = 1/x, \tilde{u} = u - \ln|x|;$
3. $x^{-3} u_t = (e^u u_x)_x + x^{-2} u_x \rightarrow (8): \quad \tilde{t} = (e^{2t} t \operatorname{sign} x)/2, \tilde{x} = e^{-t}/x, \tilde{u} = u - t - \ln|x|;$
4. $u_t = (|u|^\mu u_x)_x + \varepsilon x u_x \rightarrow (9): \quad \tilde{t} = e^{2\varepsilon t}/(2\varepsilon), \tilde{x} = x e^{\varepsilon t}, \tilde{u} = u;$
5. $|x|^{-\frac{3\mu+4}{\mu+1}} u_t = (|u|^\mu u_x)_x \rightarrow (9): \quad \tilde{t} = t, \tilde{x} = -1/x, \tilde{u} = |x|^{-\frac{1}{1+\mu}} u;$
6. $|x|^{-\frac{3\mu+4}{\mu+1}} u_t = (|u|^\mu u_x)_x + \varepsilon x |x|^{-\frac{3\mu+4}{\mu+1}} u_x \Big|_{\mu \neq 2} \rightarrow (9): \quad \tilde{t} = \frac{\mu+1}{\varepsilon(\mu+2)} (1 - e^{-\varepsilon \frac{\mu+2}{\mu+1} t}),$
 $\tilde{x} = x e^{\varepsilon t}, \tilde{u} = u;$
7. $x^{-2} u_t = (u^{-2} u_x)_x + \varepsilon x^{-1} u_x \rightarrow (5): \quad \tilde{t} = t, \tilde{x} = x e^{\varepsilon t}, \tilde{u} = u;$

8. $e^x u_t = (u^{-1} u_x)_x \rightarrow (15)$: $\tilde{t} = t$, $\tilde{x} = x$, $\tilde{u} = e^x u$;
 9. $e^x u_t = (u^{-1} u_x)_x + \varepsilon e^x u_x \rightarrow (15)$: $\tilde{t} = e^{\varepsilon t}/\varepsilon$, $\tilde{x} = x + \varepsilon t$, $\tilde{u} = e^{x+\varepsilon t} u$.

Combining these transformations with symmetry and equivalence transformations one can easily obtain solutions of such “non-essentially variable coefficient” equations. For instance, starting from solutions of equation (8), we obtain corresponding solutions for the more complicated and interesting equation

$$\frac{e^x}{(\gamma e^x + 1)^3} u_t = (e^u u_x)_x + e^u u_x$$

having the density f localized in space [49]:

$$u = \ln |c_1 + c_0(e^{-x} + \gamma)|, \quad u = \ln \left(-\frac{1}{2t(e^{-x} + \gamma)} - \frac{c_1}{t} + c_0 \frac{e^{-x} + \gamma}{t} \right).$$

Similarly one can find exact solutions of equation

$$e^x u_t = (u^{-1} u_x)_x + \varepsilon e^x u_x$$

that is reducible to the fast diffusion equation [29]:

$$\begin{aligned} u &= \frac{e^{-(x+\varepsilon t)}}{1 + c e^{x+\varepsilon t + e^{\varepsilon t}/\varepsilon}}, & u &= \frac{\varepsilon e^{-(x+\varepsilon t)}}{\varepsilon x + \varepsilon^2 t - e^{\varepsilon t} \pm e^{\varepsilon t - \varepsilon(x+\varepsilon t)} e^{-\varepsilon t}}, \\ u &= \frac{2e^{-x}}{\varepsilon(x + \varepsilon t)^2 \pm e^{2\varepsilon t}}, & u &= \frac{2e^{-x}}{\varepsilon \cos^2(x + \varepsilon t)}, & u &= -\frac{2e^{-x}}{\varepsilon \cosh^2(x + \varepsilon t)}, \\ u &= \frac{2e^{-x}}{\varepsilon \sin^2(x + \varepsilon t)}, & u &= \frac{2e^{-(x+\varepsilon t)} \sin(2e^{\varepsilon t}/\varepsilon)}{\cos(2e^{\varepsilon t}/\varepsilon) - \cos 2(x + \varepsilon t)}, \\ u &= \frac{2e^{-(x+\varepsilon t)} \sinh(2e^{\varepsilon t}/\varepsilon)}{\cosh 2(x + \varepsilon t) - \cosh(2e^{\varepsilon t}/\varepsilon)}, & u &= -\frac{2e^{-(x+\varepsilon t)} \sinh(2e^{\varepsilon t}/\varepsilon)}{\cosh 2(x + \varepsilon t) + \cosh(2e^{\varepsilon t}/\varepsilon)}, \\ u &= \frac{2e^{-(x+\varepsilon t)} \cosh(2e^{\varepsilon t}/\varepsilon)}{\sinh 2(x + \varepsilon t) - \sinh(2e^{\varepsilon t}/\varepsilon)}, & u &= \frac{2e^{-(x+\varepsilon t)} \sin(2e^{\varepsilon t}/\varepsilon)}{\cosh 2(x + \varepsilon t) - \cos(2e^{\varepsilon t}/\varepsilon)}, \\ u &= \frac{2e^{-(x+\varepsilon t)} \sinh(2e^{\varepsilon t}/\varepsilon)}{\cosh(2e^{\varepsilon t}/\varepsilon) - \cos 2(x + \varepsilon t)}. \end{aligned}$$

