# A FAKE SMOOTH $\mathbb{CP}^2 \# \mathbb{RP}^4$

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ABSTRACT. We show that the manifold  $*\mathbb{CP}^2\#*\mathbb{RP}^4$ , which is homotopy equivalent but not homeomorphic to  $\mathbb{CP}^2\#\mathbb{RP}^4$ , is in fact smoothable.

### 1. Introduction

In Kirby's problem list [Kir97, Problem 4.82] and in a recent lecture at MSRI, P. Teichner raised the question of the smoothability of a certain nonorientable 4-manifold. In this note we show that the manifold in question, denoted  $*\mathbb{CP}^2\# *\mathbb{RP}^4$ , which is homotopy equivalent but not homeomorphic to  $\mathbb{CP}^2 \# \mathbb{RP}^4$ , is in fact smoothable. The smooth model we construct will have the additional property that its universal cover is diffeomorphic to  $\mathbb{CP}^2 \# \overline{\mathbb{CP}}^2$ . To describe the manifold in question, we remind the reader that one of the first consequences of Freedman's simply-connected surgery theory was a construction of a manifold  $*\mathbb{CP}^2$ , sometimes called CH in honor of Chern, which is homotopy equivalent but not homeomorphic to  $\mathbb{CP}^2$ . The manifold  $*\mathbb{CP}^2$  is not smoothable for classical reasons: it has non-trivial Kirby-Siebenmann invariant  $KS \in \mathbb{Z}_2$ . Given any simply-connected non-spin manifold M, a similar construction produces a homotopy equivalent '\*-partner' \*M with opposite Kirby-Siebenmann invariant [Fre82]. In 1983, the first author [Rub84] constructed what is in effect the \*-partner of  $\mathbb{RP}^4$ . The connected sum  $*\mathbb{CP}^2\#*\mathbb{RP}^4$  has trivial KS-invariant and so might expected to be smoothable; on the other hand [HKT94] it is not homeomorphic to  $\mathbb{CP}^2 \# \mathbb{RP}^4$ .

**Theorem 1.** The manifold  $*\mathbb{CP}^2\# *\mathbb{RP}^4$  has a smooth structure. Moreover, it has smooth structure such that its universal cover is diffeomorphic to  $\mathbb{CP}^2\#\overline{\mathbb{CP}}^2$ .

The topological classification of non-orientable manifolds with  $\pi_1 = \mathbb{Z}_2$  is presented in [HKT94]. There a complete list, up to homeomorphism, of such manifolds is given. The only manifold in this list with vanishing Kirby-Siebenmann invariant which was unknown to be smoothable is the manifold  $*\mathbb{CP}^2\#*\mathbb{RP}^4$ . Together with theorem 1 this yields:

Corollary 2. Let X be a closed non-orientable 4-manifold with  $\pi_1(X) = \mathbb{Z}_2$ . Then X has a smooth structure if and only if KS(X) = 0.

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# 2. Construction of the manifold

The proof of Theorem 1 is constructive; we will find a smooth manifold homeomorphic to  $\mathbb{CP}^2 \# \mathbb{RP}^4$ . The construction uses a homology sphere satisfying the conclusion of the following lemma, whose proof will be given in the next section.

**Lemma 2.1.** There is a homology 3-sphere  $\Sigma^3$  with the following properties.

- (i)  $\Sigma$  is obtained by  $\pm 1$  surgery on a knot K in  $S^3$ .
- (ii) The Rohlin invariant  $\mu(\Sigma) = 1 \pmod{2}$ .
- (iii)  $\Sigma$  admits a free, orientation preserving involution  $\tau$ , which is isotopic to the identity.

Different  $\Sigma$ 's could in principle give rise to different smooth structures on  $\mathbb{CP}^2 \# \mathbb{RP}^4$ , but we know of no way to tell them apart. The situation is quite analogous to that for the fake  $\mathbb{RP}^4$ 's constructed in [FS81].

Proof of Theorem 1. Let  $\Sigma$  be a homology 3-sphere as described in the lemma; choose an orientation on  $\Sigma$  so that it becomes surgery on a knot with coefficient =+1. Items (i) and (ii) are the ingredients in Freedman's construction [Fre82] of  $*\mathbb{CP}^2$ . That is, let Y be the result of adding a 2-handle to  $B^4$  along K, with framing 1, then  $\partial Y = \Sigma$  and

$$*\mathbb{CP}^2 = Y \cup_{\Sigma} \Delta^4,$$

where  $\Delta^4$  is a contractible 4-manifold with boundary  $-\Sigma$ . (The sign of the framing is not really important, for the difference between  $*\mathbb{CP}^2$  and  $*\overline{\mathbb{CP}}^2$  will disappear when we connect sum with  $*\mathbb{RP}^4$ .) The non-trivial  $\mu$ -invariant is readily identified with the Kirby-Siebenmann invariant of  $*\mathbb{CP}^2$ .