Using the same approach we constructed exact solutions for the following equations [29, 31, 49]:

$$e^{-2x + \gamma e^{-x}} u_t = (u^{-1} u_x)_x + u^{-1} u_x :$$

$$\begin{aligned} u &= c_0 e^{(c_1 - \gamma)e^{-x}}, & u &= \frac{2c_1^2 t e^{-\gamma e^{-x}}}{\cos^2 c_1(e^{-x} + c_0)}, & u &= \frac{2tc_0 c_1^2 e^{(c_1 - \gamma)e^{-x}}}{(1 - c_0 e^{c_1 e^{-x}})^2}, \\ u &= \frac{c_1 e^{-\gamma e^{-x}}}{-\varepsilon + c_0 e^{c_1(e^{-x} - \varepsilon t)}}, & u &= \frac{\varepsilon e^{-\gamma e^{-x}}}{e^{-x} - \varepsilon t + c_0}, & u &= \frac{2te^{-\gamma e^{-x}}}{(e^{-x} + c_1)^2 + c_0 t^2}. \end{aligned}$$

Equation

$$\frac{e^{-2x}}{(e^{-x} + \gamma)^{\frac{4+3\mu}{1+\mu}}} u_t = (u^\mu u_x)_x + u^\mu u_x$$

has exact solutions of the form

$$\begin{aligned}
 u &= |c_0(e^{-x} + \gamma) - c_1|^{\frac{1}{\mu+1}}, \quad u = \left(c_0 + \frac{\varepsilon\mu}{e^{-x} + \gamma} + \varepsilon^2\mu t \right)^{\frac{1}{\mu}} |e^{-x} + \gamma|^{-\frac{1}{\mu+1}}, \\
 u &= \left(-\frac{\mu}{\mu+2} \frac{1}{2t} \left(c_0 - \frac{1}{e^{-x} + \gamma} \right)^2 + c_1 |t|^{-\frac{\mu}{\mu+2}} \right)^{\frac{1}{\mu}} |e^{-x} + \gamma|^{-\frac{1}{\mu+1}}, \\
 u &= \left(-\frac{\mu}{\mu+2} \frac{1}{2t} \left(c_0 - \frac{1}{e^{-x} + \gamma} \right)^2 + \right. \\
 &\quad \left. + c_1 \left(c_0 - \frac{1}{e^{-x} + \gamma} \right)^{\frac{\mu}{\mu+1}} |t|^{-\frac{\mu(2\mu+3)}{2(\mu+1)^2}} \right)^{\frac{1}{\mu}} |e^{-x} + \gamma|^{-\frac{1}{\mu+1}}, \\
 u &= (6t + c'_1 + c_2 e^{-x})^2 (e^{-x} + \gamma)^6.
 \end{aligned}$$

$$e^x u_t = (u^{-1} u_x)_x + \mu e^x u_x$$

admits the following invariant exact solutions:

$$\begin{aligned}
 u &= \frac{c_0}{\mu} e^{(1-c_1)(x+\mu t)}, \quad u = \frac{2c_1^2}{\mu} \frac{e^{-x}}{\cos^2[c_1(x + \mu t + c_0)]}, \\
 u &= \frac{2c_0c_1^2}{\mu} \frac{e^{(c_1-1)x+c_1\mu t}}{[1 - c_0e^{c_1(x+\mu t)}]^2}, \quad u = \frac{c_1}{\mu} \frac{e^{-(x+\mu t)}}{c_2 + c_0e^{c_1(x+\mu t+c_2e^{\mu t})}}, \\
 u &= \frac{2}{\mu} \frac{e^{-x}}{(x + \mu t + c_1)^2 + c_0e^{2\mu t}}, \quad u = \frac{1}{\mu} \frac{e^{-(x+\mu t)}}{x + \mu t - e^{\mu t} + c_0}.
 \end{aligned}$$

$$f(x)u_t = (u^{-1}u_x)_x - \left(\frac{f_x}{2f} - \frac{\sqrt{f}}{\int \sqrt{f} dx} \right) u^{-1}u_x,$$

where $f = f(x)$ is an arbitrary positive function has the following invariant solutions:

$$\begin{aligned}
 u &= c_0 \left(\int \sqrt{f} dx \right)^{c_1-2}, \quad u = \frac{2c_1^2 t \left(\int \sqrt{f} dx \right)^{-2}}{\cos^2[c_1(\ln \int \sqrt{f} dx + c_0)]}, \\
 u &= \frac{2c_0c_1^2 t \left(\int \sqrt{f} dx \right)^{c_1-2}}{[1 - c_0 \left(\int \sqrt{f} dx \right)^{c_1}]^2}, \quad u = \frac{c_1 \left(\int \sqrt{f} dx \right)^{-2}}{c_2 + c_0 \left(\int \sqrt{f} dx \right)^{c_1} e^{c_1 c_2 t}}, \\
 u &= \frac{\left(\int \sqrt{f} dx \right)^{-2}}{\ln \left(\int \sqrt{f} dx \right) - t + c_0}, \quad u = \frac{2t \left(\int \sqrt{f} dx \right)^{-2}}{[\ln \left(\int \sqrt{f} dx \right) + c_1]^2 + c_0 t^2}.
 \end{aligned}$$

$$u_t = (u^{-1}u_x)_x + \mu x u_x$$

admits the following solutions:

$$\begin{aligned}
 u &= c_0 e^{c_1 x e^{\mu t}}, \quad u = \frac{c_1^2 e^{2\mu t}}{\mu \cos^2[c_1(xe^{\mu x} + c_0)]}, \quad u = \frac{c_0 c_1^2 e^{(2\mu t + c_1 x e^{\mu t})}}{\mu (1 - c_0 e^{c_1 x e^{\mu t}})^2}, \\
 u &= \frac{c_1}{c_2 + c_0 e^{c_1(xe^{\mu t} + \frac{c_2}{2\mu} e^{2\mu t})}}, \quad u = \frac{2\mu}{2\mu x e^{\mu t} - e^{2\mu t} + 2\mu c_0}, \\
 u &= \frac{4\mu e^{2\mu t}}{4\mu^2(xe^{\mu t} + c_1)^2 + c_0 e^{4\mu t}}.
 \end{aligned}$$

See [28, 29, 31, 49] for more detail and more examples. Since the solutions of these equations can be reconstructed from ones presented in other sections, we turn back to the more interesting cases, in particular, to the equations which are “essentially variable coefficient”.

13. Examples of Lie reduction of variable coefficient equation

The results of this section have been obtained in [29, 31].

In this section we consider Lie reductions of some variable coefficient equations of form (1). We start from the equation

$$(24) \quad e^{px} u_t = [e^u u_x]_x + e^{px} u_x$$

which admits three-dimensional Lie algebra $Q_1 = -p^{-1}\partial_t$, $Q_2 = e^{-pt}(\partial_t - \partial_x)$, $Q_3 = \partial_x + p\partial_u$. The only non-zero commutators of these operators are $[Q_1, Q_2] = Q_2$. Therefore A^{\max} is a realization of the algebra $2A_{2.1}$ [40]. All the possible inequivalent (with respect to inner automorphisms) one-dimensional subalgebras of $A_{2.1} \oplus A_1$ [46] are exhausted by the ones listed in Table 11 along with the corresponding ansätze and the reduced odes.

Table 11. Reduced odes for (24). $\lambda \neq 0$, $\varepsilon = \pm 1$

N	Subalgebra	Ansatz $u =$	ω	Reduced ODE
1	Q_1	$\varphi(\omega)$	x	$(e^\varphi \varphi')' + e^{px} \varphi' = 0$
2	Q_2	$\varphi(\omega)$	$t + x$	$(e^\varphi \varphi')' = 0$
3	Q_3	$\varphi(\omega) + px$	t	$\varphi' = p^2 e^\varphi + p$
4	$Q_1 + \lambda Q_3$	$\varphi(\omega) + \lambda pt$	$x - \lambda t$	$e^\omega [\lambda p - (\lambda + 1)\varphi'] = (e^\varphi \varphi)'$
5	$Q_2 + \varepsilon Q_3$	$\varphi(\omega) + \varepsilon e^{pt}$	$x + t - \frac{\varepsilon}{p} e^{pt}$	$e^{p\omega} \varepsilon (p - \varphi') = (e^\varphi \varphi)'$

As a second example we consider the equation

$$(25) \quad x^p u_t = [u^m u_x]_x + x^{p+1} u_x.$$

The invariance algebra of (25) is generated by the operators $Q_1 = -(p+2)^{-1}\partial_t$, $Q_2 = e^{-(p+2)t}(\partial_t - x\partial_x)$, $Q_3 = mx\partial_x + (p+2)u\partial_u$ and is a realization of the algebra $A_{2.1} \oplus A_1$ too. The reduced equations for (25) are listed in table 12.

Table 12. Reduced odes for (25). $\lambda \neq 0$, $\varepsilon = \pm 1$

N	Subalgebra	Ansatz $u =$	ω	Reduced ODE
1	Q_1	$\varphi(\omega)$	x	$(\varphi^m \varphi')' + x^{p+1} \varphi' = 0$
2	Q_2	$\varphi(\omega)$	$x e^t$	$(\varphi^m \varphi')' = 0$
3	Q_3	$x \frac{p+2}{m} \varphi(\omega)$	t	$\varphi' = \frac{(p+2)(p+2+m)}{m^2} \varphi^{m+1} + \frac{p+2}{m} \varphi$
4	$Q_1 + \lambda Q_3$	$e^{\lambda(p+2)t} \varphi(\omega)$	$x e^{-\lambda m t}$	$(\varphi^m \varphi')' + (1 + \lambda m) \omega^{p+1} \varphi' = \lambda(p+2) \omega^p \varphi$
5	$Q_2 + \varepsilon Q_3$	$e^{\varepsilon e^{(p+2)t}} \varphi(\omega)$	$x e^{t - \frac{m\varepsilon}{p+2} e^{(p+2)t}}$	$(\varphi^m \varphi')' = \varepsilon(p+2) \omega^p \varphi - m\varepsilon \omega^{p+1} \varphi'$

At last, let us analyze in more detail equation

$$(26) \quad e^{px^2} u_t = (e^{px^2} u_x)_x + e^{px^2} u u_x,$$

which is invariant with respect to three-dimensional Lie symmetry algebra

$$\langle \partial_t, e^{-2pt} \partial_x, \partial_x - 2p\partial_u \rangle.$$

In contrast to the case of equations with four-dimensional Lie symmetry algebra we cannot reduce equation (26) to a constant coefficient equation of form (1). However, it is an interesting feature of this equation that using a point transformation $v =$