Now items (ii) and (iii) are exactly the ingredients for the construction of  $*\mathbb{RP}^4$  given in [Rub84], i.e.

$$*\mathbb{RP}^4 = \Delta^4/(x \in \Sigma \sim \tau(x)) = (\Sigma/\tau \times I) \cup_{\Sigma} \Delta^4.$$

(The authors of [HKT94] seem to have been unaware of this earlier construction of  $*\mathbb{RP}^4$ ; compare the discussion in [Kir97, Problem 4.74].)

Let X be the smooth manifold obtained as the union of Y and the mapping cylinder of the orbit map of the free involution  $\tau$  on  $\Sigma$ , i.e.

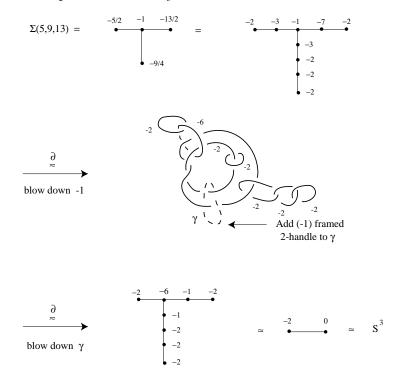
$$X = Y \cup_{\Sigma} (\Sigma/\tau \times I) = Y/(x \in \Sigma \sim \tau(x)).$$

Then X is manifestly smooth, and we claim that it is homeomorphic to  $*\mathbb{CP}^2\#*\mathbb{RP}^4$ . This seems quite plausible, for the construction amounts to performing a sort of connected sum, where instead of removing disks and gluing, we remove the 'pseudo-disc'  $\Delta^4$  and glue up. More precisely, X is homeomorphic to  $*\mathbb{CP}^2\#*\mathbb{RP}^4$  since, by [Fre82], the simply-connected topological manifolds Y and  $(Y \cup_{\Sigma} \Delta^4)\#\Delta^4$  are homeomorphic.

The additional remark about the universal cover of X being standard may be seen as follows(cf. [FS81]). By the construction of X, its cover  $\widetilde{X} \cong Y \cup_{\tau} \overline{Y} \cong Y \cup_{\overline{Y}} \overline{Y}$  since  $\tau$  is isotopic to the identity. On the other hand,  $Y \cup_{\overline{Y}} \overline{Y}$  is obtained by adding two 2-handles to  $B^4$ , together with a 4-handle. The first is added along K, with framing 1, and the second is added along a meridian of K, with framing 0. (This is a standard argument in handle theory, see for example [Kir89].) It is then easy to unknot K, by repeatedly sliding over the 0-framed handle, resulting in a standard picture of  $\mathbb{CP}^2 \# \overline{\mathbb{CP}}^2$ .

### 3. Proof of Lemma 2.1

In this section, we give two examples of homology spheres satisfying the conclusions of Lemma 2.1. Both examples are Brieskorn spheres, i.e. Seifert-fibered homology spheres of the form  $\Sigma(p,q,r)$ , where p,q, and r are relatively prime odd numbers. The involution  $\tau$  is nothing more than multiplication by  $-1 \in S^1$  in the natural circle action on  $\Sigma(p,q,r)$ . The condition that the numbers p,q, and r be odd guarantees that  $\tau$  is free; since -1 is contained in a circle, the involution is isotopic to the identity.



There are many Brieskorn spheres which are integral surgery on a knot-for some examples see [KT90, MM97] or adapt the technique of [CH81]. For most of these constructions one of the indices turns out to be even. One construction is given above, where it is shown that adding a handle (along the curve denoted  $\gamma$ ) to the Brieskorn sphere  $\Sigma(5, 9, 13)$  yields  $S^3$ . The second picture is just the

canonical resolution for the singularity of the algebraic surface  $z_1^5 + z_2^9 + z_3^{13} = 0$  in  $\mathbb{CP}^3$ , cf. [NR78]. Turning the picture upside down shows that  $\Sigma(5,9,13)$  is integral surgery on a knot in  $S^3$ . As remarked in the proof of Theorem 1, it doesn't matter whether the coefficient is positive or negative. Again, the  $\mu$ -invariant is 1 since from the picture just after blowing down the first -1 curve we see that  $\Sigma(5,9,13)$  bounds a spin manifold with definite intersection form and with signature -8. Thus, this example proves the lemma.

Another construction from the literature which provides Seifert fibered spaces is  $rs(p+q)^2 + pq$  surgery on the knot denoted  $K_{p,q}(r,s)$  in the recent paper [MM97, §9]. Choosing p = -13, q = 23, r = 3, and s = 1 gives the homology sphere  $\Sigma(3, 13, 23)$  as +1 surgery on a hyperbolic knot. Since  $\mu(\Sigma(3, 13, 23)) = 1$ , this manifold gives an example which yields the proof of Lemma 2.1. This is the only example of a  $\mu$ -invariant 1 homology sphere constructible by this method found by a moderately long computer search. It is possible to give a Kirby-calculus proof that  $\Sigma(3, 13, 23)$  is surgery on a knot similar to the one for  $\Sigma(5, 9, 13)$ ; aficionados of the subject may wish to check if the knot is the same as the one in the knot from the paper [MM97].

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