$u + 2px$ it can be mapped to a constant coefficient reaction-convection-diffusion equation

$$(27) \quad v_t = v_{xx} + vv_x - 2pv$$

that does not belong to class (1). For simplification of the technical calculations we will investigate the constant coefficient equation (27) instead of (26). The Lie symmetry algebra of equation (27)

$$\langle X_1 = \partial_t, X_2 = e^{-2pt}(\partial_x + 2p\partial_v), X_3 = \partial_x \rangle$$

is a realization of $A_{2,1} \oplus A_1$ [40]. These operators generate the following group of point transformations:

$$\tilde{t} = t + \varepsilon_1, \quad \tilde{x} = x + \varepsilon_2 e^{-2pt} + \varepsilon_3, \quad \tilde{v} = v + 2\varepsilon_2 p e^{-2pt}.$$

A list of proper inequivalent subalgebras of the given algebra is exhausted by the following ones

$$\langle X_1 + \alpha X_3 \rangle, \quad \langle X_3 + \varepsilon X_2 \rangle, \quad \langle X_2 \rangle, \quad \langle X_1, X_3 \rangle, \quad \langle X_2, X_3 \rangle, \quad \langle X_1 + \beta X_3, X_2 \rangle,$$

where α and β are arbitrary constants, $\varepsilon = 0, \pm 1$ [46].

The first three (one-dimensional) subalgebras lead to Lie reductions to ordinary differential equations, the fourth and sixth (two-dimensional) ones yield reductions to algebraic equations. Lie reductions with respect to these subalgebras are summarized in Table 13. One can easily check that it is impossible to construct a Lie ansatz corresponding to the subalgebra $\langle X_2, X_3 \rangle$.

Table 13. Lie reductions of equation (27).

N	Subalgebra	Ansatz $v =$	ω	Reduced equation
1	$\langle X_1 + \alpha X_3 \rangle$	$\varphi(\omega)$	$x - \alpha t$	$\varphi'' + (\varphi + \alpha)\varphi' - 2p\varphi = 0$
2	$\langle X_3 + \varepsilon X_2 \rangle$	$\varphi(\omega) + \frac{2p\varepsilon x}{e^{2pt} + \varepsilon}$	t	$\varphi' = \frac{2pe^{2p\omega}}{e^{2p\omega} + \varepsilon} \varphi$
3	$\langle X_2 \rangle$	$\varphi(\omega) + 2px$	t	$\varphi' = 0$
4	$\langle X_1, X_3 \rangle$	C	—	$C = 0$
5	$\langle X_1 + \beta X_3, X_2 \rangle$	$2px - 2p\beta t + C$	—	$-2p\beta = 0$

Integration of equations 2–5 from Table 13 give the following invariant solutions of equation (27):

$$v = 0, \quad v = 2px + C, \quad v = \frac{2p\varepsilon x + Ce^{2pt}}{e^{2pt} + \varepsilon}.$$

The corresponding exact invariant solutions of equation (26) have the form

$$(28) \quad u = -2px, \quad u = C, \quad u = \frac{2p\varepsilon x + Ce^{2pt}}{e^{2pt} + \varepsilon} - 2px,$$

where C is an arbitrary constant.

Ansatzes 4.2 and 4.3 give a hint for a possible form

$$v = \varphi(t)x + \psi(t)$$

of nonlinear separation of variables for construction of exact solutions of equation (27). Substitution of the ansatz to equation (27) leads to antireduction:

$$\varphi' = \varphi^2 - 2p\varphi, \quad \psi' = \varphi\psi - 2p\psi.$$

Solving the above system of ODEs for φ and ψ we obtain exactly the solutions of equations 4.2 and 4.3.

NOTE 1. Using the point transformation $\tilde{t} = e^{-2pt}$, $\tilde{x} = x$, $\tilde{v} = e^{2pt}v$ equation (27) can be mapped to a variable coefficient Burgers equation $\tilde{v}_{\tilde{t}} = -2p\tilde{t}^{-1}\tilde{v}_{\tilde{x}\tilde{x}} - 2p\tilde{v}_{\tilde{x}}$ studied in [37].

NOTE 2. The well-known Cole–Hopf transformation $v = 2w_x/w$ reduces equation (27) to the famous constant coefficient reaction–diffusion equation with weak nonlinearity

$$w_t = w_{xx} - 2pw \ln |w|.$$

After application of the Cole–Hopf transformation to the list of known exact solutions (see, e.g., [48]) of the equation with weak nonlinearity we obtain exactly solutions (28) of equation (27).

14. Exact solutions of $sl(2, \mathbb{R})$ -invariant equation

Analyzing the results of group classification of diffusion–convection equations, we can observe a number of \hat{G}^{\sim} -inequivalent equations (1) which are invariant with respect to different realizations of the algebra $sl(2, \mathbb{R})$. The set of such equations is practically exhausted by the well-known (“constant coefficient”) Burgers and $u^{-4/3}$ -diffusion equations and by the equations which are equivalent to them with respect to additional transformations. This set is supplemented by the unique essentially variable coefficient equation [28, 31]

$$(29) \quad x^2 u_t = (u^{-6/5} u_x)_x + x^2 u_x,$$

$sl(2, \mathbb{R})$ -invariance of (29) is directly connected with the fact that h is not constant. The corresponding realization

$$P_t = \partial_t, \quad D = 2t\partial_t + 2x\partial_x - 5u\partial_u, \quad \Pi = t^2\partial_t + (2tx + x^2)\partial_x - 5(t+x)u\partial_u.$$

of the algebra $sl(2, \mathbb{R})$ is quite different from ones of cases of Burgers and $u^{-4/3}$ -diffusion equations and is the maximal Lie invariance algebra of equation (29). It was a reason to study equation (29) from the symmetry point of view in detail in [29]. These operators generate the following one-parameter groups of point transformations:

$$\begin{aligned} P_t: \quad & \tilde{t} = t + \varepsilon, \quad \tilde{x} = x, \quad \tilde{u} = u; \\ D: \quad & \tilde{t} = e^\varepsilon t, \quad \tilde{x} = e^\varepsilon x, \quad \tilde{v} = e^{3\varepsilon} v; \\ \Pi: \quad & \tilde{t} = \frac{t}{1 - \varepsilon t}, \quad \tilde{x} = \frac{t+x}{1 - \varepsilon(t+x)} - \frac{t}{1 - \varepsilon t}, \quad \tilde{u} = (1 - \varepsilon(t+x))^6 u. \end{aligned}$$

The complete Lie invariance group G^{\max} is generated by both the above continuous transformations and the discrete transformation of changing of sign in the triple (t, x, u) . The transformations from G^{\max} can be used for construction of new solutions from known ones.

A list of proper G^{\max} -inequivalent subalgebras of A^{\max} is exhausted by the algebras $\langle P_t \rangle$, $\langle D \rangle$, $\langle P_t + \Pi \rangle$, $\langle P_t, D \rangle$. Reduction of (29) with respect to these subalgebras and application of the invariance transformations lead to the following

set of G^{\max} -inequivalent Lie invariant exact solutions (below $\delta \in \{0, 1\}$):

$$\begin{aligned} u &= C(t+x)^{-5}, \quad u = 2^{-5/6} \left(\frac{x}{t}\right)^{-5/2} (t+x)^{-5/2}, \\ u &= \left(\frac{3x^4}{4t} \frac{(t+x)^2}{Ct-1} + 2\frac{x^3}{t^3}(t+x)^3\right)^{-5/6}, \\ u &= x^{-5/6} \left(\frac{(t+x)^2}{Ct+1}\right)^{-5/6} \left(\frac{5x^3}{4t^3} + 2\frac{x^2}{t^2}(C(t+x)+1)\right)^{-5/6}. \end{aligned}$$

In [29] it was proposed to use functional separation of variables

$$(30) \quad u = \left(\sum_{i=0}^6 \varphi^i(t)x^i\right)^{-5/6}.$$

to obtain solutions of equation (29). The set of all solutions of the form (30) is closed with respect to transformations from G^{\max} and is exhausted, up to translations with respect to t and scale transformations, by the above solutions $u = \delta$ and $u = \delta(t+x)^{-5}$ and the solutions given by the generalized ansatz

$$(31) \quad u = (2x^3 + \varphi^4(t)x^4 + \varphi^5(t)x^5 + \varphi^6(t)x^6)^{-5/6}$$

and the corresponding reduced system

$$(32) \quad \varphi_t^4 = 7\varphi^5 - \frac{4}{3}(\varphi^4)^2, \quad \varphi_t^5 = 18\varphi^6 - \frac{4}{3}\varphi^4\varphi^5, \quad \varphi_t^6 = -\frac{5}{6}(\varphi^5)^2 + 2\varphi^4\varphi^6.$$

System (32) can be reduced to the single third-order ordinary differential equation on the function φ^4 :

$$63\varphi_{ttt}^4 + 387(\varphi_t^4)^2 + 126\varphi^4\varphi_{tt}^4 + 192(\varphi^4)^2\varphi_t^4 + 16(\varphi^4)^4 = 0$$

having particular solutions $\varphi^4 = 0$, $\varphi^4 = C/t$, where $C \in \{0, 3/4, 21/4, 6\}$, that lead to Lie invariant solutions of (29).

Conclusive remarks. This work is constantly under updating. So, the author will appreciate any suggestions, comments and references sent to the e-mail ivanova@imath.kiev.ua.

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Appendix A. Group classification of diffusion-convection equations

Table 14. Case of $\forall A(u), g = 1$

N	$B(u)$	$f(x)$	$h(x)$	Basis of A^{\max}
1	\forall	\forall	\forall	∂_t
2a	\forall	e^{px}	1	$\partial_t, pt\partial_t + \partial_x$
2a'	\forall	$ x ^p$	x^{-1}	$\partial_t, (p+2)t\partial_t + x\partial_x$
2b	1	e^x	$e^x + \beta$	$\partial_t, e^{-t}(\partial_t - \partial_x)$
2c	1	$ x ^p$	$x x ^p + \beta x^{-1}$	$\partial_t, e^{-(p+2)t}(\partial_t - x\partial_x)$
3	1	x^{-2}	$x^{-1} \ln x $	$\partial_t, e^{-t}x\partial_x$
4	0	1	1	$\partial_t, \partial_x, 2t\partial_t + x\partial_x$

Here $p \in \{0, 1\} \bmod G_1^\sim$ in case 2; $p \neq -2$ in case 2c; $\beta \in \{0, \pm 1\}$ in case 2b. Additional equivalence transformations:

1. $2a(p = 0, B = 1) \rightarrow 2a(p = 0, B = 0)$: $\tilde{t} = t, \tilde{x} = x + t, \tilde{u} = u$;
- 1'. $2a'(p = -2, B = 1) \rightarrow 2a'(p = -2, B = 0)$: $\tilde{t} = t, \tilde{x} = xe^t, \tilde{u} = u$;
2. $2b \rightarrow 2a(B = \beta, p = 1)$: $\tilde{t} = e^t, \tilde{x} = x + t, \tilde{u} = u$;
3. $2c(p \neq -2) \rightarrow 2'a(p \neq -2)$: $\tilde{t} = (e^{(p+2)t} - 1)/(p+2), \tilde{x} = xe^t, \tilde{u} = u$.

Table 15. Case of $A(u) = e^{\mu u}$

N	$B(u)$	$f(x)$	$g(x)$	$h(x)$	Basis of A^{\max}
1	0	\forall	1	1	$\partial_t, t\partial_t - \partial_u$
2	$e^{\nu u}$	$ x ^p$	1	$ x ^q$	$\partial_t, p\mu - p\nu - 2\nu - q\mu + \mu)t\partial_t + ((\mu - \nu)x\partial_x + (q+1)\partial_u)$
2*	$e^{\nu u}$	e^{px}	1	εe^x	$\partial_t, (p\mu - p\nu - \mu)t\partial_t + (\mu - \nu)\partial_x + \partial_u$
3	ue^u	e^{px^2+qx}	e^{px^2}	e^{px^2}	$\partial_t, (2p+q)t\partial_t + \partial_x - 2p\partial_u$
4	$e^{\nu u} + \varkappa$	1	1	1	$\partial_t, \partial_x, (\mu - 2\nu)t\partial_t + ((\mu - \nu)x + \nu\varkappa t)\partial_x + \partial_u$
5	u	1	1	1	$\partial_t, \partial_x, t\partial_t + (x - t)\partial_x + \partial_u$
6a	0	$f^1(x)$	1	1	$\partial_t, t\partial_t - \partial_u, \alpha t\partial_t + (\beta x^2 + \gamma_1 x + \gamma_0)\partial_x + \beta x\partial_u$
6b	1	$ x ^p$	1	$\varepsilon x x ^p$	$\partial_t, x\partial_x + (p+2)\partial_u, e^{-\varepsilon(p+2)t}(\partial_t - \varepsilon x\partial_x)$
6b*	1	e^x	1	εe^x	$\partial_t, \partial_x + \partial_u, e^{-\varepsilon t}(\partial_t - \varepsilon\partial_x)$
6c	1	x^{-2}	1	εx^{-1}	$\partial_t, x\partial_x, t\partial_t - \varepsilon t x\partial_x - \partial_u$
7a	0	1	1	1	$\partial_t, t\partial_t - \partial_u, 2t\partial_t + x\partial_x, \partial_x$
7b	1	1	1	1	$\partial_t, \partial_x, t\partial_t - t\partial_x - \partial_u, 2t\partial_t + (x - t)\partial_x$
7c	1	1	1	εx	$\partial_t, x\partial_x + 2\partial_u, e^{-\varepsilon t}\partial_x, e^{-2\varepsilon t}(\partial_t - \varepsilon x\partial_x)$
7d	0	x^{-3}	1	1	$\partial_t, t\partial_t - \partial_u, x\partial_x - \partial_u, x^2\partial_x + x\partial_u$
7e	1	x^{-3}	1	x^{-2}	$\partial_t, x\partial_x - \partial_u, e^t(\partial_t - x\partial_x), e^t(x^2\partial_x + x\partial_u)$

Here $(\mu, \nu) \in \{(0, 1), (1, \nu)\}, \nu \neq \mu$ in cases 2, 2* and 4; $\mu = 1$ and $\nu \neq 1$ in the other cases; $q \neq -1$ in case 2* (otherwise it is subcase of the case 1.2a'); $\varepsilon = \pm 1$ in cases 2, 6b-6c and 7e; $p \notin \{-3, -2, 0\}$ in case 6b; $\alpha, \beta, \gamma_1, \gamma_0 = \text{const}$ and

$$f^1(x) = \exp \left\{ \int \frac{-3\beta x - 2\gamma_1 + \alpha}{\beta x^2 + \gamma_1 x + \gamma_0} dx \right\}.$$

Case 2($q = -1$) is a subcase of case 1.2a'. Additional equivalence transformations:

1. $4(\varkappa \neq 0) \rightarrow 4(\varkappa = 0)$: $\tilde{t} = t, \tilde{x} = x + \varkappa t, \tilde{u} = u$;
2. $6b \rightarrow 6a (\beta = \gamma_0 = 0, \alpha = (p+2)\gamma_1)$: $\tilde{t} = (e^{\varepsilon(p+2)t} - 1)/(\varepsilon(p+2)), \tilde{x} = xe^{\varepsilon t}, \tilde{u} = u$;
3. $6b^* \rightarrow 6a (\beta = \gamma_1 = 0, \alpha = \gamma_0)$: $\tilde{t} = e^{\varepsilon t}/\varepsilon, \tilde{x} = x + \varepsilon t, \tilde{u} = u$;

4. 6c \rightarrow 6a ($\beta = \gamma_0 = \alpha = 0$): $\tilde{t} = t$, $\tilde{x} = xe^{\varepsilon t}$, $\tilde{u} = u$;
 5. 7b \rightarrow 7a: $\tilde{t} = t$, $\tilde{x} = x + t$, $\tilde{u} = u$;
 6. 7c \rightarrow 7a: $\tilde{t} = e^{2\varepsilon t}/(2\varepsilon)$, $\tilde{x} = xe^{\varepsilon t}$, $\tilde{u} = u$;
 7. 7d \rightarrow 7a: $\tilde{t} = t \operatorname{sign} x$, $\tilde{x} = 1/x$, $\tilde{u} = u - \ln|x|$;
 8. 7e \rightarrow 7a: $\tilde{t} = (e^{2t} t \operatorname{sign} x)/2$, $\tilde{x} = e^{-t}/x$, $\tilde{u} = u - t - \ln|x|$.

Table 16. Case of $A(u) = |u|^\mu$

N	μ	$B(u)$	$f(x)$	$g(x)$	$h(x)$	Basis of Λ^{\max}
1	\forall	0	\forall	1	1	$\partial_t, \mu t \partial_t - u \partial_u$
2	\forall	$ u ^\nu$	$ x ^p$	1	$ x ^q$	$\partial_t, (\mu + p\mu - q\mu - p\nu - 2\nu)t\partial_t$ $+ (\mu - \nu)x\partial_x + (q + 1)u\partial_u$
2*	\forall	$ u ^\nu$	e^{px}	1	εe^x	$\partial_t, (p\mu - p\nu - \mu)t\partial_t + (\mu - \nu)\partial_x + u\partial_u$
3	\forall	$ u ^\mu \ln u $	e^{px^2+qx}	e^{px^2}	e^{px^2}	$\partial_t, (2\mu p + q)t\partial_t + \partial_x - 2pu\partial_u$
4	\forall	1	f^2	1	$\varepsilon x f^2$	$\partial_t,$ $e^{\varepsilon t}(\partial_t - \varepsilon((\mu + 1)\beta x^2 + x)\partial_x - \varepsilon\beta x u \partial_u)$
5	0	\forall	e^{px^2}	e^{px^2}	e^{px^2}	$\partial_t, e^{-2pt}\partial_x$
6	0	\forall	$e^{x+\gamma e^x}$	$e^{\gamma e^x}$	$e^{\gamma e^x}$	$\partial_t, e^{-\gamma t}(\partial_t - \gamma\partial_x)$
7	0	u	e^{px^2+x}	e^{px^2}	e^{px^2}	$\partial_t, t\partial_t + \partial_x - 2p\partial_u$
8	\forall	$ u ^\nu + \varkappa$	1	1	1	$\partial_t, \partial_x,$ $(\mu - 2\nu)t\partial_t + ((\mu - \nu)x + \nu\varkappa)\partial_x + u\partial_u$
9	\forall	$\ln u $	1	1	1	$\partial_t, \partial_x, \mu t \partial_t + (\mu x - t)\partial_x + u\partial_u$
10	0	u	e^{px^2}	e^{px^2}	e^{px^2}	$\partial_t, e^{-2pt}\partial_x, \partial_x - 2p\partial_u$
11	0	$\ln u $	e^{px^2}	e^{px^2}	e^{px^2}	$\partial_t, e^{-2pt}\partial_x, \partial_x - 2pu\partial_u$
12a	\forall	0	f^3	1	1	$\partial_t, \mu t \partial_t - u \partial_u, \alpha t \partial_t$ $+ ((\mu + 1)\beta x^2 + \gamma_1 x + \gamma_0)\partial_x + \beta x u \partial_u$
12b	\forall	1	$ x ^p$	1	$\varepsilon x x ^p$	$\partial_t, \mu x \partial_x + (p + 2)u \partial_u,$ $e^{-\varepsilon(p+2)t}(\partial_t - \varepsilon x \partial_x)$
12b*	$\neq -1$	1	e^x	1	εe^x	$\partial_t, \mu \partial_x + u \partial_u, e^{-\varepsilon t}(\partial_t - \varepsilon \partial_x)$
12c	$\neq -2$	1	x^{-2}	1	εx^{-1}	$\partial_t, x \partial_x, \mu t \partial_t - \varepsilon \mu t x \partial_x - u \partial_u$
13	$-\frac{6}{5}$	1	x^2	1	x^2	$\partial_t, 2t\partial_t + 2x\partial_x - 5u\partial_u,$ $t^2\partial_t + (2tx + x^2)\partial_x - 5(t+x)u\partial_u$
14a	$\neq -\frac{4}{3}$	0	1	1	1	$\partial_t, \mu t \partial_t - u \partial_u, \partial_x, 2t\partial_t + x\partial_x$
14b	$\neq -\frac{4}{3}$	1	1	1	1	$\partial_t, \mu t \partial_t - \mu t \partial_x - u \partial_u, \partial_x,$ $2t\partial_t + (x - t)\partial_x$
14c	$\neq -\frac{4}{3}$	1	1	1	εx	$\partial_t, \mu x \partial_x + 2u \partial_u, e^{-\varepsilon t} \partial_x,$ $e^{-2\varepsilon t}(\partial_t - \varepsilon x \partial_x)$

Table 16. Continuation

N	μ	$B(u)$	$f(x)$	$g(x)$	$h(x)$	Basis of A^{\max}
14d	$\neq -\frac{4}{3}, -1$	0	$ x ^{s(\mu)}$	1	1	$\partial_t, \mu t \partial_t - u \partial_u, (\mu + 2)t \partial_t - (\mu + 1)x \partial_x, (\mu + 1)x^2 \partial_x + xu \partial_u$
14e	$\neq -2, -\frac{4}{3}, -1$	1	$ x ^{s(\mu)}$	1	$\varepsilon x x ^{s(\mu)}$	$\partial_t, \mu(\mu + 1)x \partial_x - (\mu + 2)u \partial_u, e^{\varepsilon \frac{\mu+2}{\mu+1}t}(\partial_t - \varepsilon x \partial_x), e^{\varepsilon t}((\mu + 1)x^2 \partial_x + xu \partial_u)$
14f	-1	0	e^x	1	1	$\partial_t, t \partial_t + u \partial_u, \partial_x - u \partial_u, 2t \partial_t + x \partial_x - xu \partial_u$
14g	-1	1	e^x	1	εe^x	$\partial_t, \partial_x - u \partial_u, e^{-\varepsilon t}(\partial_t - \varepsilon \partial_x), (x + \varepsilon t - 2)\partial_x - (x + \varepsilon t)u \partial_u$
14h	-2	1	x^{-2}	1	εx^{-1}	$\partial_t, x \partial_x, 2t \partial_t - 2\varepsilon t x \partial_x + u \partial_u, e^{\varepsilon t}(x^2 \partial_x - xu \partial_u)$
15a	$-\frac{4}{3}$	0	1	1	1	$\partial_t, 4t \partial_t + 3u \partial_u, \partial_x, 2t \partial_t + x \partial_x, x^2 \partial_x - 3xu \partial_u$
15b	$-\frac{4}{3}$	1	1	1	1	$\partial_t, 4t \partial_t + 4x \partial_x - 3u \partial_u, 2t \partial_t + (x - t)\partial_x, \partial_x, (x + t)^2 \partial_x - 3(x + t)u \partial_u$
15c	$-\frac{4}{3}$	1	1	1	εx	$\partial_t, 2x \partial_x - 3u \partial_u, e^{-\varepsilon t} \partial_x, e^{-2\varepsilon t}(\partial_t - \varepsilon x \partial_x), e^{\varepsilon t}(x^2 \partial_x - 3xu \partial_u)$
16	0	u	1	1	1	$\partial_t, \partial_x, t \partial_x - \partial_u, 2t \partial_t + x \partial_x - u \partial_u, t^2 \partial_t + tx \partial_x - (tu + x)\partial_u$

Here $s(\mu) = -\frac{3\mu+4}{\mu+1}$, $\nu \neq \mu$; $\varepsilon = \pm 1$; $q \neq -1$ in case 2* (otherwise it is subcase of the case 1.2a'); $p \neq -2, -(3\mu + 4)/(\mu + 1)$ in case 12c; $\alpha, \beta, \gamma_1, \gamma_0 = \text{const}$, and

$$f^2(x) = \exp \left\{ \int \frac{-(3\mu + 4)\beta x - 3}{(\mu + 1)\beta x^2 + x} dx \right\}, \quad f^3(x) = \exp \left\{ \int \frac{-(3\mu + 4)\beta x - 2\gamma_1 + \alpha}{(\mu + 1)\beta x^2 + \gamma_1 x + \gamma_0} dx \right\}.$$

Additional equivalence transformations:

1. $8(\varkappa \neq 0) \rightarrow 8(\varkappa = 0)$: $\tilde{t} = t, \tilde{x} = x + \varkappa t, \tilde{u} = u$;
2. $12b \rightarrow 12a$ ($\beta = \gamma_0 = \alpha = 0$), $14e \rightarrow 14a$: $\tilde{t} = (e^{(p+2)t} - 1)/(p + 2), \tilde{x} = xe^t, \tilde{u} = u$;
3. $12b^* \rightarrow 12a$ ($\beta = \gamma_1 = 0, \alpha = \gamma_0$): $\tilde{t} = (e^{\varepsilon(p+2)t} - 1)/(\varepsilon(p + 2)), \tilde{x} = xe^{\varepsilon t}, \tilde{u} = u$;
4. $12c \rightarrow 12a$ ($\beta = \gamma_0 = \alpha = 0$), $14h \rightarrow 14a$: $\tilde{t} = t, \tilde{x} = xe^{\varepsilon t}, \tilde{u} = u$;
5. $14b \rightarrow 14a, 15b \rightarrow 15a$: $\tilde{t} = t, \tilde{x} = x - t, \tilde{u} = u$;
6. $14c \rightarrow 14a, 15c \rightarrow 15a$: $\tilde{t} = e^{2\varepsilon t}/(2\varepsilon), \tilde{x} = xe^{\varepsilon t}, \tilde{u} = u$;
7. $14d \rightarrow 14a$: $\tilde{t} = t, \tilde{x} = -1/x, \tilde{u} = |x|^{-\frac{1}{1+\mu}} u$;
8. $14f \rightarrow 14a(\mu = -1)$: $\tilde{t} = t, \tilde{x} = x, \tilde{u} = e^x u$;
9. $14g \rightarrow 14a(\mu = -1)$: $\tilde{t} = e^{\varepsilon t}/\varepsilon, \tilde{x} = x + \varepsilon t, \tilde{u} = e^{x+\varepsilon t} u$;

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